

Book

GK Batchelor, An introduction to  
Fluid mechanics  
(Cambridge) - 1967

Content

- MP110 + MP112
- MP201
- MP205
- MP203, MP204 (?)
- MP361

Maybe : MP461 + MP352

## O. Background

subset of classical Mechanics

$\Rightarrow$  Newton's Laws of Motion

(+ a bit of thermo + EM)

## Continuum Mechanics

- FM
- elasticity
- plasticity
- classical solid state

## "Continuum hypothesis"

Macroscopic behavior of materials is  
virtually identical to that of a  
continuous substance

# Fluid?

Semi-technical: a substance that does not resist or weakly resists deformations that don't change its volume

Non-technical: a substance that can change shape to fit its surroundings

- Fluids that don't resist deformation that do change their volume are gases

If they do resist then we call them liquids

If the fluid is also electrically charged, then we have a plasma

⇒ about 99% of the observable universe is a fluid of some sort

# I, Intro to fluid Mechanics

## A, Basic Quantities of a Fluid

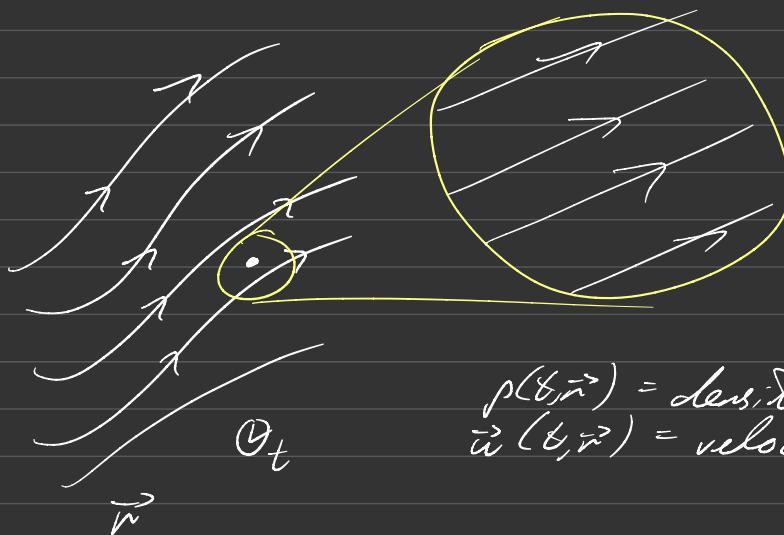
=> Fields are needed

MP201: functions of the co-ordinates  
in your space

$$f(x, y, z)$$

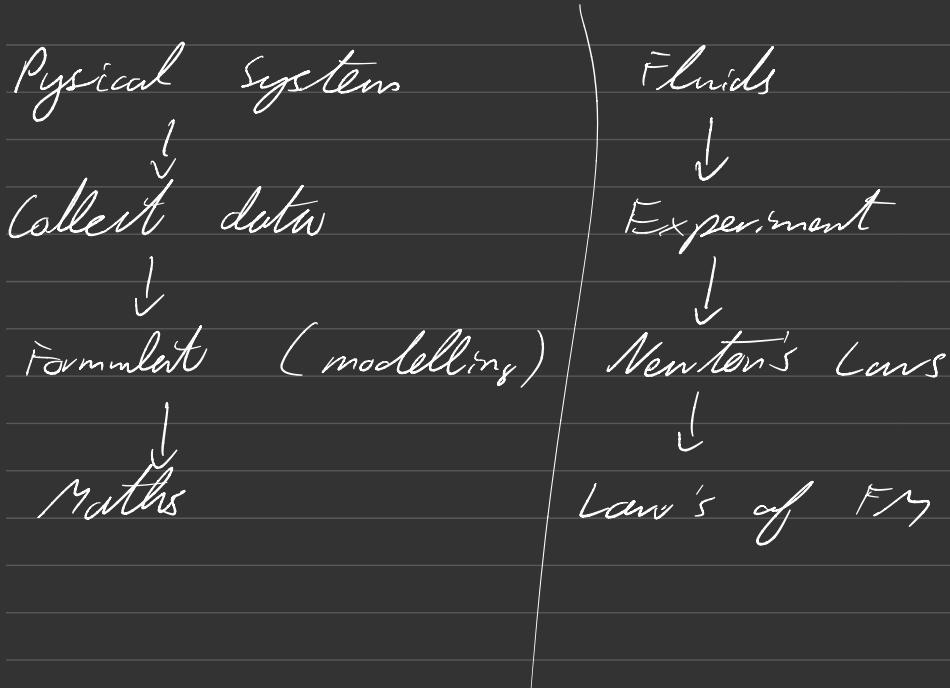
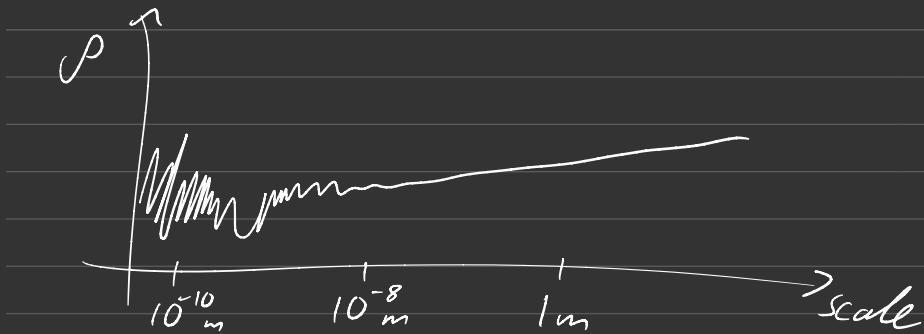
$$\rho(x, y, z)$$

$$\vec{E}(t, \vec{r}), \vec{B}(t, \vec{r})$$



$$\rho(t, \vec{r}) = \text{density}$$

$$\vec{u}(t, \vec{r}) = \text{velocity field}$$

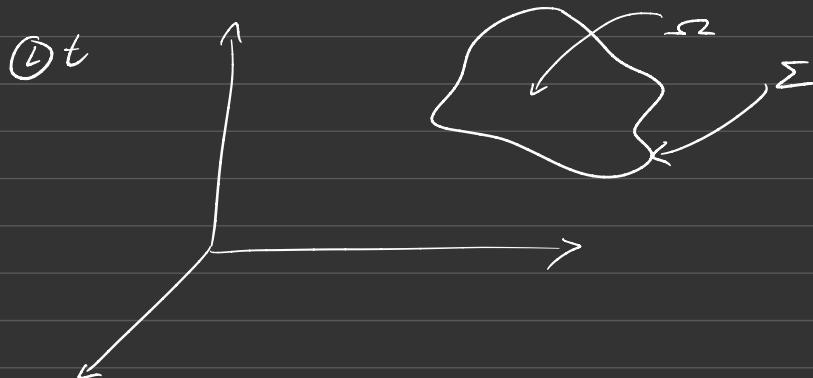


$\rho(t, \vec{r})$  = mass density

$\vec{u}(t, \vec{r})$  = velocity field

## B. The continuity equation

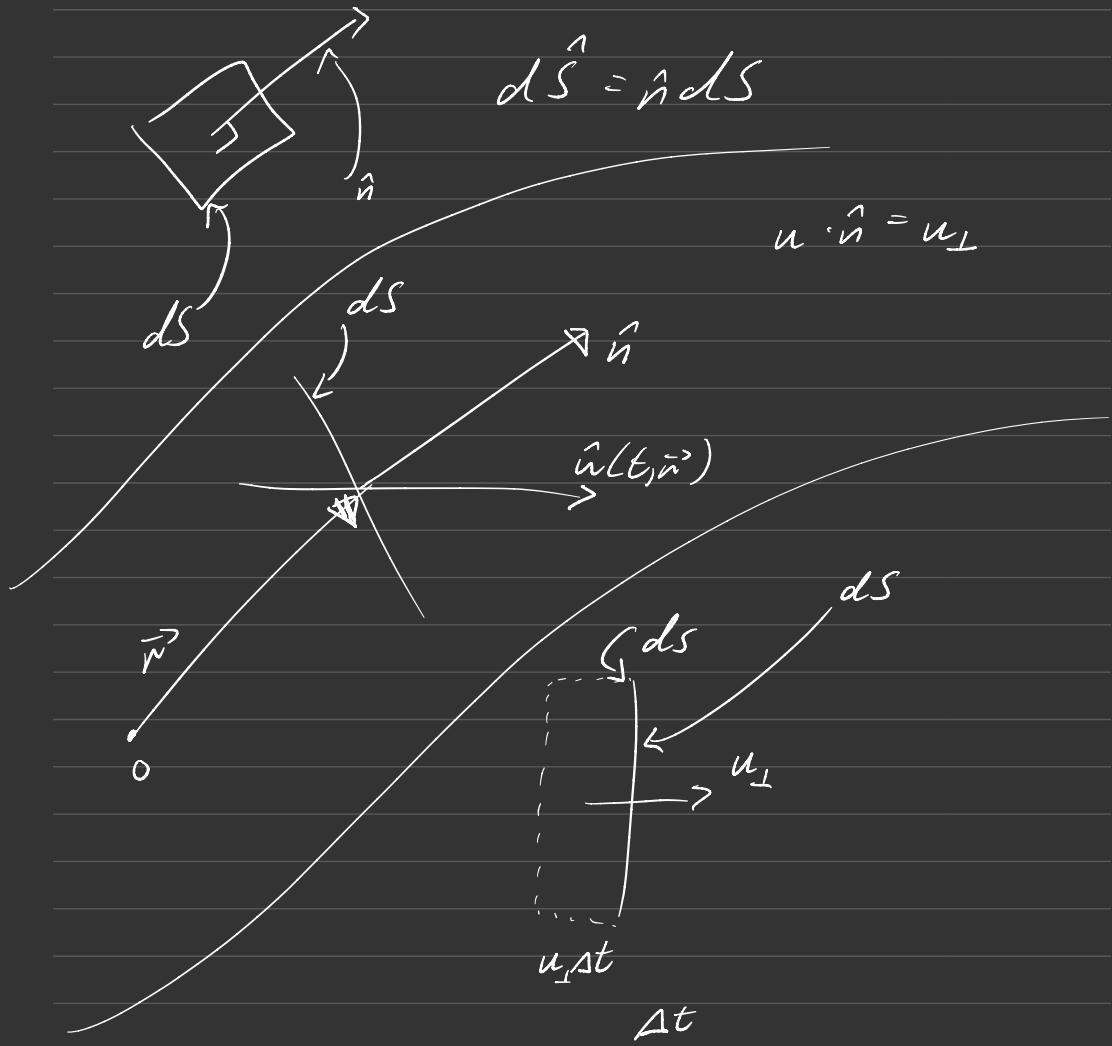
Mass is conserved (Note in SR)



$$m_{\Omega}(t) = \int_{\Omega} \rho(t, \vec{r}) dV$$

$$\frac{dm_{\Omega}}{dt} = \frac{d}{dt} \left( \int_{\Omega} \rho dV \right)$$

$$= \int_{\Omega} \frac{\partial \rho}{\partial t} dV$$



$\rho u_{\perp} \Delta t dS =$  mass that flows across the  
 area element in time  $\Delta t$

$$= \rho \bar{u}^{\perp} \cdot \hat{n} \Delta t dS$$

$$= \rho \vec{w} \cdot d\vec{s} \Delta t$$

The mass gain in  $\Sigma$  in  $\Delta t$  is  $= -\Delta t \oint_{\Sigma} \rho \vec{w} \cdot d\vec{s}$

$$= \frac{dm}{dt} \Delta t = \left( \int_{\Sigma} \frac{\partial \rho}{\partial t} dV \right) \Delta t$$

$$= - \left( \oint_{\Sigma} \rho \vec{w} \cdot d\vec{s} \right) \Delta t$$

$$\int_{\Sigma} \frac{\partial \rho}{\partial t} dV + \oint_{\Sigma} \rho \vec{w} \cdot d\vec{s} = 0$$

$$\oint_{\Sigma} \vec{A} \cdot d\vec{s} = \int_{\Omega} \vec{V} \cdot \vec{A} dV \quad \text{Gauss Law}$$

$$= \int_{\Omega} \frac{\partial \rho}{\partial t} dV + \int_{\Omega} \vec{V} \cdot (\rho \vec{w}) dV$$

$$= \int_{\Omega} \left[ \frac{\partial \rho}{\partial t} + \vec{V} \cdot (\rho \vec{w}) \right] dV = 0$$

$$\Rightarrow \boxed{\frac{\partial \rho}{\partial t} + \vec{V} \cdot (\rho \vec{w}) = 0} \quad \text{Continuity Equation}$$

MP 204

$\vec{p}\vec{u}$  = "mass current density"

$\rho_e, \vec{j}$

$$\frac{\partial \rho_e}{\partial t} + \nabla \cdot \vec{j} = 0$$

Wherever you have a conserved quantity  
there is a continuity equation

$$|\psi|^2, i(\psi^* \nabla \psi - \psi \nabla \psi^*)$$

(Noether theorem)

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0$$

Common case:  $\rho = \text{constant} \sim \text{incompressible}$

(liquids)

$$\left. \begin{array}{l} \frac{\partial \rho}{\partial t} = 0 \\ \nabla \rho = \vec{0} \end{array} \right\} \Rightarrow \nabla \cdot \vec{u} = 0 \quad ("solenoidal")$$

Need 3 more equations

vector form?

Newton's 2nd law

$$\frac{d\vec{p}}{dt} = \vec{F}$$

### C. External and internal forces on Fluids

External: due to influences from outside the fluid and acts on the fluid as a whole

Internal: due to the internal nature of the fluid itself

#### (1) External Forces



$$dm = \rho dV$$

Many (not all) external forces have the form

$$d\vec{F}_{\text{ext}} = (\text{mass})(\text{acceleration}) = (\rho dV) \underbrace{\vec{f}(t, \vec{r})}_{\text{"Body Force"}}$$

$$d\vec{F}_{ext} = \rho \vec{J} dV$$

specifying  $\vec{J}$  gives the external force

Example gravity

approx  $\vec{J} = \vec{g} = -g\hat{e}_z$

$$d\vec{F}_{ext} = \rho \vec{g} dV$$

$$\vec{F}_{ext} = \int_{fluid} (\rho \vec{g} dV)$$

$$= \left( \int_{fluid} \rho dV \right) \vec{g}$$

$$= M_{fluid} \vec{g}$$



$$\vec{F} = \frac{-\alpha \gamma}{r^3} \vec{n}$$

$$\vec{F}_{ext} = -G \gamma \int_{fluid} \frac{\rho(\vec{r})}{r^3} \vec{n} dV$$

most (not all) forces of interest  
are conservative

$$\vec{\nabla} \times \vec{f} = \vec{0}$$

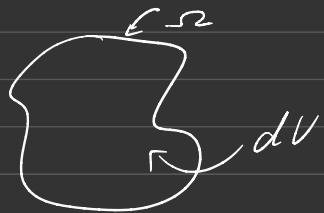
$$f = -\vec{\nabla} \Phi$$

$\uparrow$  Body Potential

### External Forces (Recap)

$$d\vec{F}_{ext} = \rho \vec{f} dV$$

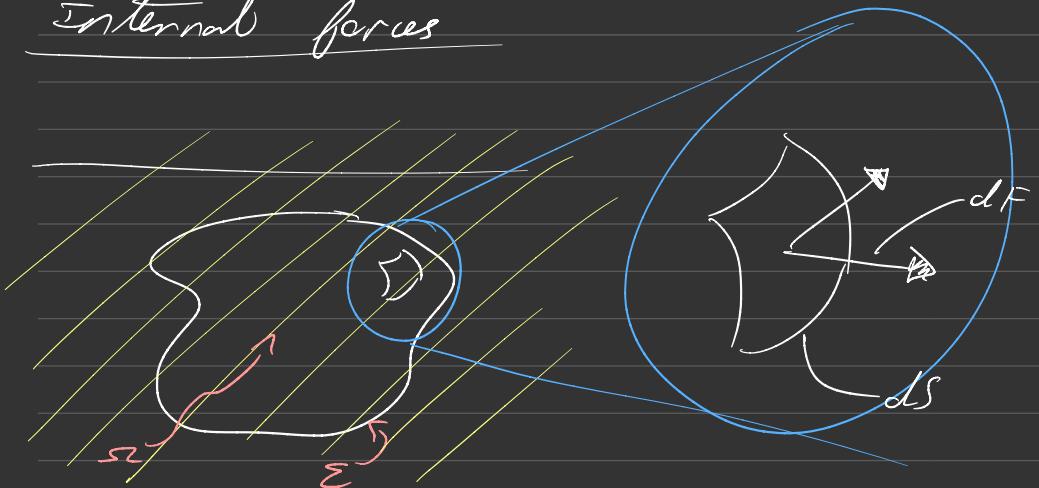
$\uparrow$  body "force"



$$\left( \vec{f} = -\vec{\nabla} \Phi \right)$$

$\downarrow$  conservative

## internal forces



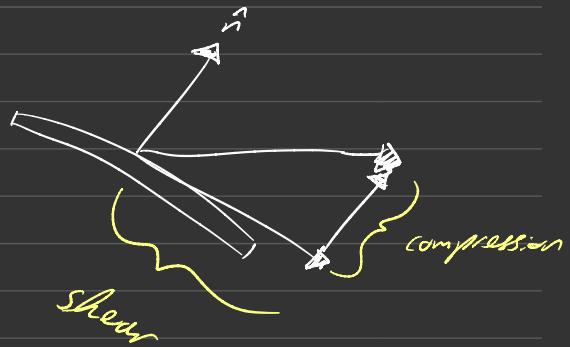
Catch all term  
for deformational  
processes  $\rightarrow$

"stress"

= Force /  
unit area

$$= \frac{d\vec{F}_{\text{internal}}}{dS} \quad \text{depend on } \hat{n}$$

$$d\vec{F}_{\text{int}} = \sigma(t, \vec{r}) \cdot \hat{n} dS$$



$\sigma$  = Cauchy stress tensor =  $3 \times 3$  matrix

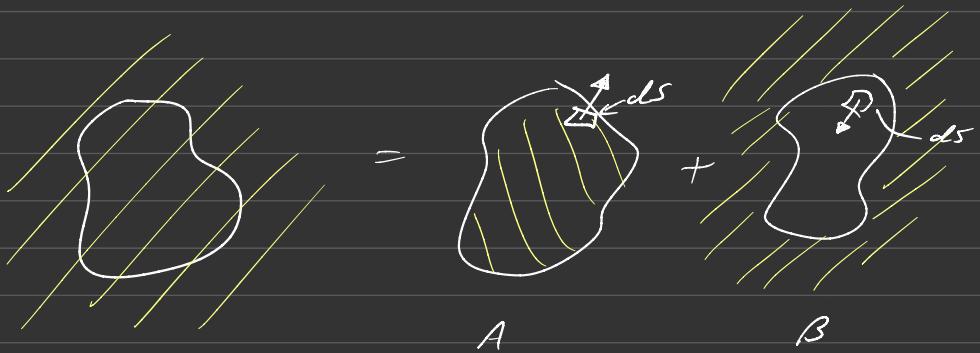
$$\sigma = \begin{pmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} \end{pmatrix}$$

$$= (\sigma_{ij})$$

Fact  $\sigma^T = \sigma$  : symmetric

$$\sigma_{ij} = \sigma_{ji}$$

$$\sigma_{xy} = \sigma_{yx} \text{ etc}$$

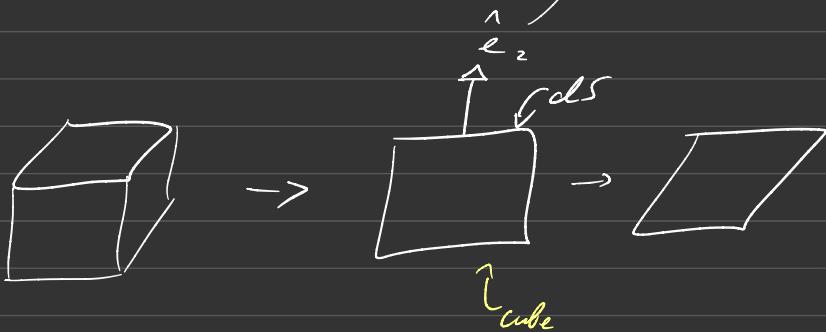


$$\vec{d\tilde{F}_{int,A}} + \vec{d\tilde{F}_{int,B}} = \vec{0}$$

## Specif. Case

stationary fluid

$$\vec{u}(t, \vec{r}) = \vec{0} \quad d\vec{F}_{int} = \sigma \cdot \hat{e}_z ds$$

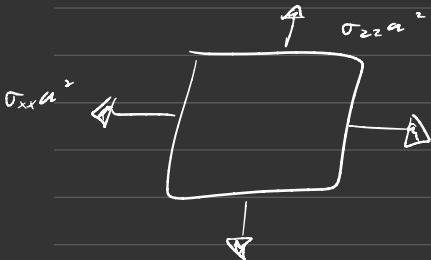


$$d\vec{F}_{int} = \sigma \cdot \hat{e}_z ds = (\sigma_{xx}\hat{e}_x + \sigma_{yz}\hat{e}_y + \sigma_{zz}\hat{e}_z)ds$$

$$\sigma_{xz} = \sigma_{yz} = 0$$

$$= \sigma_{zy} = \sigma_{zy} = \sigma_{xy} = \sigma_{yx}$$

$$\sigma = \begin{pmatrix} \sigma_{xx} & & \\ & \sigma_{yy} & \\ & & \sigma_{zz} \end{pmatrix}$$



$$\frac{\partial \phi}{\partial t} + \vec{V} \cdot \rho \vec{u} = 0$$

$$\Rightarrow \text{stat fluid} \quad \frac{\partial \phi}{\partial t} = 0$$

$$\sigma = \sigma_{xx} \begin{pmatrix} 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$$

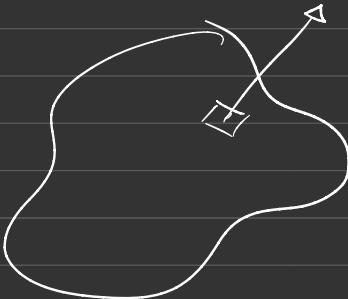
$$d\vec{F}_{int} = \sigma_{xx} I \cdot \hat{n} dS$$

$$= \sigma_{xx} \hat{n} dS$$

$$\frac{d\vec{F}_{int}}{dS} = \sigma_{xx} \hat{n}$$

$$= -P \hat{n}$$

$\hat{n}$   
normal  
pressure



For stationary fluid + inviscid fluids

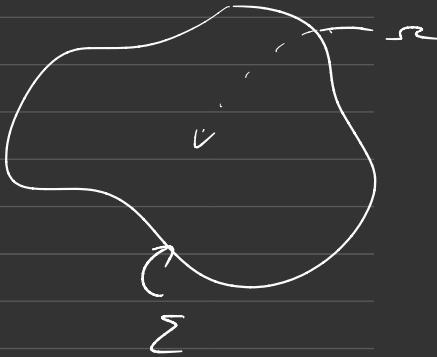
$$\sigma = \begin{pmatrix} -P & 0 & 0 \\ 0 & -P & 0 \\ 0 & 0 & -P \end{pmatrix}$$

### 3. Total Force on a Fluid

$$d\vec{F} = d\vec{F}_{ext} + d\vec{F}_{int}$$
$$= \rho \vec{f} dV + \sigma \cdot d\vec{s}$$

$$\vec{F} = \int_{\Sigma} \rho \vec{f} dV + \oint_{\Sigma} \sigma \cdot d\vec{s}$$

$$\text{and } \left( \oint_{\Sigma} \sigma \cdot d\vec{s} \right)_x$$



$$= \oint_{\Sigma} (\sigma \cdot d\vec{s})_x$$

$$= \oint_{\Sigma} \sum_{i=1}^3 \sigma_{xi} ds_i$$

$$\rightarrow \vec{A}^{(x)} = \sigma_{xx} \hat{e}_x + \sigma_{xy} \hat{e}_y + \sigma_{xz} \hat{e}_z$$

$$= \oint_{\Sigma} \vec{A}^{(x)} \cdot d\vec{s}$$

$$= \int_{\Sigma} (\vec{V} \cdot \vec{A}^{(x)}) dV$$

$$\vec{\nabla} \cdot \vec{A}^{(s)} = \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + \frac{\partial \sigma_{xz}}{\partial z}$$

$$= \sum_{j=1}^3 \frac{\partial \sigma_{xj}}{\partial x_j}$$

$$\downarrow \int_V \sum_{j=1}^3 \frac{\partial \sigma_{xj}}{\partial x_j} dV$$

$$\vec{F} = \int_V \rho \vec{f} dV + \underbrace{\oint_{\Sigma} \sigma \cdot d\vec{s}}_{(\vec{\nabla} \sigma)_c}$$

$$(\oint_{\Sigma} \sigma \cdot d\vec{s})_c = \int_V \sum_j \frac{\partial \sigma_{xj}}{\partial x_j} dV$$

$$\vec{F} = \int_V (\rho \vec{f} + \vec{\nabla} \sigma) dV$$

$$\vec{F} = \frac{d\vec{p}}{dt}$$

stationary friction) ( $\vec{a} = \vec{0}$ ) or instead (no internal

$$\sigma_{ij} = -\rho \delta_{ij}$$

$$(\vec{\nabla} \sigma)_i = \sum \frac{\partial}{\partial x_i} (-\rho \delta_{ij})$$

$$= -\frac{\partial \rho}{\partial x_i}$$

$$= (-\vec{\nabla} \rho)_i$$

## II Hydrostatics

### A. Definition

Time-independent :  $\frac{d}{dt} (\text{anything}) = 0 \quad \left. \begin{array}{l} \text{Equilibrium} \\ \text{stationary} \end{array} \right\}$

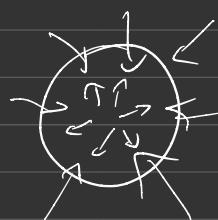
stationary :  $\vec{v}(t, \vec{r}) \approx \vec{0}$  station

$$\vec{F} = \vec{0}$$

$$= \int_{\Omega} (\rho \vec{f} - \nabla p) dV$$

$$\Rightarrow \boxed{\rho \vec{f} - \nabla p = \vec{0}}$$

Hydrostatic Equilibrium

- 2006 : redefinition of "planet" - non-stellar
- orbits a stellar object
  - clears its orbit
  - hydrostatic equilibrium
- 

$$\boxed{\rho \vec{f} - \vec{\nabla} \rho = \vec{0}}$$

hydrostatic equilibrium

$$\rho(\vec{r})$$

$$\vec{f}(\vec{r}) \rightarrow \text{given}$$

$$\rho(\vec{r})$$

$\Rightarrow$  over-determined system

incompressible :  $\rho \approx \text{constant} \rightarrow \text{liquid}$

compressible :  $\rho \neq \text{constant} \rightarrow \text{gas, plasmas}$

### B. Incompressible Static Fluids

$$\rho(\vec{r}) \approx \text{constant} = \rho_0$$

$$\vec{\nabla} \rho = \rho_0 \vec{f}(\vec{r})$$

$$\frac{\partial \rho}{\partial x} = \rho_0 f_x, \quad \frac{\partial \rho}{\partial y} = \rho_0 f_y, \quad \frac{\partial \rho}{\partial z} = \rho_0 f_z$$

$$\underbrace{\text{Conservation}}_{\text{ }} : \vec{f}(\vec{r}) = -\vec{\nabla} \phi(\vec{r})$$

$$\vec{\nabla} \rho = -\rho_0 \vec{\nabla} \mathcal{D}$$

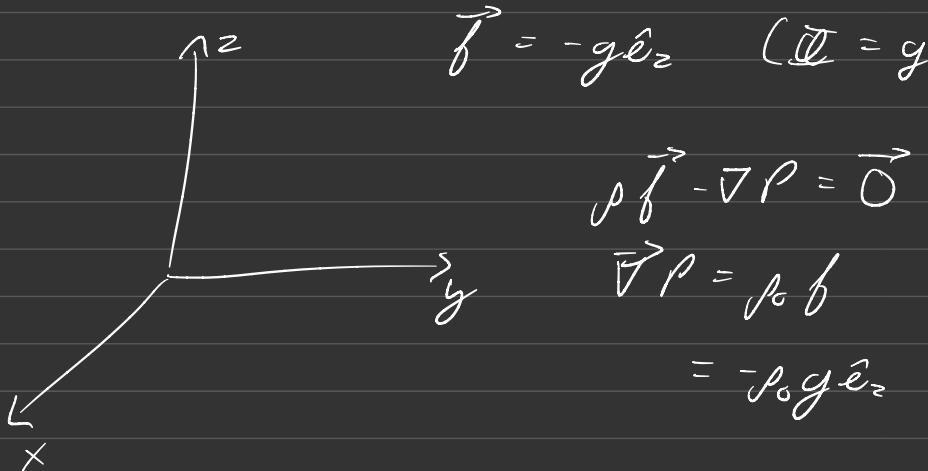
$$= -\vec{\nabla}(\rho_0 \mathcal{D})$$

$$\vec{\nabla}(\rho + \rho_0 \mathcal{D}) = 0$$

$$\Rightarrow \rho + \rho_0 \mathcal{D} = \text{constant}$$

Static liquid in a constant gravitational field

$$\vec{f} = -g \hat{e}_z \quad (\mathcal{D} = g z)$$



$$\frac{\partial \rho}{\partial x} = 0, \quad \frac{\partial \rho}{\partial y} = 0$$

$$\frac{\partial \rho}{\partial z} = -\rho_0 g$$

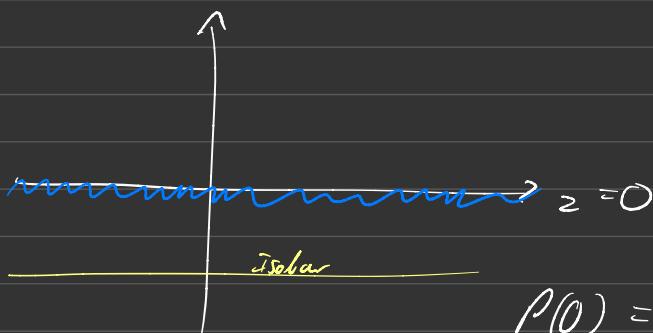
$$\Rightarrow \rho(z)$$

$$\frac{dP}{dz} = \frac{d\rho}{dz} = -\rho_0 g$$

$$\rho(z) = -\rho_0 g z + C$$

$$\rho(0) = C = \rho_0$$

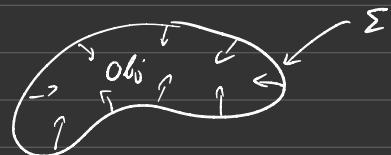
$$\Rightarrow \boxed{\rho(z) = \rho_0 - \rho_0 g z}$$



$$\begin{aligned}\rho(0) &= \rho_A = 1 \text{ atm} \\ &= 1.01 \cdot 10^5 \text{ Pa} \\ &= 1010 \text{ hPa}\end{aligned}$$

$$\rho(z) = \rho_A - \rho_{H_2O} g z$$

$$\begin{aligned}\rho(-10) &= 1.01 \cdot 10^5 \text{ Pa} - (1000 \text{ kg/m}^3)(9.81 \text{ ms}^{-2})(-10 \text{ m}) \\ &= 1.99 \cdot 10^5 \text{ Pa} \approx 1.96 \text{ atm}\end{aligned}$$



$\uparrow$  buoyancy

$$\overrightarrow{F}_{\text{buoy}} = \oint_{\Sigma} \sigma \cdot d\overrightarrow{S}$$

$$= \int_V (\nabla \sigma) dV$$

$$= \rho_0 V g \hat{e}_z$$

= (displaced mass of fluid)  $g \hat{e}_z$

= (weight of displaced fluid)  $\hat{e}_z$

$$(\nabla \sigma)_i = \sum \frac{\partial \sigma_i}{\partial x_j}$$

$$(\nabla \sigma)_x = \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + \frac{\partial \sigma_{xz}}{\partial z}$$

$$= -\frac{\partial P}{\partial x} = 0$$

$$(\nabla \sigma)_y = -\frac{\partial P}{\partial y} = 0$$

$$(\nabla \sigma)_z = -\frac{\partial P}{\partial z} = \rho g$$

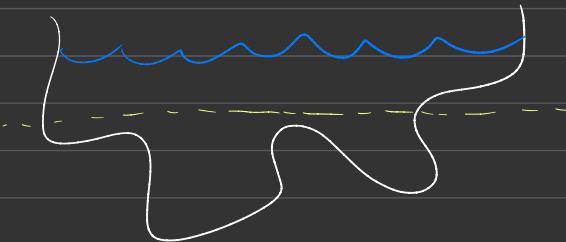
246 BCE by Archimedes

## Hydrostatic Systems

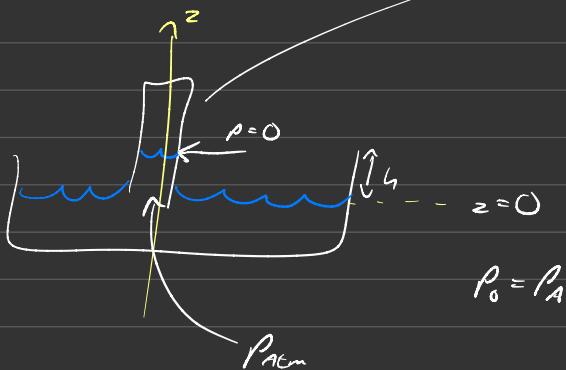
$$\rho \vec{f} - \vec{\nabla} p = \vec{0} \quad \vec{f} = -g \hat{e}_z$$

$$\rho(\vec{r}) = \rho_0 \quad \text{incompressible}$$

$$\Rightarrow \rho(z) = \rho_0 - \rho_0 g z$$



Barometer



$$\rho_0 = \rho_A$$

$$\rho(h) = 0 = \rho_A - \rho_0 g h$$

$$h = \frac{\rho_A}{\rho_0 g}$$

$$\rho_A \approx 1000 h \rho_a = 10^5 \rho_a$$

STP: standard temperature and pressure

$$T_{STP} = 20^\circ C \quad (= 297 K) \quad \left. \right\} (\text{E.U})$$

$$\rho_{STP} = 1 \text{ atm} = 1.01 \times 10^5 \text{ Pa}$$

NTP: Normal temp and pressure

$$T_{NTP} = 0^\circ C \quad (= 273 K) \quad \left. \right\} (\text{us})$$

$$\rho_{NTP} = 10^5 \text{ Pa}$$

STP

$$\rho_0 = 13546 \text{ kg m}^{-3}$$

$$g = 9.81 \text{ ms}^{-1}$$

$$\rho_A = 1.01 \times 10^5 \text{ Pa}$$

$$\Rightarrow h = 750 \text{ mm}$$

## B. Compressible Fluids

$$\rho \vec{J} - \vec{\nabla} p = \vec{0}$$

$\rho \neq \text{constant}$

Thermal and Stat. Phys.

Equations of State: relations between  
the thermodynamic state variables

$$(T, V, N, P, S, U, \dots)$$

$$P(p; \text{other variables})$$

Intensive:  $\rho$

Extensive:  $V, N$

$$\underbrace{\phantom{V}}$$

$$\frac{N}{V}$$

$$\rho = \frac{N}{V} = \frac{mN}{V}$$

$$\Rightarrow P(\rho)$$

$$\vec{\nabla} P(\rho) = \rho'(\rho) \vec{\nabla} \rho$$

$$\rho \vec{J} = \rho'(\rho) \vec{\nabla} \rho$$

$$\underbrace{\rho'(\rho)}_{\rho} \vec{\nabla} \rho = \vec{J} \Rightarrow \rho(x, y, z)$$

## The Ideal Gas

$$PV = Nk_B T$$

$$\rho = \frac{Nk_B T m}{V_m}$$

$$P(\rho) = \frac{k_B T}{m} \rho$$

### Example

Isothermal, ideal gas,  $T = \text{const}$

$$P(\rho) = \frac{k_B T}{m} \rho$$

$$\vec{\nabla} P = \frac{k_B T}{m} \vec{\nabla} \rho$$

$$\rho \vec{J} = \frac{k_B T}{m} \vec{J}_\rho$$

$$\frac{1}{\rho} \vec{\nabla} \rho = \frac{m \vec{T}}{k_B T}$$

$$\left[ \vec{T} = -g \hat{e}_z \right]$$

$$\frac{1}{\rho} \vec{\nabla} \rho = \frac{-mg}{k_B T} \hat{e}_z$$

$$\left. \begin{aligned} \frac{1}{\rho} \frac{\partial \rho}{\partial x} &= 0 \\ \frac{1}{\rho} \frac{\partial \rho}{\partial y} &= 0 \end{aligned} \right\} \Rightarrow \rho = \rho(z)$$

$$\frac{1}{\rho} \frac{\partial \rho}{\partial z} = \frac{-mg}{k_B T}$$

$$= \frac{d\rho}{\rho} = \frac{-mg}{k_B T} dz$$

$$= \ln \rho = \frac{-mgz}{k_B T} + C$$

$$\rho(z) = e^C e^{\frac{-mgz}{k_B T}}$$

$$\rho(0) = \rho_0 \Rightarrow \boxed{\rho(z) = \rho_0 e^{\frac{-mgz}{k_B T}}}$$

$$\text{Sea level } \rho_{\text{SP}} = 1.204 \text{ kg m}^{-3}$$

$$T_{\text{SP}} = 20^\circ C$$

$$z = 8849 \text{ m}$$

$$20 \% O_2 + 80 \% N_2$$

$$m \approx 0.2(32 \text{ mg}) + 0.8(28 \text{ mg})$$

$$= 4.82 \cdot 10^{-26} \text{ mg}$$

$$\frac{mgz}{k_B T} = 1.03$$

$$e^{-1} \approx 0.36$$

$$\rho_{\text{Everest}} = 0.43 \text{ kg m}^{-3}$$

More accurate

• different  $\rho(p)$

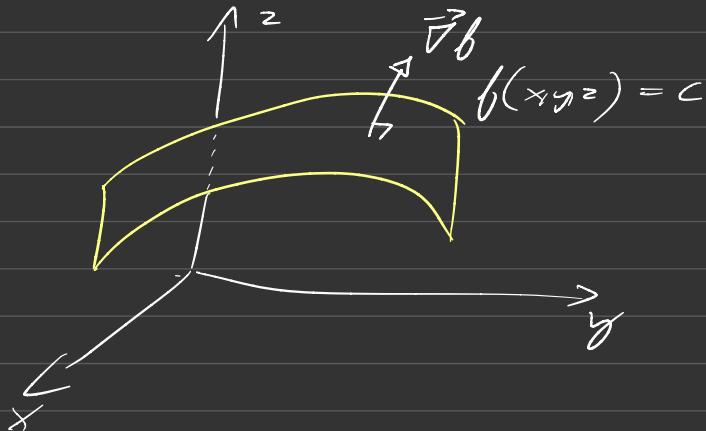
•  $T(z)$

## C. Level Surfaces and Hydrostatic Systems

$$f(x, y, z) = c$$

Level surfaces of  $f$

MP 201



$$\vec{\nabla} P = \rho \vec{f}$$

$$\vec{f} = -\vec{\nabla} \mathcal{U} \quad (\text{conservative body force})$$

$$\text{eg } \mathcal{U} = -gy \Rightarrow \vec{f} = -g\hat{e}_z$$

$$\vec{\nabla} P = -\rho \vec{\nabla} \mathcal{U}$$

$$\vec{\nabla} \times (\vec{\nabla} P) = -\vec{\nabla} \times (\rho \vec{\nabla} \mathcal{U})$$

$$\vec{O} = -[\vec{\nabla}P \times \vec{\nabla}\Phi + \rho \vec{\nabla} \times (\vec{\nabla}\Phi)]$$

$$\Rightarrow \vec{\nabla}P \times \vec{\nabla}\Phi = \vec{O}$$

$\vec{\nabla}P$  and  $\vec{\nabla}\Phi$  are parallel

### Equipotential surfaces

$$\Phi(x, y, z) = c$$

$\Rightarrow \vec{\nabla}\Phi$  is normal to the equipotential surface

$\Rightarrow \rho = \text{const}$  equipotential state

$$\vec{\nabla}\Phi = -\frac{1}{\rho} \vec{\nabla}P$$

$$\vec{O} = \frac{\vec{\nabla}P \times \vec{\nabla}P}{\rho^2}$$

$\Rightarrow \text{const } \rho$  surface (so bar)

$$\rho(z) = \rho_0 \cdot \sqrt{g_0 g z}$$



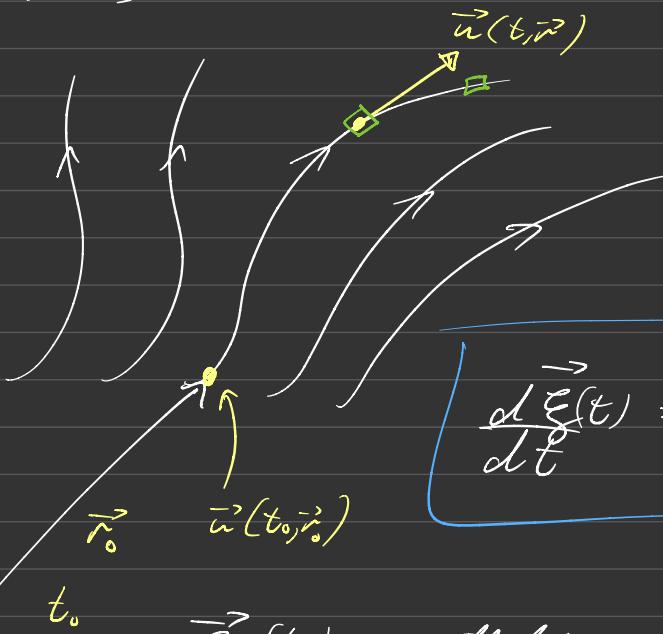
### IV , Dynamics of Fluids

$$\vec{F} = \int (\rho \vec{j} + \vec{\nabla} \sigma) dV$$

$$\frac{d\vec{p}}{dt} \neq \vec{0}$$

#### A. Path lines and the Material Derivative

Poche's Stokes



$$\frac{d\vec{w}(t)}{dt} = \vec{w}(t, \vec{r}(t))$$

$\vec{r}(t)$  = position of the particle  
of the fluid at  $(t, \vec{r}_0)$

$$\vec{r}(t_0) = \vec{r}_0$$

$Q(t, \vec{r})$  is the same quantity of interest in the fluid

$$\frac{d}{dt} Q(t, \vec{\xi}(t))$$

$$= \left. \frac{\partial Q}{\partial t} (t, \vec{r}) \right|_{\vec{r}, \vec{\xi}(t)} + \left. \frac{\partial Q}{\partial t} (t, \vec{r}) \right|_{\vec{r}, \vec{\xi}(t)} \frac{d \vec{\xi}(t)}{dt}$$

$$+ \frac{\partial Q}{\partial y} \frac{d \xi_y}{dt} + \frac{\partial Q}{\partial z} \frac{d \xi_z}{dt}$$

$$= \frac{\partial Q}{\partial t} + \frac{d \vec{\xi}}{dt} \cdot \vec{\nabla} Q$$

$$= \frac{\partial Q}{\partial t} + (\vec{u} \cdot \vec{\nabla}) Q$$

$$= \left( \frac{\partial}{\partial t} + \vec{u} \cdot \vec{\nabla} \right) Q$$

$$\frac{\partial}{\partial t} = \frac{\partial}{\partial t} + \vec{u} \cdot \vec{\nabla} = "material derivative"$$

$$= "stream derivative"$$

$$\rho(t, \vec{u})$$

$$\frac{\partial \rho}{\partial t} = \frac{\partial \rho}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \rho$$

continuity equation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

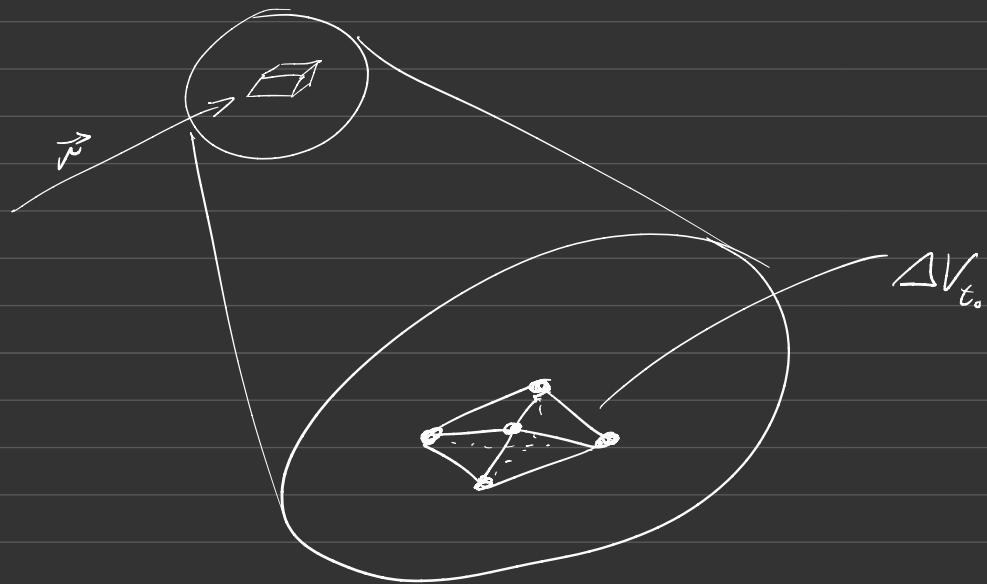
$$= \frac{\partial \rho}{\partial t} + \vec{\nabla} \rho \cdot \vec{u} + \rho (\vec{\nabla} \cdot \vec{u})$$

$$= \frac{\partial \rho}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \rho + \rho (\vec{\nabla} \cdot \vec{u})$$

$$= \frac{\partial \rho}{\partial t} + \rho (\vec{\nabla} \cdot \vec{u})$$

$$\frac{\partial \rho}{\partial t} = -\rho (\vec{\nabla} \cdot \vec{u})$$

$t_0$



$$\Delta V_{t_0 + \Delta t} = [1 + \Delta t (\vec{V} \cdot \vec{u})] \Delta V_{t_0}$$

$$\lim_{\Delta t \rightarrow 0} \frac{\Delta V_{t_0 + \Delta t} - \Delta V_{t_0}}{\Delta t} = (\vec{V} \cdot \vec{u}) \Delta V_{t_0}$$

$$= \frac{d}{dt}(\Delta V_t)$$

$$= (\vec{V} \cdot \vec{u}) \Delta V_t$$

⑤ t

$$\Delta m_{t+\Delta t} = \Delta m_t \quad \text{cloud}$$

$$\Delta m_t = \rho(t, \vec{\xi}(t)) \Delta V_t$$

$$\Delta m_{t+\Delta t} = \left( \rho + \frac{\partial \rho}{\partial t} \Delta t \right) \left( 1 + (\vec{\nabla} \cdot \vec{u}) \Delta t \right) \Delta V_t$$

$$= \rho \Delta V_t + \Delta t \left[ \rho (\vec{\nabla} \cdot \vec{u}) \Delta V_t + \frac{\partial \rho}{\partial t} \Delta V_t \right]$$

$$+ O(\Delta t^2)$$

$$= \Delta m_t + \Delta t \left[ \rho (\vec{\nabla} \cdot \vec{u}) + \frac{\partial \rho}{\partial t} \right] \Delta V_t$$

$$\frac{\partial \rho}{\partial t} = \frac{\partial \rho}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \rho + \rho (\vec{\nabla} \cdot \vec{u})$$

$$= \frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$\Delta \vec{\rho}_t = \Delta m_t \vec{u}(t, \vec{\xi}(t))$$

$$= \rho(t, \vec{\xi}(t)) \vec{u}(t, \vec{\xi}(t)) \Delta V_t$$

$$\frac{d}{dt} \Delta \vec{p}_t = \frac{\partial \vec{p}}{\partial t} \vec{u} \Delta V_t + \rho \frac{d\vec{u}}{dt} \Delta V_t$$

$$+ \rho \vec{u} \frac{\partial}{\partial t} \Delta V_t$$

$$= \vec{u} \left[ \frac{\partial \vec{p}}{\partial t} + \rho (\vec{\nabla} \cdot \vec{u}) \right] \Delta V_t$$

$$+ \rho \frac{d\vec{u}}{dt} \Delta V_t$$

$$= \rho \Delta V_t \frac{d\vec{u}}{dt} = \rho \Delta V_t \left[ \frac{d\vec{u}}{dt} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right]$$

$$\left( \frac{d\vec{u}}{dt} \right)_i = \frac{\partial u_i}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_i$$

$$\Rightarrow = (\rho \vec{f} + \vec{\nabla} \sigma) \Delta V_t$$

Newton's second law for fluids

$$\boxed{\frac{d\vec{u}}{dt} = \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} = \vec{f} + \frac{1}{\rho} (\vec{\nabla} \sigma)}$$

$$\frac{\partial \vec{p}}{\partial t} + \vec{\nabla} \cdot (\vec{p} \vec{u}) = 0$$

$\vec{p}, \vec{u}$ : unknowns

$\vec{f}$ : Known

$\sigma_{ij}$ : ??

Friction in the fluid viscosity

$\downarrow$   
resistance to shear  
deformation of the  
fluid

$\Rightarrow$  Inviscid Fluids

### B. Inviscid Fluids

$$\sigma_{ij} = -\rho \delta_{ij}$$

$$\vec{\nabla} p = -\vec{\nabla}^2 p$$

$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} = \vec{f} - \frac{1}{\rho} \vec{\nabla} p$$

Euler's  
Equation

Reynolds

Equations for inviscid fluid

$$\frac{\partial \vec{u}}{\partial t} = \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} = \vec{f} - \frac{1}{\rho} \vec{\nabla} P$$

Plus continuity eqn

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

plus one more

(incompressible, equation of state)

What's inviscid anyway?

viscosities in mPa s

Plant Butter	$10^4 - 10^6$	$\text{CH}_4$	$1.1 \times 10^{-2}$
Honey	$2000 - 10,000$	$\text{H}_2$	$9 \times 10^{-3}$
Blood	$2 - 1$		
Hg	1.53		
Water	1		
He	$1.9 \times 10^{-2}$		
Ar	$1.8 \times 10^{-2}$		
Cl	$1.3 \times 10^{-2}$		

inviscid  $\approx 2 \text{ mPa s}$

## B. Bernoulli's Principle

• inviscid

• incompressible ( $\rho(t, \vec{r}) = \rho_0$ )

• steady flow (no time dependence)

• conservative body force ( $\vec{f} = -\vec{\nabla}\Phi$ )

Energy

$$\frac{d\vec{\xi}(t)}{dt} = \vec{u}(t, \vec{\xi}(t)) \quad \begin{matrix} \text{(solve for} \\ \text{path line)} \end{matrix}$$

$$= \vec{u}(\vec{\xi}(t))$$



$$\Delta T_t = \frac{1}{2} \rho \Delta V_t / |\vec{u}|^2$$

$$\frac{D}{Dt}(\Delta T_t) = \frac{D}{Dt} \left( \frac{1}{2} \rho \Delta V_t / |\vec{u}|^2 \right)$$

$$= \frac{1}{2} \left( \frac{\partial}{\partial t} (\rho \Delta V_t |\vec{u}|^2) + \rho \Delta V_t \frac{\partial}{\partial t} |\vec{u}|^2 \right)$$

$$\begin{aligned}
 \frac{\partial}{\partial t} (\Delta V_t) &= \frac{1}{2} \rho \Delta V_t \frac{\partial}{\partial t} (\vec{\omega} \cdot \vec{\omega}) \\
 &= \frac{1}{2} \rho \Delta V_t \left[ \frac{\partial \vec{\omega}}{\partial t} \cdot \vec{\omega} + \vec{\omega} \cdot \frac{\partial \vec{\omega}}{\partial t} \right] \\
 &= \rho \Delta V_t \vec{\omega} \cdot \frac{\partial \vec{\omega}}{\partial t} \\
 &= \rho \Delta V_t \vec{\omega} \cdot \left( \vec{\nabla} - \frac{1}{\rho} \vec{\nabla} \rho \right) \\
 &= -\rho \Delta V_t \vec{\omega} \cdot \left( \vec{\nabla} \Psi + \frac{1}{\rho} \vec{\nabla} \rho \right) \\
 &= -\rho \Delta V_t \left[ \frac{\partial \Psi}{\partial t} - \frac{\partial \Psi}{\partial t} + \frac{1}{\rho} \frac{\partial \rho}{\partial t} - \frac{\partial \rho}{\partial t} \right] \\
 &= -\rho \Delta V_t \left( \frac{\partial \Psi}{\partial t} + \frac{1}{\rho} \frac{\partial \rho}{\partial t} \right) \\
 &= -\rho \Delta V_t \left[ \frac{\partial \Psi}{\partial t} + \frac{\partial \rho}{\partial t} \left( \frac{\rho}{\rho_0} \right) \right] \\
 &= -\rho \Delta V_t \frac{\partial}{\partial t} \left( \Psi + \frac{\rho}{\rho_0} \right) \quad \left. \right\} \\
 &= \rho \Delta V_t \frac{\partial}{\partial t} \left( \frac{1}{2} |\vec{\omega}|^2 \right) \quad \left. \right\}
 \end{aligned}$$

$$\Rightarrow \frac{D}{Dt} \left( \frac{1}{2} |\vec{u}|^2 + \underline{\underline{F}} + \frac{P}{\rho_0} \right) = 0$$

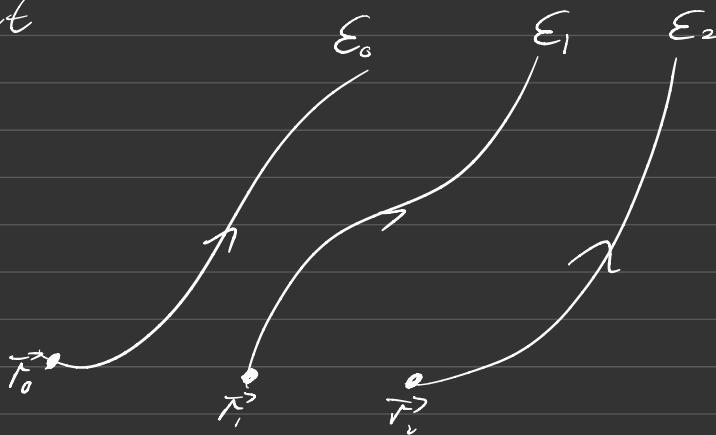
$$\underbrace{\frac{1}{2} |\vec{u}|^2}_{\text{KE per unit mass}} + \underbrace{\underline{\underline{F}}}_{\text{potential energy per unit mass from ext forces}} + \underbrace{\frac{P}{\rho_0}}_{\text{PE per unit mass for int forces}} = \text{const} = E \quad \left( = \frac{\text{energy}}{\text{unit mass}} \right)$$

on each path there

$$\frac{d\vec{\xi}}{dt} = \vec{u}(\vec{\xi}(t)) , \quad \vec{\xi}(t_0) = \vec{r}_0$$

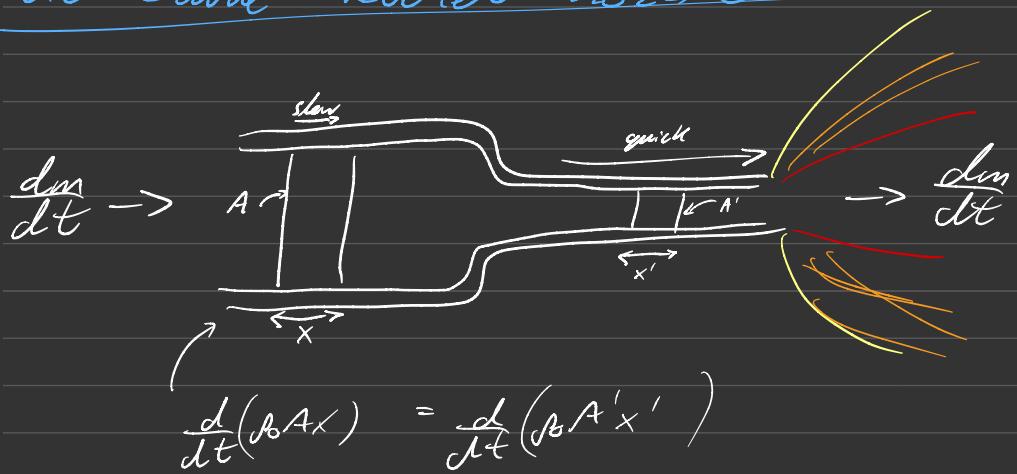
$$E(t) = \frac{1}{2} \left| \frac{d\vec{\xi}(t)}{dt} \right|^2 + \underline{\underline{F}}(\vec{\xi}(t)) + \frac{P(\vec{\xi}(t))}{\rho_0}$$

$$\frac{dE(t)}{dt} = 0$$

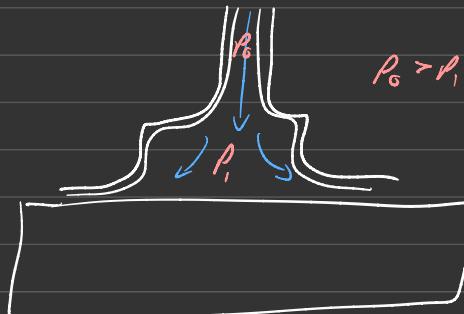


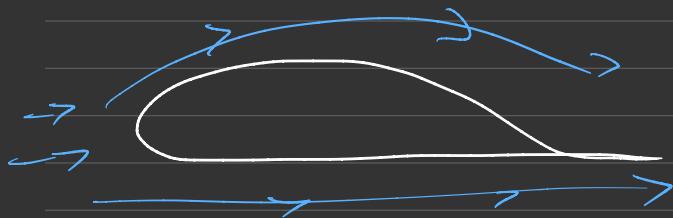
$\frac{dI}{dt} = \text{const} \Rightarrow$  speed rises when pressure falls, vice versa

## de Laval Rocket nozzle

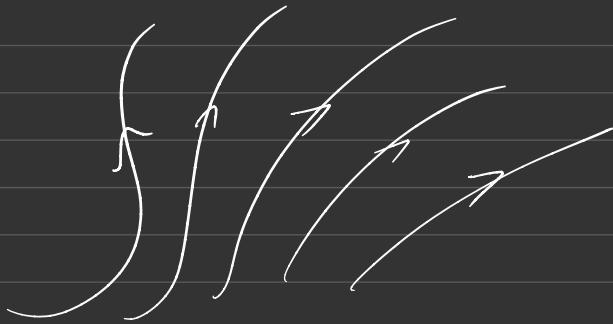


## Bernoulli Group



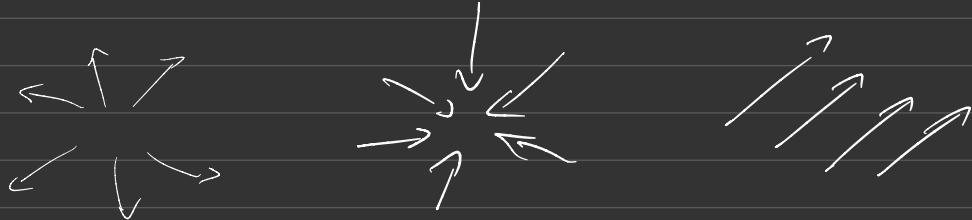


$$\frac{1}{2} |\vec{u}|^2 + \frac{\gamma}{\rho} + \frac{P}{\rho} = \mathcal{E}$$



## Irrotational Fluids

$$\frac{d}{dt}(\Delta V_t) = (\vec{\nabla} \cdot \vec{\omega}) \Delta V_t$$



$$\vec{\nabla} \cdot \vec{\omega} \geq 0$$

$$|\vec{\nabla} \times \vec{\omega}| \approx 0$$

$$\vec{\nabla} \cdot \vec{\omega} < 0$$

$$|\vec{\nabla} \times \vec{\omega}| \approx 0$$

$$\vec{\nabla} \cdot \vec{\omega} \approx 0$$

$$|\vec{\nabla} \times \vec{\omega}| \approx 0$$



$$\vec{\nabla} \cdot \vec{\omega} \approx 0 \leftrightarrow \text{spready outness}$$

$$|\vec{\nabla} \times \vec{\omega}| > 0$$

Vorticity:  $\vec{\omega} = \vec{\nabla} \times \vec{v}$

For any  $\vec{a}$

$$(\vec{\nabla} \times \vec{a}) \times \vec{a} = (a \cdot \vec{\nabla}) \vec{a} - \vec{\nabla}( \frac{1}{2} |a|^2 )$$

$$a^2 = \vec{a}^2$$

$$\vec{w} \times \vec{u} = (\vec{u} \cdot \vec{\nabla}) \vec{u} - \vec{\nabla}( \frac{1}{2} |\vec{u}|^2 )$$

Inviscid

$$\frac{d\vec{u}}{dt} + (\vec{u} \cdot \vec{\nabla}) \vec{u} = \vec{f} - \frac{1}{\rho} \vec{\nabla} p$$

$$\frac{\partial \vec{u}}{\partial t} + \vec{\nabla}( \frac{1}{2} |\vec{u}|^2 ) + \vec{u} \times \vec{u} = \vec{f} - \frac{1}{\rho} \vec{\nabla} p$$

Irrational fluid

$$\vec{w} = \vec{\nabla} \times \vec{u} = 0$$

$\vec{u}$  is a conservative field  $\hookrightarrow$  "velocity potential"

$\Rightarrow$  pose a scalar field,  $\varphi(t, \vec{r})$

$$\vec{u} = \vec{\nabla} \varphi$$

$$\cancel{\frac{\partial}{\partial t} (\vec{V}\varrho) + \vec{V} \left( \frac{1}{2} |\vec{V}\varrho|^2 \right)} = \vec{J} - \frac{1}{\rho} \vec{V} P$$

$\vec{V} \left( \frac{\partial \varrho}{\partial t} \right)$

$$\vec{V} \left[ \frac{\partial \varrho}{\partial t} + \frac{1}{2} |\vec{V}\varrho|^2 \right] = \vec{J} - \frac{1}{\rho} \vec{V} P$$

$$\vec{J} = -\vec{V} \Psi = -\vec{V} \Psi - \frac{1}{\rho} \vec{V} \Pi$$

$$\vec{V} \left[ \frac{\partial \varrho}{\partial t} + \frac{1}{2} |\vec{V}\varrho|^2 + \Psi + \Pi \right] = -\frac{1}{\rho} \vec{V} P$$

$-\frac{1}{\rho} \vec{V} P$  is the gradient  
of some scalar field

$$\vec{V} w = \frac{1}{\rho} \vec{V} P$$

$$\vec{V} \left[ \frac{\partial \varrho}{\partial t} + \frac{1}{2} |\vec{V}\varrho|^2 + \Psi + w \right] = 0$$

( $w$  = total enthalpy per mass)

$$\left( \int_{\vec{r}_0}^{\vec{r}_i} \vec{v} w \cdot d\vec{r} = w(\vec{r}_i) - w(\vec{r}_0) \right)$$

Define

$$\int \frac{dP}{P} = \int_{\vec{r}_0}^{\vec{r}_i} \frac{\vec{v} P}{P} \cdot d\vec{r}$$

$$\vec{V} \left[ \frac{\partial Q}{\partial t} + \frac{1}{2} |\vec{V} Q|^2 + \underline{\underline{\Sigma}} + \int \frac{dP}{P} \right] = \vec{O}$$

$$\frac{\partial Q}{\partial t} + \frac{1}{2} |\vec{V} Q|^2 + \underline{\underline{\Sigma}} + \int \frac{dP}{P} = C(t)$$

Some maths

$$\frac{\partial Q}{\partial t} + \frac{1}{2} |\vec{V} Q|^2 + \underline{\underline{\Sigma}} + \int \frac{dP}{P} = E = \text{constant}$$

Inviscid + conservative force

incompressible  
steady flow

irrotational

$$\frac{1}{2} |\vec{u}|^2 + \underline{\underline{\sigma}} + \frac{\rho}{\rho_0} = E$$

= constant on  
each pathline

$$\frac{\partial \phi}{\partial t} + \frac{1}{2} |\nabla \phi|^2 + \underline{\underline{\sigma}} + \int \frac{d\phi}{\rho} = E$$

everywhere

$$E_A \int \int \int E_B \int \int$$

incompressible  
steady flow

irrotational

$$\frac{1}{2} |\nabla \phi|^2 + \underline{\underline{\sigma}} + \frac{\rho}{\rho_0} = E$$

everywhere

I<sup>5</sup> fluid : irrotational + steady flow  
incompressible  
inviscid

inviscid  
irrotational  $\Rightarrow \vec{u} = \vec{\nabla} \varphi$   
conservative  
incompressible  $\rho = \rho_0$

$$\int \frac{dP}{\rho} = \int \frac{dP}{\rho_0} = \frac{P}{\rho_0}$$

$$\frac{dp}{dt} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$\rho_0 \vec{\nabla} \cdot \vec{u} = 0$$

$$\vec{\nabla} \cdot \vec{u} = 0$$

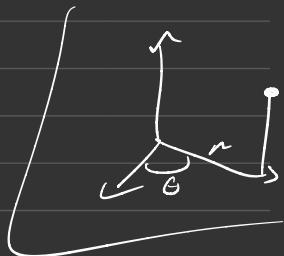
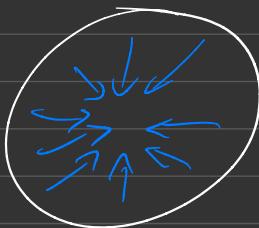
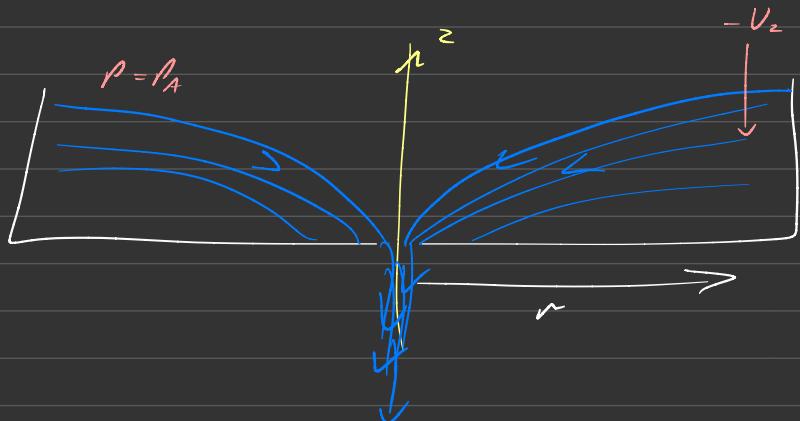
$$\boxed{\vec{\nabla}^2 \varphi = 0}$$

$\mathbb{T}^3$  fluid + conservative (but not necessarily steady flow)

$$\vec{\nabla}^2 \varphi = 0 + BC_s$$

$$\frac{d\varphi}{dt} + \frac{1}{2} |\vec{\nabla} \varphi|^2 + \frac{p}{\rho_0} = 0$$

## Example



- Inviscid (Euler equation)
- incompressible ( $\rho = \rho_0$ )
- irrotational (cylindrical symmetry)  $\nabla^2 \phi = 0$
- Steady flow
- Conservative force :  $\vec{F} = -g\hat{e}_z$ ,  $\nabla \phi = g$

$$\frac{1}{2} |\vec{\nabla} \phi|^2 + g_z + \frac{p}{\rho_0} = 0$$

$$\frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial \mathcal{Q}}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \mathcal{Q}}{\partial \theta^2} + \frac{\partial^2 \mathcal{Q}}{\partial z^2} = 0$$

$$\frac{\partial}{\partial r} \left( r \frac{\partial \mathcal{Q}}{\partial r} \right) = 0 \Rightarrow \frac{\partial \mathcal{Q}}{\partial r} = \frac{f(z)}{r}$$

$$\frac{\partial^2 \mathcal{Q}}{\partial z^2} = 0$$

$$\mathcal{Q}(r, z) = f(z) \ln r + g(z)$$

$$\frac{\partial^2 \mathcal{Q}}{\partial z^2} = f''(z) \ln r + g''(z) = 0$$

$$f(z) = az + b$$

$$g(z) = cz + d$$

$$\mathcal{Q}(r, z) = (az + b) \ln r + cz + d$$

$$\vec{w} = \vec{\nabla} \mathcal{Q}$$

$$w_r = \frac{\partial \mathcal{Q}}{\partial r} = \frac{az + b}{r}$$

$$w_z = \frac{\partial \mathcal{Q}}{\partial z} = a \ln r + c$$

$\lim_{n \rightarrow \infty} u_2$  diverges unless  $a=0$

$$u_r = \frac{b}{r} = -\frac{U_r}{r}$$

$$u_2 = c = -U_2$$

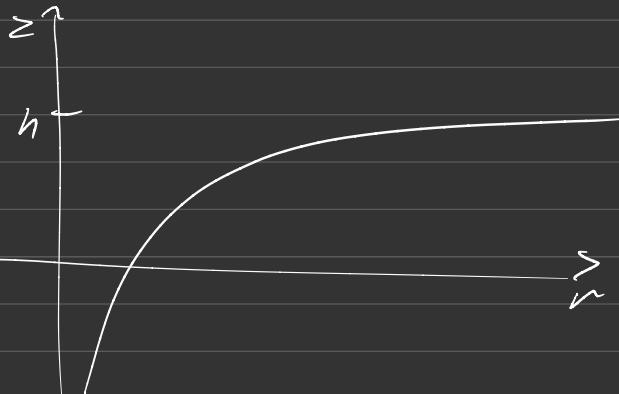
$$\frac{1}{2} \left( \frac{U_r^2}{r^2} + U_2^2 \right) + g_2 + \frac{\rho}{\rho_0} = \mathcal{E}$$

$$= \frac{1}{2} \left( \frac{U_r^2}{r_0^2} + U_2^2 \right) + g_{20} + \frac{\rho_0}{\rho_0}$$

Outside :  $\frac{1}{2} \left( \frac{U_r^2}{r^2} + U_2^2 \right) + g_2 + \frac{\rho_A}{\rho_0} = \mathcal{E}$

$$g_2 + \frac{U_r^2}{2r^2} = \mathcal{E} - \frac{U_2^2}{2} - \frac{\rho_A}{\rho_0}$$

$$z = A - \frac{\beta}{r^2}$$



## 4. Sound Waves and Mach number

Inviscid, no body force

$$\left[ \frac{d\vec{w}}{dt} + (\vec{u} \cdot \vec{\nabla}) \vec{w} \right] = -\vec{\nabla} P$$

Background adiabat: incompressible, static  
background  
(equation of state  $P(\rho)$ )

$$\vec{O} = -\vec{\nabla} P$$

$$P(t, r) = \rho_0$$

$$\vec{w}(t, r) = \vec{O}$$

$$P(t, r) = \rho_0 = P(\rho_0) \quad \varepsilon \approx 10^{-2}$$

Perturbation

$$P(t, \vec{r}) = \rho_0 + \varepsilon p_1(t, \vec{r}) + \varepsilon^2 p_2(t, \vec{r}) + \dots$$

$$\vec{w}(t, \vec{r}) = \vec{O} + \varepsilon \vec{u}_1(t, \vec{r}) + \varepsilon^2 \vec{u}_2(t, \vec{r}) + \dots$$

$$P(\rho) = P(\rho_0 + \varepsilon p_1(t, \vec{r}) + \varepsilon^2 p_2(t, \vec{r})) + \dots$$

$$= \rho(\rho_0) + \rho'(\rho_0)(\varepsilon\rho_1 + \varepsilon^2\rho_2 + \dots) \\ + \frac{1}{2} \rho''(\rho_0)(\varepsilon\rho_1 + \varepsilon^2\rho_2 + \dots)^2 + \dots$$

$$\frac{\partial \rho}{\partial t} + \vec{\nabla}(\rho \cdot \vec{u}) = 0$$

$$\frac{\partial}{\partial t} (\rho_0 + \varepsilon\rho_1 + \varepsilon^2\rho_2 + \dots)$$

$$+ \vec{\nabla} \left[ (\rho_0 + \varepsilon\rho_1 + \varepsilon^2\rho_2 + \dots) (\varepsilon \vec{u}_1 + \varepsilon^2 \vec{u}_2 + \dots) \right] = 0$$

$$\varepsilon \frac{\partial \rho_1}{\partial t} + \varepsilon^2 \frac{\partial \rho_2}{\partial t} + \varepsilon \rho_1 (\vec{\nabla} \cdot \vec{u}_1) + \varepsilon^2 \vec{\nabla} (\rho_1 \vec{u}_1 + \rho_0 \vec{u}_2) + \dots$$

$$= 0$$

$$O(\varepsilon) : \frac{\partial \rho_1}{\partial t} + \rho_1 (\vec{\nabla} \cdot \vec{u}) = 0$$

$$O(\varepsilon^2) : \frac{\partial \rho_2}{\partial t} + \vec{\nabla} \cdot (\rho_1 \vec{u}) + \rho_1 (\vec{\nabla} \cdot \vec{u}) = 0$$

$$\rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right] = \vec{\nabla} \cdot \rho$$

$$(\rho_0 + \epsilon \rho_1 + \dots) \left[ \frac{\partial}{\partial t} (\vec{\omega}) + (\vec{\omega} \cdot \vec{\nabla}) \vec{\omega} + \vec{\nabla} \cdot (\vec{\omega}) \right]$$

$$= -\vec{\nabla} \left( P(\rho) + \epsilon P'(\rho) \rho_1 + \dots \right)$$

$$O(\epsilon): \boxed{\rho_0 \frac{\partial \vec{\omega}}{\partial t} = -P'(\rho_0) \vec{\nabla} P} \Rightarrow \rho_1, \vec{\omega}$$

$$O(\epsilon^2): \rho_0 \frac{\partial \vec{\omega}_2}{\partial t} + \rho_1 \frac{\partial \vec{\omega}_2}{\partial t} + \rho_0 (\vec{\omega} \cdot \vec{\nabla}) \vec{\omega}_1$$

$$= -\frac{1}{2} P'(\rho_0) \vec{\nabla} P_1 - P'(\rho_0) \vec{\nabla} P_2$$

$$\frac{\partial P}{\partial t} + \rho_0 (\vec{\nabla} \cdot \vec{v}_1) = 0$$

$$\rho_1 \frac{\partial \vec{\omega}_1}{\partial t} = -P'(\rho_0) \vec{\nabla} P_1$$

$$\vec{\nabla} \cdot \left( \rho_1 \frac{\partial \vec{\omega}}{\partial t} \right) = \vec{\nabla} \cdot (-P'(\rho_0) \vec{\nabla} P_1)$$

$$\rho_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{v}_1) = -P'(\rho_0) \vec{\nabla}^2 P_1 \quad \boxed{\frac{\partial^2 P_1}{\partial t^2} = P'(\rho_0) \vec{\nabla}^2 P_1}$$

$$= \frac{\partial}{\partial t} \left( -\frac{\partial P_1}{\partial t} \right)$$

wave equation  
 $c_0 = \sqrt{P'(\rho_0)} = \text{speed of sound}$

$$\rho(t, \vec{r}) \approx \rho_0 + \epsilon \rho_1(t, \vec{r})$$

Plane wave ( $\text{nm}^{-1}$ )

$$\rho_1(t, \vec{r}) = A \cos(\vec{k} \cdot \vec{r} - \omega t)$$

$$|\vec{k}|/c = \omega \quad v = \frac{\omega}{2\pi} \quad \lambda = \frac{2\pi}{|\vec{k}|}$$

$$\rho(p) \Rightarrow \rho(P)$$

$$\rho'(P) = \frac{dp}{dP} = \frac{1}{\left(\frac{dP}{dp}\right)} = \frac{1}{P'(p)} = \frac{1}{c^2}$$

$$\rho(p) \text{ liquid}$$

$$\rho'(P) \text{ very small}$$

$$\Rightarrow c \text{ very large}$$

$$\frac{\partial \rho}{\partial t} + \rho_0 (\vec{v} \cdot \vec{u}_1) = 0$$

$$\rho_1 \frac{\partial \vec{u}}{\partial t} = -c_s^2 \vec{\nabla} P_1$$

$$\rho_1 \frac{\partial^2 \vec{u}}{\partial t^2} = -c_s^2 \vec{\nabla} \frac{\partial P_1}{\partial t}$$

$$= -c_0^2 \vec{\nabla} \left( -\rho_0 \vec{\nabla} \cdot \vec{u} \right)$$

$$\frac{\partial^2 \vec{u}}{\partial t^2} = c_0^2 \vec{\nabla}^2 \vec{u} + c_0^2 \vec{\nabla} \times (\vec{\nabla} \times \vec{u})$$

$$= c_0^2 \vec{\nabla}^2 \vec{u} + c_0^2 \vec{\nabla} \times \vec{u}$$



$$c(p) = \sqrt{p(p)}$$

When can we take a fluid as incompressible  
Inviscid & isotropic, no body forces etc.

$$\rho(\vec{u} \cdot \vec{\nabla}) \vec{u} = -\vec{\nabla} P(p)$$

$$= -P'(p) \vec{\nabla} p$$

$$= -c^2(p) \vec{\nabla} p$$

$$\vec{V}_P = - \frac{\rho(\vec{u} \cdot \vec{v}) \vec{u}}{c^2}$$

$$= \frac{-|\vec{u}|^2}{c^2} \quad \cancel{\frac{\rho(\vec{u} \cdot \vec{v}) \vec{u}}{|\vec{u}|^2}}$$

$$|\vec{u}| \frac{\vec{V}_P}{\rho} = \frac{-|\vec{u}|^2}{c^2} \frac{1}{(\vec{u} \cdot \vec{v}) \vec{u}}$$

$$\frac{|\vec{u}| |\vec{V}_P|}{\rho} = \frac{|\vec{u}|^2}{c^2} \frac{1}{|(\vec{u} \cdot \vec{v}) \vec{u}|}$$

Schwarz inequality

$$|\langle a | b \rangle|^2 \leq \langle a | a \rangle \langle b | b \rangle$$

$$|\vec{u}| = \sqrt{\vec{u} \cdot \vec{u}}$$

$$(\vec{V}_P) = \sqrt{\vec{V}_P \cdot \vec{V}_P} \quad |\vec{u}| |\vec{V}_P| \geq |\vec{u} \cdot \vec{V}_P|$$

$$\frac{|\vec{u}|^2}{c^2} \frac{1}{|(\vec{u} \cdot \vec{v}) \vec{u}|} \geq \frac{(\vec{u} \cdot \vec{V}_P)}{\rho} = \frac{|\omega|}{\frac{2\omega t}{\rho}}$$

$$\frac{D\rho}{Dt} = \frac{\partial \rho}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \rho$$

$$\frac{1}{\rho} \left| \frac{D\rho}{Dt} \right| \leq \frac{|\vec{u}|}{c^2} \frac{1}{|(\vec{u} \cdot \vec{\nabla}) \vec{u}|}$$

$$\Rightarrow \frac{|\vec{u}|}{c} < 1 = M \text{ Mach number}$$

$M \ll 1 \Rightarrow \text{incompressible}$

Recap,

Barotropic fluid

equation of state  $P(\rho)$  or  $\rho(P)$

speed of sound at density  $\rho$

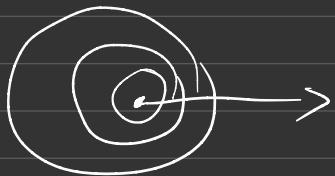
$$c(\rho) = \sqrt{P(\rho)}$$

$$\Rightarrow \text{Mach number } M = \frac{|\vec{u}|}{c} = \frac{|\vec{u}(t, \vec{x})|}{c(\rho(t, \vec{x}))}$$

$M \ll 1$  in some reg.  $\Rightarrow$  flow is approx  
incompressible  
can treat  $\rho$  as constant

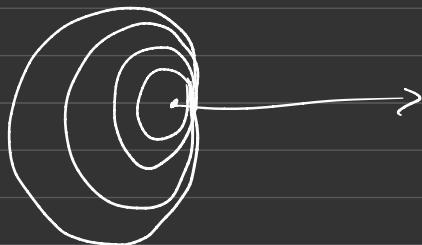
Note  $c \rightarrow \infty$   $\rho(r) \rightarrow$  const function)

$M < 1 :$



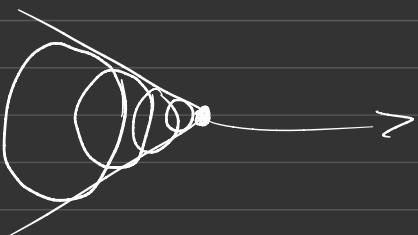
subsonic

$M = 1 :$



sonic

$M > 1 :$



supersonic

$c \approx 340 \text{ m.s}^{-1}$  for Air at NTP

Irrational, inviscid, no body force

$$\frac{d\ell}{dt} + \frac{1}{2} |\nabla \phi|^2 + \underbrace{\int \frac{dp}{\rho}}_{\text{body}} = C(t)$$

$$\int \frac{p'_{\text{body}} dy}{\rho}$$
$$= w(p)$$

steady

$$\frac{d\ell}{dt} + \frac{1}{2} |\nabla \phi|^2 + w(p) = C(t)$$

$$\frac{1}{2} u^2 + w(p) = E$$

$$\frac{1}{2} M^2 c_p^2 + w(p) = E$$

$$\Rightarrow M(p)$$

$$\Rightarrow M(c)$$

$$\Rightarrow M(p)$$

## 5. More on Potential flow

$$\text{irrotational} : \vec{\nabla} \times \vec{u} = \vec{\omega} = 0$$

$$\vec{\omega} = \vec{0} \Rightarrow \vec{u} = \vec{\nabla} \phi$$

$$\frac{\partial \phi}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$\frac{\partial \phi}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \phi + \rho (\vec{\nabla} \cdot \vec{u}) = 0$$

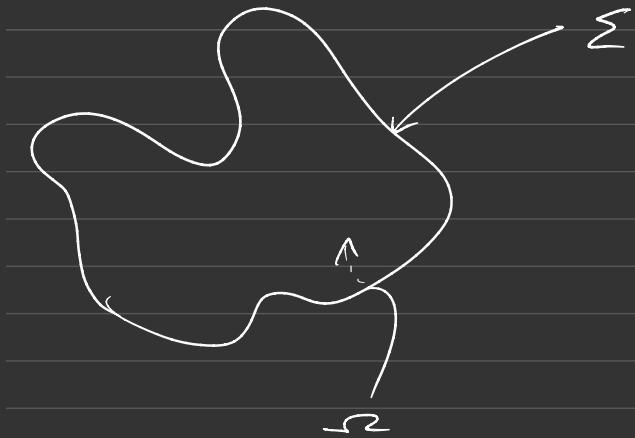
$$\frac{\partial \phi}{\partial t} = -\rho (\vec{\nabla} \cdot \vec{u}) \quad \vec{\nabla} = \frac{\partial}{\partial x} \hat{e}_x + \frac{\partial}{\partial y} \hat{e}_y + \frac{\partial}{\partial z} \hat{e}_z$$

$$\frac{\partial \phi}{\partial t} = -\rho \nabla^2 \phi$$

$$\text{Incompressibility} \quad \frac{\partial \phi}{\partial t} = 0$$

$$\nabla^2 \phi = 0 + BC's$$

$\Rightarrow$  BC some  $\Sigma$  entirely defines the fluid flow



$$\vec{u}, \rho$$

$$\vec{w} = \vec{\nabla} \varphi$$

$\vec{u}|_{\Sigma}$  satisfied

$\varphi_1$  and  $\varphi_2$

$$\begin{aligned}\nabla^2 \varphi_1 &= 0 & \nabla^2 \varphi_2 &= 0 \\ \vec{\nabla} \varphi_1|_{\Sigma} &= BC & \vec{\nabla} \varphi_2|_{\Sigma} &= BC\end{aligned}$$

$$\nabla^2 (\varphi_1 - \varphi_2) = 0$$

$$\vec{\nabla} \varphi_1|_{\Sigma} = \vec{\nabla} \varphi_2|_{\Sigma}$$

$$\vec{\nabla} (\varphi_1 - \varphi_2)|_{\Sigma} = \vec{0}$$

$$f = \varphi_1 - \varphi_2$$

$$\nabla^2 f = 0 \quad \text{on } \partial\Sigma$$

$$\vec{\nabla} f|_{\Sigma} = \vec{0}$$

$$\int \nabla^2 f = 0 \text{ on } \Sigma$$

$$\int_{\Sigma} \nabla^2 f dV = 0$$

$$\int \nabla^2 f = \int \vec{\nabla} \cdot (\vec{\nabla} f)$$

$$= \vec{\nabla} \cdot (\int \vec{\nabla} f) - \vec{\nabla} f \cdot \vec{\nabla} f$$

$$= \vec{\nabla} \cdot (\int \vec{\nabla} f) - |\vec{\nabla} f|^2$$

$$0 = \int_{\Sigma} \vec{\nabla} \cdot (\int \vec{\nabla} f) dV - \int_{\Sigma} |\vec{\nabla} f|^2 dV$$

$$= \oint_{\Sigma} (\int \vec{\nabla} f) \cdot \vec{n} ds - \int_{\Sigma} |\vec{\nabla} f|^2 dV$$

$$\Rightarrow \int_{\Sigma} |\vec{\nabla} f|^2 dV = 0$$

$$|\vec{\nabla} f| \geq 0$$

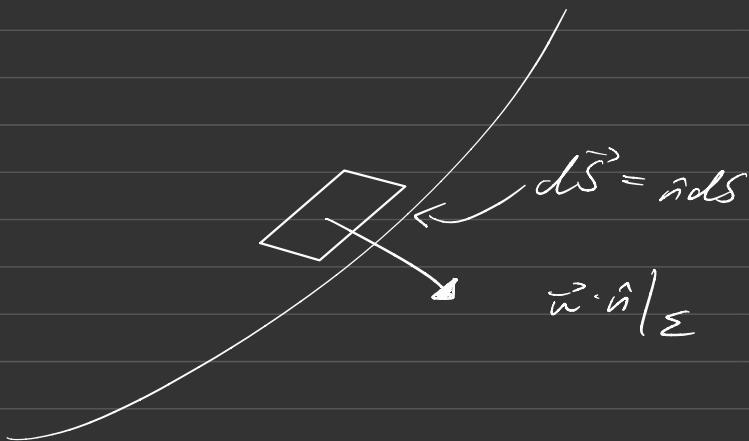
$$\Rightarrow |\vec{\nabla} f|^2 = 0$$

$$\Rightarrow \vec{\nabla} f = \vec{0}$$

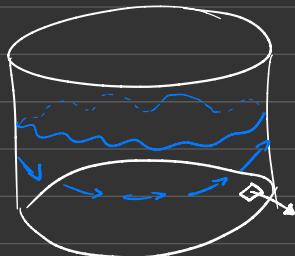
$$\vec{\nabla} f = \vec{0} \quad \text{on } \Sigma$$

$$\vec{\nabla} d_1 = \vec{\nabla} d_2 \quad \text{on } \Sigma$$

$\vec{w}|_{\Sigma} \Rightarrow$  unique velocity field



Given an inviscid fluid with  $\vec{w} \cdot \hat{n}|_{\Sigma}$  specified, there is a unique flow which is both irrotational and incompressible.



$$\vec{w} \cdot \hat{n}|_{\Sigma} = 0$$

$$\vec{w} = \vec{0}$$

$$\frac{\partial \phi}{\partial t} = -\rho \nabla^2 \phi$$

$$\nabla^2 \phi = -\frac{1}{\rho} \frac{\partial \rho}{\partial t} = \text{known?}$$

$$= \vec{E} \cdot \vec{u} = s(t, \vec{r})$$

$$\nabla^2 \phi = s(t, \vec{r}) \quad \text{Poisson equation}$$

### Electrostatics

$$\vec{E} = -\vec{\nabla} \phi$$

$$\vec{D} \cdot \vec{E} = -\nabla^2 \phi = -\frac{\rho}{\epsilon_0}$$

$$\nabla^2 \phi = -\frac{\rho}{\epsilon_0}$$

## rotational

$$\vec{\omega} = \vec{\nabla} \times \vec{u} = \vec{\Omega}$$

$$\vec{u} = \vec{\nabla} \varphi$$

$$\frac{\partial \varphi}{\partial t} + \vec{\nabla} \cdot (\rho \vec{a}) = 0$$

$$\underbrace{\frac{\partial \varphi}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \rho + \rho (\vec{\nabla} \cdot \vec{u})}_{= 0} = 0$$

$$\frac{\partial \rho}{\partial t} = -\rho (\vec{\nabla} \cdot \vec{u})$$

$$\vec{\nabla} \cdot \vec{u} = \gamma(t, \vec{r})$$

$$\vec{\nabla}^2 \varphi = \gamma(t, \vec{r})$$

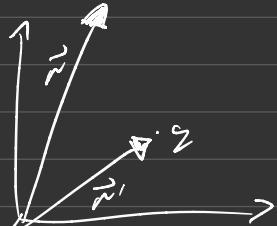
= Poisson's equation

MP 204:

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\text{statik} : \vec{E} = -\vec{\nabla} \mathcal{Q}$$

$$\vec{\nabla}^2 \mathcal{Q} = -\frac{\rho}{\epsilon_0}$$



$$d\varphi = \sqrt{dV'} \\ = \sqrt{dr'^2} dV'$$

$$d\mathcal{Q}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{d\varphi}{|\vec{r} - \vec{r}'|}$$

$$\mathcal{Q}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_S \frac{\rho(\vec{r}') dV'}{|\vec{r} - \vec{r}'|}$$

$$Q(t, \vec{r}) = -\frac{1}{4\pi} \int \frac{\gamma(t, \vec{r}') dV'}{|\vec{r} - \vec{r}'|} + Q_0(t, \vec{r})$$

$$\vec{\nabla}^2 Q_0 = 0$$

$$\vec{u}(t, \vec{r}) = \vec{\nabla} \varphi(t, \vec{r})$$

$$= -\frac{1}{4\pi} \vec{\nabla} \int_{\Omega} \frac{Y(t, \vec{r})}{|\vec{r} - \vec{r}'|} dV'$$

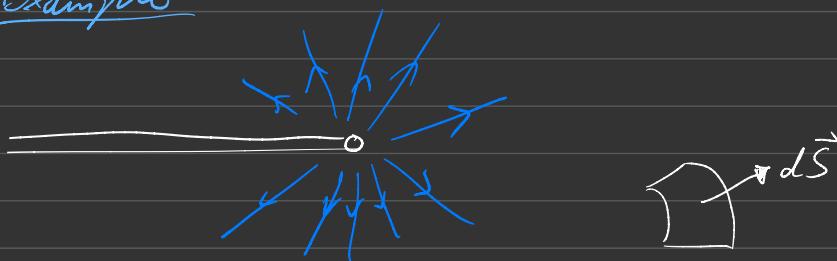
$$= -\frac{1}{4\pi} \int_{\Omega} Y(t, \vec{r}) \left( \vec{\nabla} \frac{1}{|\vec{r} - \vec{r}'|} \right) dV'$$

$$= -\frac{1}{4\pi} \int_{\Omega} \frac{\partial}{\partial \vec{r}} \frac{1}{\sqrt{(\vec{r}-\vec{r}')^2 + g^{-1} f(\vec{r}-\vec{r}')}^2} dV'$$

$$= -\frac{1}{4\pi} \int_{\Omega} \frac{(\vec{r} - \vec{r}')_x}{|\vec{r} - \vec{r}'|^3} dV'$$

$$\boxed{\vec{u}(t, \vec{r}) = \frac{1}{4\pi} \int_{\Omega} \frac{Y(t, \vec{r})(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dV' + \vec{\nabla} \varphi_0(t, \vec{r})}$$

Example



$$\oint_{\Sigma} \rho \vec{u} \cdot d\vec{S} = \rho \mathcal{T}$$

$$= \int \vec{\nabla} \cdot (\rho \vec{u}) dV$$

$$\mathcal{T} = \frac{\text{volume}}{\text{time}}$$

$$= \int \rho (\vec{\nabla} \cdot \vec{u}) dV$$

$$= \vec{\nabla} \cdot \vec{u}(t, \vec{r}) = \Im \delta(\vec{r}) = Y(t, \vec{r})$$

$$\vec{u}(\vec{r}) = \frac{1}{4\pi} \int \frac{\Im \delta(\vec{r}') (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dV'$$

$$= \frac{\Im(t)}{4\pi} \frac{\vec{r}}{r^3}$$

$$\mathcal{Q}(t, \vec{r}) = -\frac{1}{4\pi} \int \frac{Y(t, \vec{r}) dV}{|\vec{r} - \vec{r}'|}$$

$$= -\frac{\Im(t)}{4\pi} \frac{1}{r}$$

$$\frac{d\mathcal{Q}}{dt} + \frac{1}{2} |\vec{\nabla} \mathcal{Q}|^2 + \frac{\rho}{\rho} = \varepsilon$$

## 6. Vorticity

$$\vec{\omega} = \vec{\nabla} \times \vec{u}$$

### Euler's Equation

$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} = \vec{f} - \frac{1}{\rho} \vec{\nabla} p$$

$$(\vec{u} \cdot \vec{\nabla}) \vec{u} = \vec{\nabla} \left( \frac{1}{2} |\vec{u}|^2 \right) + (\vec{\nabla} \times \vec{u}) \times \vec{u}$$

$$\frac{\partial \vec{u}}{\partial t} + \vec{\nabla} \left( \frac{1}{2} |\vec{u}|^2 \right) + \vec{\omega} \times \vec{u} = \vec{f} - \frac{1}{\rho} \vec{\nabla} p$$

$$\vec{\nabla} \times \left( \frac{\partial \vec{u}}{\partial t} + \vec{\nabla} \left( \frac{1}{2} |\vec{u}|^2 \right) + \vec{\omega} \times \vec{u} \right) = \vec{\nabla} \times \left( \vec{f} - \frac{1}{\rho} \vec{\nabla} p \right)$$

$$\frac{\partial \vec{\omega}}{\partial t} + \vec{\nabla} \times (\vec{\omega} \times \vec{u}) = \vec{\nabla} \times \vec{f} + \frac{\vec{\nabla}_p \times \vec{\nabla} p}{\rho}$$

If  $\vec{f}$  is conservative, then

$$\vec{\nabla} \times \vec{f} = \vec{0}$$

If the fluid is inviscid

$$\rho = \rho(p)$$

then  $\vec{\nabla} p = p'(p) \vec{\nabla}_p$

$$\Rightarrow \frac{\partial \vec{w}}{\partial t} + \vec{\nabla} \times (\vec{w} \times \vec{u}) = \vec{0}$$

$$\vec{\nabla} \times (\vec{w} \times \vec{u}) = \vec{u}(\vec{\nabla} \cdot \vec{u}) + (\vec{u} \cdot \vec{\nabla})\vec{u}$$

$$- \vec{u}(\vec{\nabla} \cdot \vec{u}) - (\vec{u} \cdot \vec{\nabla})\vec{u}$$

$$\frac{\partial \vec{w}}{\partial t} = \vec{w}(\vec{\nabla} \cdot \vec{u}) + (\vec{u} \cdot \vec{\nabla})\vec{w} - \vec{u}(\vec{\nabla} \cdot \vec{w})^{\circ}$$
$$- (\vec{w} \cdot \vec{\nabla})\vec{u}$$

$$\frac{\partial \vec{w}}{\partial t} + (\vec{u} \cdot \vec{\nabla})\vec{w} - (\vec{w} \cdot \vec{\nabla})\vec{u} + \vec{w}(\vec{\nabla} \cdot \vec{u}) = \vec{0}$$

$$\boxed{\frac{\partial \vec{w}}{\partial t} = (\vec{w} \cdot \vec{\nabla})\vec{u} - \vec{w}(\vec{\nabla} \cdot \vec{u})}$$

Verbiest's  
Equation  
for inviscid  
fluids

- $\vec{\omega}(t) = \vec{\omega}_{\text{path}}(t) = \vec{\omega}(t, \vec{r}(t))$

$$\vec{\omega}(t) = \vec{\omega}(t_0) + \frac{1}{\Delta t} \vec{\omega}(t_0)(t - t_0) + \frac{1}{2} \frac{\partial^2 \vec{\omega}}{\partial t^2}(t_0)(t - t_0)^2 + \frac{1}{6} \frac{\partial^3 \vec{\omega}}{\partial t^3}(t_0)(t - t_0)^3 + \dots$$

$$\vec{\omega}(t_0) = \vec{0}$$

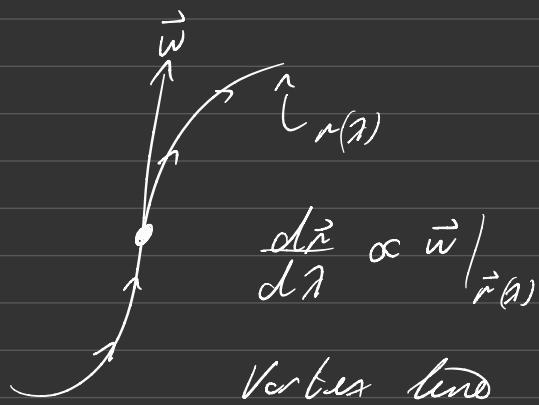
$$\frac{\partial \vec{\omega}}{\partial t}(t_0) = 0$$

$$\frac{\partial^2 \vec{\omega}}{\partial t^2}(t_0) = \vec{0}$$

$$\vec{\omega}(t_0) = \vec{0} \Rightarrow \vec{\omega}(t) = \vec{0}$$

•  $\vec{w}(t, \vec{r})$

non zero velocity

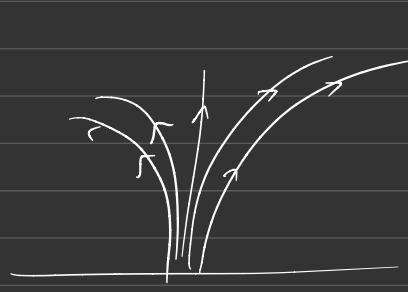


Vortex line

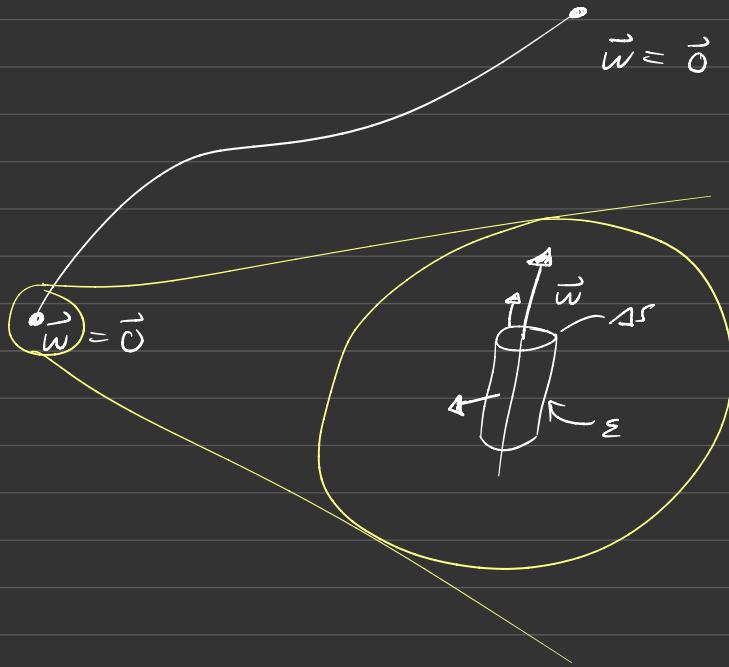
water spout  
Tornado



Hurricane



Fun fact : vortex lines cannot end within a fluid



$$\oint_{\Sigma} \vec{w} \cdot d\vec{S} = \vec{w} \cdot \hat{n} \Delta S$$
$$= \int_{\Omega} \nabla \cdot \vec{w} dV$$
$$= 0$$

irrotational but not compressible fluid

$$\vec{u} = \vec{\nabla} \varphi, \quad \vec{\nabla} \cdot \vec{u} = 0$$

$$\vec{u}_{\text{int}}(t, \vec{r}) = \frac{1}{4\pi} \int \frac{Y(t, \vec{r})(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dV$$

$$\nabla^2 \varphi = 0 \Rightarrow \varphi = - \frac{1}{4\pi} \int \frac{Y(t, \vec{r})}{|\vec{r} - \vec{r}'|} dV'$$

Incompressible but not irrotational

$$\vec{\nabla} \cdot \vec{u} = 0,$$

$$\vec{u} = \vec{\nabla} \times \vec{A} = \vec{\nabla} \times (\vec{A} + \vec{\nabla} \phi)$$

$$\vec{\nabla} \times \vec{u} = \vec{\omega} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A})$$

$$= \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A}$$

use this flexibility to  
pick  $\vec{\nabla} \cdot \vec{A} = 0$

$$\nabla^2 \vec{A} = -\vec{\omega}$$

$$\vec{A} = -\frac{1}{4\pi} \int \frac{\vec{\omega}(t, \vec{r}')}{|\vec{r} - \vec{r}'|} dV'$$

$$\begin{aligned}\vec{u}(t, \vec{r}) &= \vec{\nabla} \times \left( -\frac{1}{4\pi} \int \frac{\vec{\omega}(t, \vec{r}')}{|\vec{r} - \vec{r}'|} dV' \right) \\ &= -\frac{1}{4\pi} \int \frac{(\vec{r} - \vec{r}') \times \vec{\omega}(t, \vec{r}')}{|\vec{r} - \vec{r}'|^3} dV' \quad \text{(Biot Savart Law)}\end{aligned}$$

$$\begin{aligned}\vec{u}(t, \vec{r}) &= \frac{1}{4\pi} \int \frac{(\vec{r} - \vec{r}') Y(t, \vec{r}')}{|\vec{r} - \vec{r}'|} dV' \\ &\quad + \frac{1}{4\pi} \int \frac{(\vec{r} - \vec{r}') \times \vec{\omega}(t, \vec{r}')}{|\vec{r} - \vec{r}'|^3} dV' \\ &\quad + \vec{u}_o(t, \vec{r})\end{aligned}$$

$$\vec{A}(t, \vec{r}) = -\frac{1}{4\pi} \int \frac{\vec{\omega}(t, \vec{r}')}{|\vec{r} - \vec{r}'|} dV'$$

$$\vec{\nabla} \cdot \vec{A} = 0 ?$$

$$\vec{\nabla} \cdot \vec{A}(t, \vec{r}) = -\frac{1}{4\pi} \int \vec{\nabla} \left( \frac{1}{|\vec{r} - \vec{r}'|} \right) \cdot \vec{w}(t, \vec{r}') dV'$$

$$= \frac{1}{4\pi} \int \vec{\nabla}' \left( \frac{1}{|\vec{r} - \vec{r}'|} \right) \cdot \vec{w}(t, \vec{r}') dV'$$

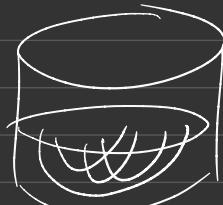
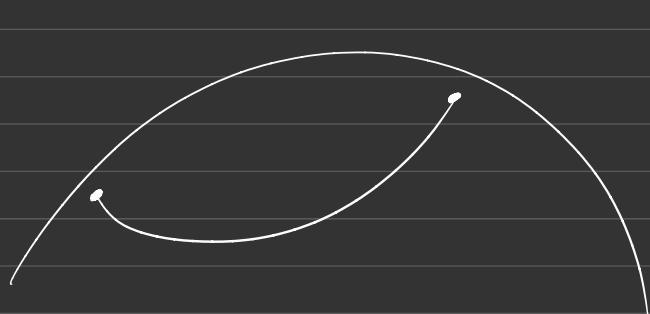
$$\vec{\nabla} \cdot \vec{A} = \frac{1}{4\pi} \int \left[ \vec{\nabla}' \cdot \left( \frac{1}{|\vec{r} - \vec{r}'|} \vec{w}(t, \vec{r}') \right) \right.$$

$$\left. - \frac{1}{|\vec{r} - \vec{r}'|} \vec{\nabla}' \cdot \vec{w}(t, \vec{r}') \right] dV$$

$$= \frac{1}{4\pi} \oint_{\Sigma} \frac{\vec{w}(t, \vec{r}')}{|\vec{r} - \vec{r}'|} \cdot d\vec{s}' = 0$$

$$\frac{1}{4\pi} \oint_{\Sigma} \frac{[\vec{w}(t, \vec{r}') \cdot \hat{n}']}{|\vec{r} - \vec{r}'|} dS' = 0$$

$$\vec{w} = 0 \rightarrow \text{possible}$$



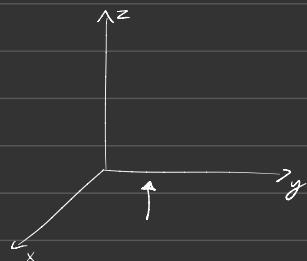
inviscid barotropic fluid with conservative body forces

$$\frac{\partial \vec{w}}{\partial t} = (\vec{w} \cdot \vec{\nabla}) \vec{w} - \vec{w} (\vec{\nabla} \cdot \vec{u})$$

- Incompressible :  $\vec{\nabla} \cdot \vec{u} = 0$

- 2-dimensional :  $\frac{\partial (w \hat{e}_z)}{\partial t} = (w \hat{e}_z \cdot \vec{\nabla}) \vec{u}$   
 $= w \frac{\partial}{\partial z} \vec{u} = \vec{0}$

$$\frac{\partial \vec{w}}{\partial t} = \vec{0}$$

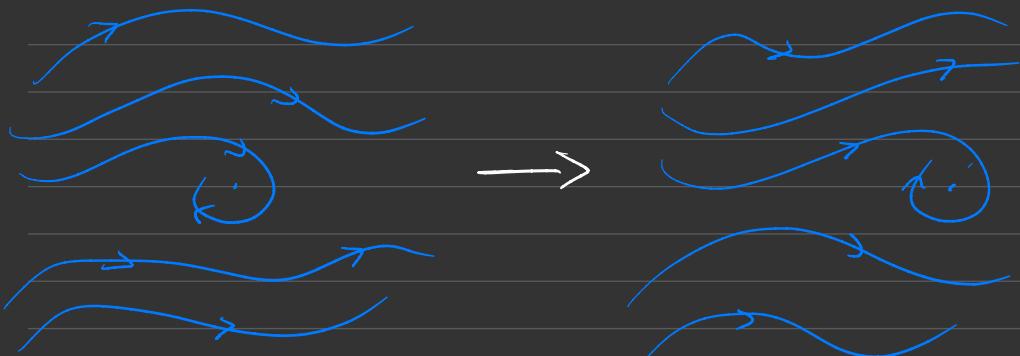


xy-plane :  $\vec{u}(t, \vec{r}) = u_x(t, x, y) \hat{e}_x + u_y(t, x, y) \hat{e}_y$

$$\vec{w} = \vec{\nabla} \times \vec{u} = \hat{e}_x \left( \frac{-\partial u_y}{\partial z} \right)^C + \hat{e}_y \left( \frac{-\partial u_x}{\partial z} \right)^C$$

$$+ \hat{e}_z \left( \frac{\partial u_x}{\partial y} - \frac{\partial u_y}{\partial x} \right)$$

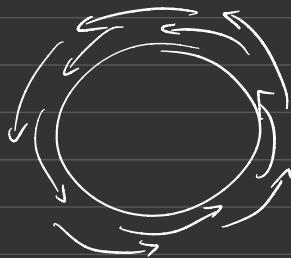
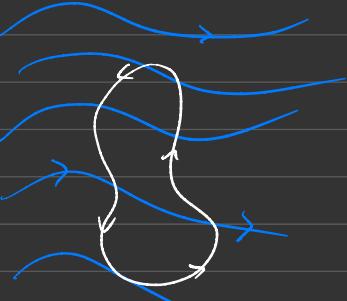
$$= \left( \frac{\partial u_x}{\partial y} - \frac{\partial u_y}{\partial x} \right) \hat{e}_z$$



En 3D ?

$$\Gamma_C = \oint \vec{u} \cdot d\vec{s}$$

= circulation around C



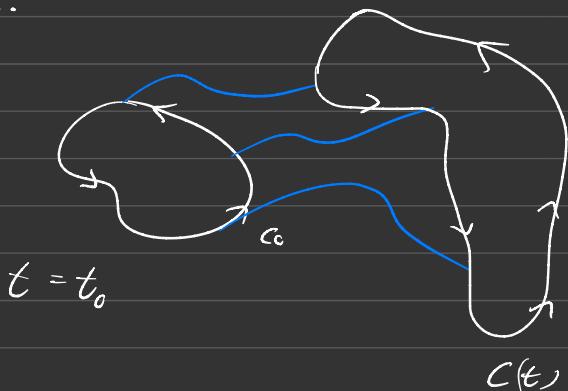
# Irish Physics

## Kelvin's Theorem

inviscid, incompressible, subject to a conservative body force.

The circulation of the fluid around any material closed curve is constant.

If  $t = t_0$



$t = t_0$

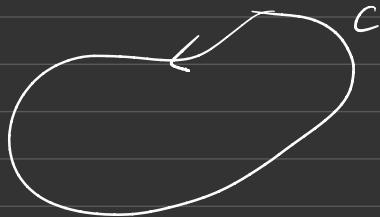
$C(t)$

$$\Gamma_{C(t)} = \oint_{C(t)} \vec{u} \cdot d\vec{\sigma}$$

$$\frac{d\Gamma_{C(t)}}{dt}$$

Recap

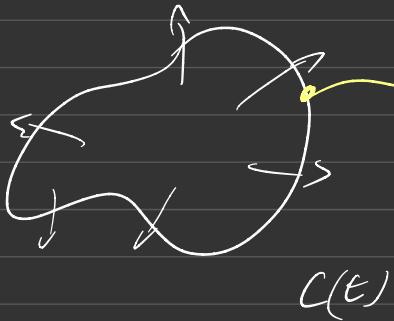
Kelvin's Theorem



$$\oint \vec{u} \cdot d\vec{r} = \Gamma_c$$

$t = t_0$

$t > t_0$



$$\frac{d\Gamma_{c(t)}}{dt} = 0$$

Inviscid, incompressible, conservative force

$$t \quad \vec{f}_t(\lambda) \quad \lambda \in [0, 1]$$

$$\vec{f}_t(0) = \vec{f}_t(1)$$

$$\frac{\partial \vec{r}_t(\lambda)}{\partial t} = \vec{u}(t, \vec{r}_t(\lambda))$$

$$\int_{c(t)} = \oint_{C(t)} \vec{u} \cdot d\vec{r}$$

$$= \int_0^1 \vec{u}(t, \vec{r}_t(\lambda)) \cdot \frac{\partial \vec{r}_t(\lambda)}{\partial \lambda} d\lambda$$

$$\frac{d}{dt} \int_{c(t)} = \int_0^1 \left[ \frac{\partial \vec{u}}{\partial t} \cdot \frac{\partial \vec{r}_t}{\partial \lambda} + \vec{u}(t, \vec{r}_t(\lambda)) \cdot \frac{\partial^2 \vec{r}_t}{\partial t \partial \lambda} \right] d\lambda$$

$$= \int_0^1 \left\{ \left[ \vec{f} - \frac{1}{\rho} \vec{\nabla} p \right] \cdot \frac{\partial \vec{r}_t}{\partial \lambda} (\lambda) \right.$$

$$+ \vec{u}(t, \vec{r}_t(\lambda)) \cdot \frac{d}{d\lambda} \vec{u}(t, \vec{r}_t(\lambda)) \right\} d\lambda$$

$$\vec{u} \cdot \frac{d\vec{u}}{d\lambda} = \frac{d}{d\lambda} \left( \frac{1}{2} \vec{u} \cdot \vec{u} \right)$$

$$= \frac{1}{2} |\vec{u}|^2 \Big|_0^1 + \int_0^1 \left( \vec{f} - \frac{1}{\rho} \vec{\nabla} p \right) \cdot \frac{\partial \vec{r}_t}{\partial \lambda} (\lambda) d\lambda$$

$$= \int_0^1 \left[ -\vec{\nabla} \varphi - \vec{\nabla} \left( \frac{p}{\rho} \right) \right] \cdot \frac{\partial \vec{r}_t}{\partial \lambda} d\lambda$$

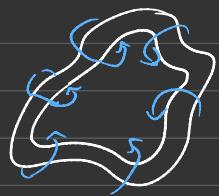
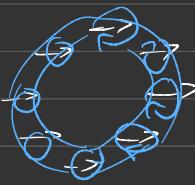
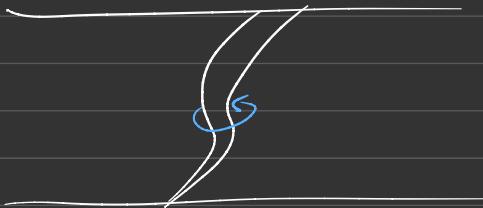
$$\frac{d\Gamma_{ce}}{dt} = - \int_0^1 \vec{\nabla} \left( \varphi + \frac{P}{\rho_0} \right) \cdot \frac{\partial \vec{x}}{\partial t} dt$$

$$= - \left. \varphi + \frac{P}{\rho_0} \right|_0^1 = 0$$

$$\Gamma_{ce} = \oint \vec{a} \cdot d\vec{s}$$

$$= \int_{\Sigma(t)} (\vec{\nabla} \times \vec{a}) \cdot d\vec{s}$$

$$= \int_{\Sigma(t)} \vec{w} \cdot d\vec{s}$$

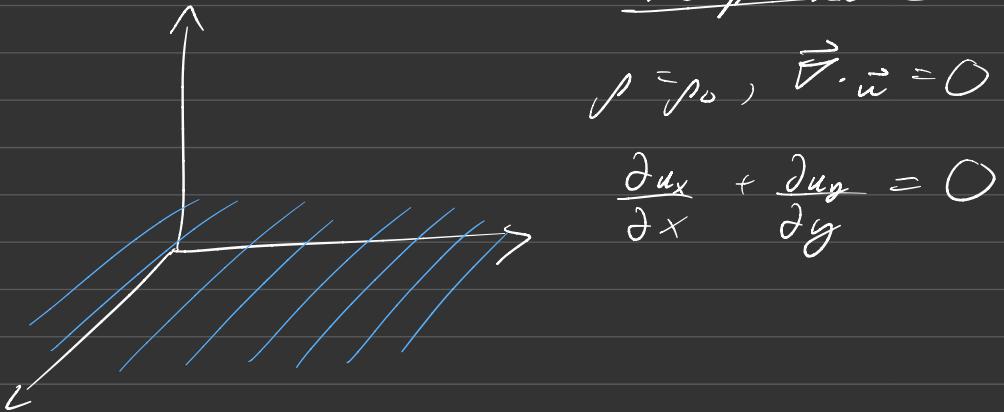


2D incompressible, inviscid flow

$$\frac{\partial \vec{u}}{\partial t} = \vec{0} \quad (= (\vec{\omega} \cdot \vec{\nabla}) \vec{u} - \vec{u} (\vec{\nabla} \cdot \vec{\omega}))$$

## 6. Inviscid Fluids in 2D

$$\vec{u}(t, \vec{r}) = u_x(t, x, y) \hat{e}_x + u_y(t, x, y) \hat{e}_y$$



Propose a vector  $\vec{\Psi}$  such that

$$\vec{u} = \vec{\nabla} \times \vec{\Psi}, \text{ then } \vec{\nabla} \cdot \vec{u} = 0$$

$$\vec{\nabla} \times \vec{\Psi} = \left( \frac{\partial \psi_z}{\partial y} - \cancel{\frac{\partial \psi_y}{\partial z}} \right) \hat{e}_x + \left( \cancel{\frac{\partial \psi_x}{\partial z}} - \frac{\partial \psi_z}{\partial x} \right) \hat{e}_y \\ + \left( \frac{\partial \psi_y}{\partial x} - \cancel{\frac{\partial \psi_x}{\partial y}} \right) \hat{e}_z$$

$$\frac{\partial \psi_y}{\partial x} = \frac{\partial \psi_x}{\partial y}$$

$$\vec{\nabla} \times \vec{\Psi} = \vec{\nabla} \times (\vec{\Psi} + \vec{\nabla} f)$$

$\Rightarrow$  1 degree of freedom

$$\vec{\Psi}(t, x, y, z) = \vec{\Psi}(t, x, y) \hat{e}_z$$

$$\vec{u} = \frac{\partial \Psi}{\partial y} \hat{e}_x - \frac{\partial \Psi}{\partial x} \hat{e}_y$$

$$u_x = \frac{\partial \Psi}{\partial y}, \quad u_y = -\frac{\partial \Psi}{\partial x}$$

$$\vec{u} \cdot (\vec{\nabla} \psi) = u_x \frac{\partial \psi}{\partial x} + u_y \frac{\partial \psi}{\partial y}$$

$$= -u_x u_y + u_y u_x = 0$$

$\vec{\nabla} \psi$  pick a time  $t$ , then look at the curve

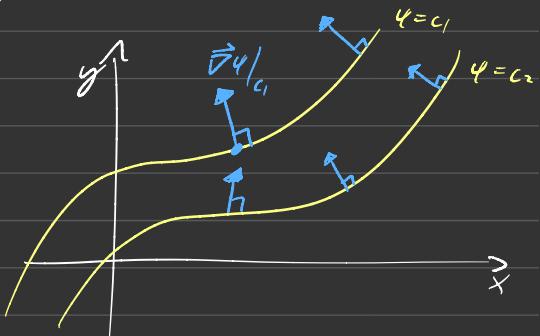
$$\psi(t, x, y) = \text{constant}$$

$\Rightarrow$  the tangent vectors of the level curves

$$\psi = \text{const}$$

are parallel to  $\vec{u}$

Definitions

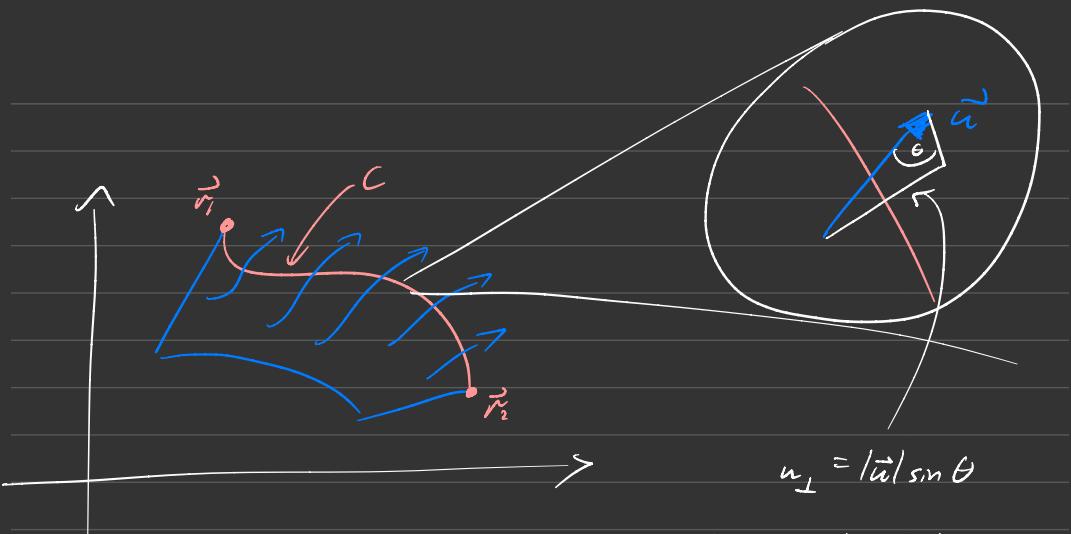


- Pathlines: a curve whose tangent vectors are equal to the fluid's velocity field

- Streamlines: a curve whose tangent vectors are parallel to  $\vec{u}$

Note: for steady flow, streamlines = pathlines

↳  $\psi$  is called the stream function of the fluid



$$u_{\perp} = |\vec{u}| \sin \theta$$

$$dA = |\vec{u}| \sin \theta |ds| \Delta t$$

$$|ds| = |\vec{dr}|$$

$$dA = |\vec{u}| / |\vec{dr}| \sin \theta \Delta t$$

$$= |\vec{u} \times \vec{dr}| \Delta t$$

$$= (\vec{u} \times \vec{dr}) \cdot \hat{e}_z \Delta t$$

$Q$  = "areal rate of flow"

$$= \frac{dA}{dt} = \int_C \vec{u} \times \vec{dr} \cdot \hat{e}_z$$

2D incompressible inviscid fluid

$$\vec{u} = u_x(t, x, y) \hat{e}_x + u_y(t, x, y) \hat{e}_y$$

Incompressible

$$\Rightarrow \vec{\nabla} \cdot \vec{u} = 0 \Rightarrow \vec{u} = \vec{\nabla} \times \vec{\Psi}$$

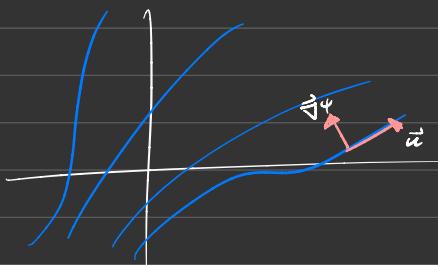
Can choose  $\vec{\Psi} = \psi(t, x, y) \hat{e}_z$

↗ stream function

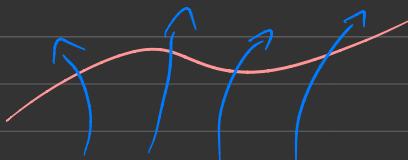
Gives

$$u_x = \frac{\partial \psi}{\partial y}, \quad u_y = -\frac{\partial \psi}{\partial x}$$

$\psi = \text{constant}$  gives streamlines of flow



path curve  
and create flow  
throughout



Agued

$$(\vec{u} \times d\vec{r}) \cdot \hat{e}_z \Delta t = \Delta A$$

$$\frac{dA}{dt} = Q_c = \left( \int_C \vec{u} \times d\vec{r} \right) \cdot \hat{e}_z$$

$$= \frac{\text{area}}{\text{time}}$$

$$\rho(t, \vec{r}) = \sigma_0 S(z)$$

$$\Rightarrow \sigma_0 Q_c = \frac{\text{mass}}{\text{time}}$$

$$\begin{aligned}\vec{u} \times d\vec{r} &= (u_x \hat{e}_x + u_y \hat{e}_y) \times (dx \hat{e}_x + dy \hat{e}_y) \\ &= (u_x dy - u_y dx) \hat{e}_z\end{aligned}$$

$$Q_c = \int (u_x dy - u_y dx)$$

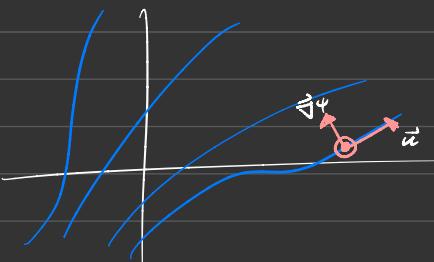
$$= \int \left( \frac{\partial \Psi}{\partial y} dy - \frac{\partial \Psi}{\partial x} dx \right)$$

$$= \int_C \vec{\nabla} \Psi \cdot d\vec{r}$$

$$= \Psi(\vec{r}_2) - \Psi(\vec{r}_1)$$

$$u_x = \frac{\partial \Psi}{\partial y}, \quad u_y = -\frac{\partial \Psi}{\partial x}$$

$\Psi = \text{constant}$  gives streamlines of flow



$$\vec{u} \times \vec{\nabla} \Psi$$

$$= \left( u_x \frac{\partial \Psi}{\partial y} - u_y \frac{\partial \Psi}{\partial x} \right) \hat{e}_z$$

$$= (u_x^2 + u_y^2)^{\frac{1}{2}} = |\vec{u}| > 0$$

$$\begin{matrix} \hookrightarrow (\vec{u}, \vec{\nabla} \Psi, \hat{e}_z) \\ (\hat{e}_x, \hat{e}_y, \hat{e}_z) \end{matrix}$$

If the fluid is also irrotational, then  
for continues

$$\Rightarrow \vec{\omega} = \vec{\nabla} \times \vec{u} = \vec{0}$$

$$\vec{u} = \vec{\nabla} \varphi = \vec{\nabla} \times \vec{\psi}$$

$$u_x = \frac{\partial \varphi}{\partial y} = \frac{\partial \psi}{\partial x}$$

$$u_y = -\frac{\partial \varphi}{\partial x} = \frac{\partial \psi}{\partial y}$$

2D I<sup>3</sup>:  $\varphi(t, x, y), \psi(t, x, y)$

that satisfy the

Cauchy-Riemann conditions (CR)

$$\frac{\partial \varphi}{\partial x} = \frac{\partial \psi}{\partial y}, \quad \frac{\partial \varphi}{\partial y} = -\frac{\partial \psi}{\partial x}$$

Facts about the CR conditions

If  $\varphi(x, y), \psi(x, y)$  satisfy the CR conditions, then the complex function

$$\varphi(x, y) + i\psi(x, y)$$

is a function of  $z = x + iy$

$$w(z)$$

Example

$$\varphi = x, \psi = y$$

$$\varphi + i\psi = x + iy$$

$$W(z) = z$$

Example

$$\varphi(x, y) = 2xy - y$$

$$\psi(x, y) = y^2 - x^2 + x$$

$$\frac{\partial \varphi}{\partial x} = 2y \quad \frac{\partial \varphi}{\partial y} = 2x - 1$$

$$\frac{\partial \psi}{\partial x} = -2x + 1 \quad \frac{\partial \psi}{\partial y} = 2y$$

$$\begin{aligned} & 2xy - y + i(y^2 - x^2 + x) \\ &= -i(x^2 - y^2 + 2ixy) + i(x + iy) \\ &= -i(x + iy)^2 + i(x + iy) \end{aligned}$$

$$W(z) = -iz^2 + iz$$

Any complex function gives a 2D $\mathbb{F}$

$$\varrho(x, y) = \operatorname{Re}(w(x, y))$$

$$\psi(x, y) = \operatorname{Im}(w(x, y))$$

Example

$$w(z) = a \in \mathbb{C}$$

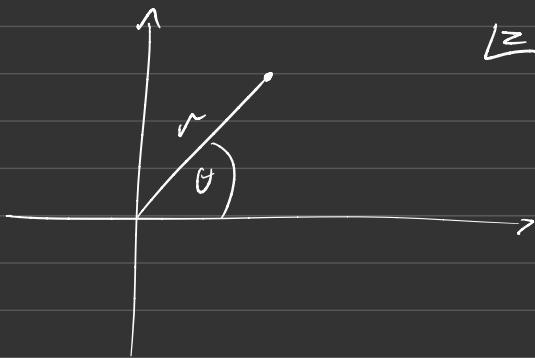
$$\varrho = \operatorname{Re}(a)$$

$$\vec{w} = \vec{0}$$

Example

$$w(z) = az \quad a \in \mathbb{C}$$

$$a = re^{i\theta}$$



Lz

$$r = |a|$$
$$\theta = \arg(a)$$

$$a = r \cos \theta + i r \sin \theta$$

$$w(x, y) = u(x, y)$$

$$= (r \cos \theta + i \sin \theta)(x + iy)$$

$$= r \cos \theta x - r \sin \theta y$$

$$+ i(r \cos \theta x + r \sin \theta y)$$

$$Q(x, y) = r \cos \theta x - r \sin \theta y$$

$$\psi(x, y) = r \sin \theta x - r \cos \theta y$$

$$\vec{u} = \vec{\nabla} \phi = r \cos \theta \hat{e}_x - r \sin \theta \hat{e}_y$$

$$= r \cos \theta \hat{e}_x + r \sin \theta \hat{e}_y$$

$$\psi = c = r \sin \theta x + r \cos \theta y$$

$$y = -\tan \theta x + \frac{c}{r \cos \theta}$$

$$= \tan(-\theta)x + \frac{c}{r \cos \theta}$$



$$w(z) = \varphi(x, y) + i\psi(x, y)$$

$$w'(z) = \left( \frac{\partial \varphi}{\partial x} - i \frac{\partial \psi}{\partial y} \right)$$

$$= \frac{\partial \varphi}{\partial y} + i \frac{\partial \psi}{\partial x}$$

Example

$$w(z) = az^2 + \frac{3z}{z} - \sin((1+i)z)$$

$$w'(z) = 2az - \frac{3}{z^2} - (1+i)\cos((1+i)z)$$

$$= u_x - iu_y$$

Example

$$w(z) = -cz^2 + iz$$

$$\varphi(x, y) = 2xy - y$$

$$\begin{aligned} u_x &= 2y \\ u_y &= 2x - 1 \end{aligned}$$

$$= -2i(x+iy) + i$$

$$= 2y + i(1-2x)$$

$$= u_x - i u_y$$

$$W'(z) = u_x - i u_y$$

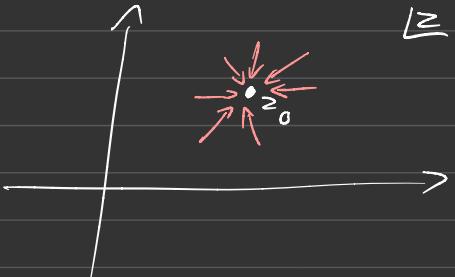
$$|W'(z)| = \sqrt{u_x^2 + u_y^2} = |\vec{u}|$$

We say that if  $z_0 \in \mathbb{C}$  such that

$\lim_{z \rightarrow z_0} W(z)$  does not exist

Then we call  $z_0$  a "singularity" of  $W(z)$

$$x \rightarrow x_0$$



## Types On P53

P2 numerator of 4 should be

$$y^{-x-1}, \text{ not } y^{-x+1}$$

P4 (1) "circle"  $\rightarrow$  "curve"

Recap

Velocity potential       $\phi(x, y)$   
Stream function       $\psi(x, y)$

CR cond's

$$\frac{\partial \phi}{\partial x} = \frac{\partial \psi}{\partial y}, \quad \frac{\partial \phi}{\partial y} = -\frac{\partial \psi}{\partial x}$$

$$\Rightarrow w(z) = \phi(x, y) + i\psi(x, y)$$

$$z = x + iy$$

$$w'(z) = u_x - iu_y$$

$$\text{So } |w'(z)| = |\vec{u}|$$

Singularity: if  $z_0 \in \mathbb{C}$  such that

$\lim_{z \rightarrow z_0} w(z)$  doesn't exist

then  $z_0$  is a singularity of  $w(z)$

$w(z)$ : if  $z_0 \in \mathbb{C}$ , then we can write

$$w(z) = \sum_{n=-\infty}^{\infty} a_n (z - z_0)^n$$

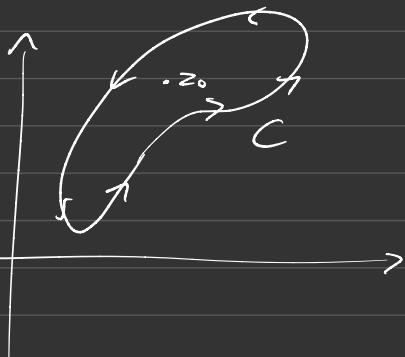
$$= \dots + \frac{a_{-2}}{(z-z_0)^2} + \frac{a_{-1}}{(z-z_0)} + a_0 + a_1(z-z_0) + a_2(z-z_0)^2 + \dots$$

Called a Laurent series

$$\oint_C W(z) dz = 2\pi i a_{-1}$$

$= 0$

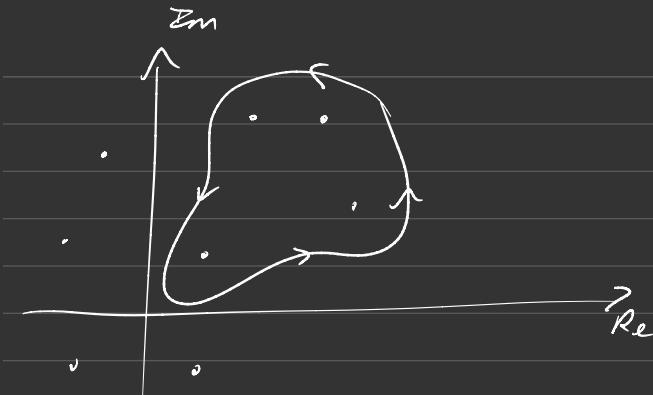
if  $C$  encircles  $z_0$   
if  $C$  does not  
encircle  $z_0$



Residue of  $w(z)$  at  
 $z_0$   
 $= \text{Res}(w(z), z_0)$

$=$  coefficient of the  
 $(z - z_0)^{-1}$  term in the  
Laurent series

$$\oint_C W(z) dz = 2\pi i \sum_{\substack{z_0 \text{ enclosed} \\ \text{by } C}} \text{Res}(w(z), z_0)$$



### Example

$$W(z) = a \ln z \quad a \in \mathbb{R}$$

$$= a \ln(x+iy)$$

$$= a \ln(re^{i\theta})$$

$$= a(\ln r + i\theta)$$

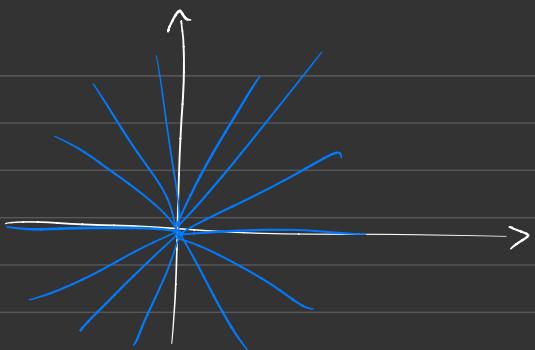
$$= a \ln r + i a \theta$$

$$\operatorname{Re}(W(z)) = \operatorname{Re}(x, y) = a \ln r = a \ln \sqrt{x^2+y^2}$$

$$\operatorname{Im}(W(z)) = \operatorname{Im}(x, y) = a\theta(x, y)$$

$$\psi = c_1 = a\theta$$

$$\Rightarrow \theta = \frac{c_1}{a}$$



$$\ell(x,y) = \frac{a}{2} \ln(x^2 + y^2)$$

$$\frac{\partial \ell}{\partial x} = \frac{ax}{x^2 + y^2} = ux$$

$$\frac{\partial \ell}{\partial y} = \frac{ay}{x^2 + y^2} = uy$$

$$w(z) = a \ln z$$

$$w'(z) = \frac{a}{z} = \frac{a}{x+iy} \frac{x-iy}{x-iy}$$

$$= \frac{a(x-iy)}{x^2+y^2} = \frac{ax}{x^2+y^2} - i \frac{ay}{x^2+y^2}$$



## Example

$$W(z) = i b \ln z \quad b \in \mathbb{R}$$

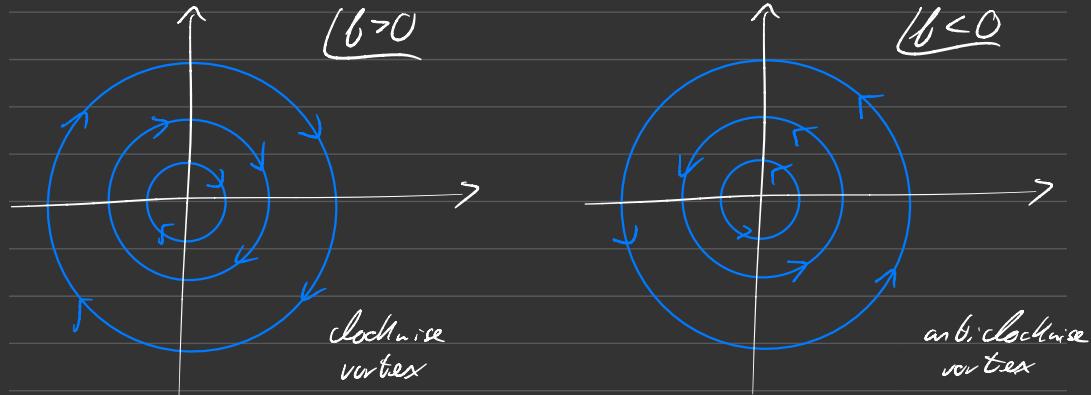
$$= i b \ln(r e^{i\theta})$$

$$= i b (\ln r + i\theta)$$

$$= -b\theta + i b \ln r$$

$$\vartheta(x,y) = -b\theta = -b[\arctan(\frac{y}{x}) + \alpha]$$

$$\psi(x,y) = b \ln r$$



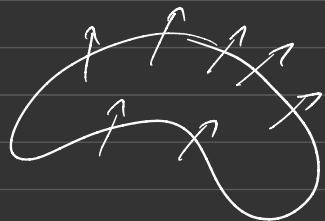
$$W'(z) = \frac{i b}{z} = \frac{i b (x - iy)}{x^2 + y^2} = \frac{iy + ix}{x^2 + y^2}$$

$$= \frac{iy}{x^2 + y^2} + \frac{ix}{x^2 + y^2} = u_x - iu_y$$

$$u_x(x, y) = \frac{ky}{x^2 + y^2}$$

$$u_y(x, y) = \frac{-kx}{x^2 + y^2}$$

## Circulation stuff



$$\Gamma_c = \oint_c \vec{u} \cdot d\vec{r}$$

$$Q_c = \left( \oint_c \vec{u} \times d\vec{r} \right) \cdot \hat{e}_z$$

$$\oint_c W(z) dz$$

$$W(z) = u_x - i u_y$$

$$z = x + iy$$

$$dz = dx + idy$$

$$\oint_c (u_x + i u_y) dx + i dy$$

$$= \oint_c [u_x dx + u_y dy + i(u_x dy - u_y dx)]$$

$$= \oint_C \vec{u} \cdot d\vec{r} + i \oint (u_x dy - u_y dx)$$

$$= \oint_C \vec{u} \cdot d\vec{r} + i \oint (\vec{u} \times d\vec{r}) \cdot \hat{e}_z$$

$$= \boxed{\oint_C W'(z) dz = \int_C + iQ_C}$$

Consider

$$W(z) = a \ln z \quad \text{singularities at } 0$$

$$W(z) = \frac{a}{z}$$

$$= \dots + \frac{a_{-2}}{z^2} + \frac{a_{-1}}{z} + a_0 + a_1 z + a_2 z^2 + \dots$$

$$\text{Res}(W(z), 0) = a$$

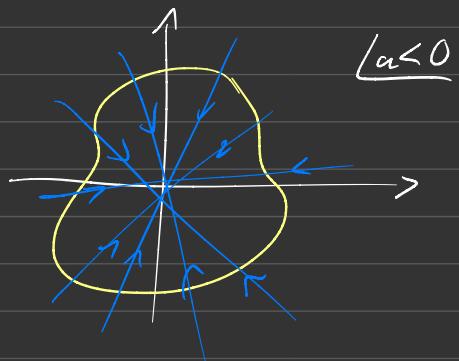
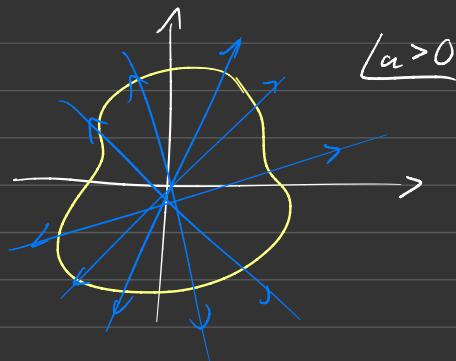
$$\oint_C W(z) dz = \begin{cases} 2\pi i a & \text{if } C \text{ encloses } 0 \\ 0 & \text{if not} \end{cases}$$

note that as

$$\oint_C w'(z) dz = \Gamma_c + iQ_c$$

$$\Rightarrow \Gamma_c = 0$$

and  $Q_c = \begin{cases} 2\pi a & \text{if } C \text{ encloses } 0 \\ 0 & \text{if not} \end{cases}$



Now consider

$$w(z) = ib \ln z$$

$$w'(z) = \frac{ib}{z}$$

$$\Rightarrow \operatorname{Res}(w'(z), 0) = ib$$

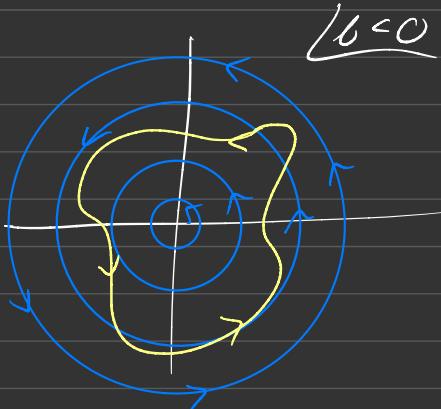
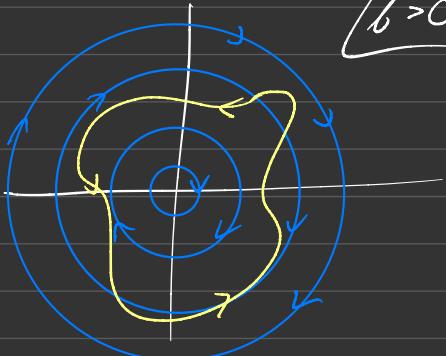
$$\oint \nabla V(z) dz = 2\pi i (i k)$$

$$= -2\pi k$$

$$= \Gamma_c + i Q_c$$

$$\Rightarrow \Gamma_c = -2\pi k$$

$$Q_c = 0$$



## Bernoulli's Principle

$$\frac{d\ell}{dt} + \frac{1}{2} |\vec{\nabla} \phi|^2 + \frac{p}{\rho} = C(t)$$

$$\text{Incompressible} \Rightarrow \int \frac{dp}{\rho} = \frac{p}{\rho_0}$$

$$\text{steady} \Rightarrow \frac{\partial \varphi}{\partial t} = 0, \quad C(t) = \mathcal{E}$$

$$\frac{1}{2} |\vec{\nabla} \varphi|^2 + \Psi + \frac{P}{\rho_0} = \mathcal{E}$$

Reyn

2D  $\mathbb{E}^3$  fluid

$$V(t, z) = \varphi(x, y) + i\psi(x, y)$$

$$\vec{u} = \vec{\nabla} \varphi \quad \text{or} \quad W(z) = u_x - i u_y \Rightarrow$$

$$\psi(t, x, y) = \text{constant} \Rightarrow \text{streamline}$$

But there's ~~the~~ pressure

irrotational + incompressible + inviscid + conservative force

↳ Bernoulli's Principle

$$\frac{\partial \varphi}{\partial t} + \frac{1}{2} |\vec{\nabla} \varphi|^2 + \Psi + \frac{P}{\rho_0} = C(t)$$

$$\text{if steady} \quad \frac{1}{2} |\vec{\nabla} \varphi|^2 + \Psi + \frac{P}{\rho_0} = \mathcal{E}$$

$$\Rightarrow \rho$$

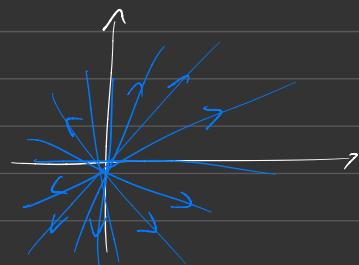
$$W(z) = \text{abs } z$$

$$= \alpha \ln \sqrt{x^2 + y^2} + i \arg(x + iy)$$

$$\vartheta = \frac{\alpha}{2} \ln(x^2 + y^2)$$

$$\vec{\nabla} \vartheta = \vec{w} = \frac{\alpha}{2} \left( \frac{2x}{x^2 + y^2} \hat{e}_x + \frac{2y}{x^2 + y^2} \hat{e}_y \right)$$

$$= \frac{\alpha \vec{r}}{r^2}$$



$$|\vec{w}|^2 = |\vec{\nabla} \vartheta|^2 = \frac{\alpha^2}{r^2}$$

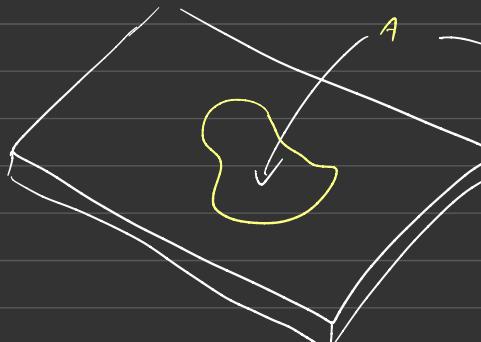
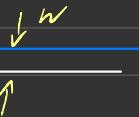
$$\underline{\epsilon} = 0 \Rightarrow \frac{\alpha^2}{2r^2} + \frac{\rho}{\rho_0} = \epsilon$$

Assume we know  $\rho_\infty$  no pressure as  $r \rightarrow \infty$

$$\epsilon = \frac{\rho_\infty}{\rho_0}$$

$$\Rightarrow \rho(r) = \rho_\infty - \frac{\sigma_0 a^2}{2r^2}$$

Consider this sheet of fluid



$$A w / \rho_0 = \text{mass}$$

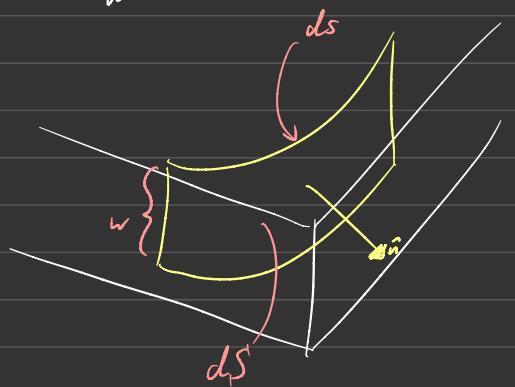
$$\rho_0 w = \frac{\text{mass}}{A} = \sigma_0$$

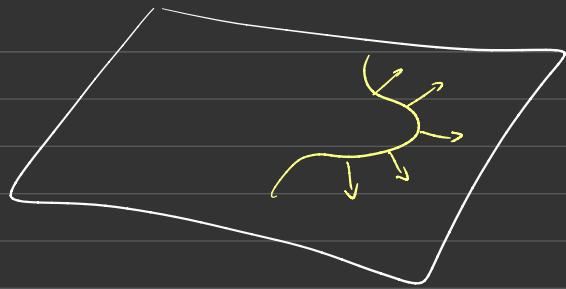
$$\rho_0 = \sigma_0 \delta(z)$$

$$\rho_0 = \frac{\sigma_0}{w}$$

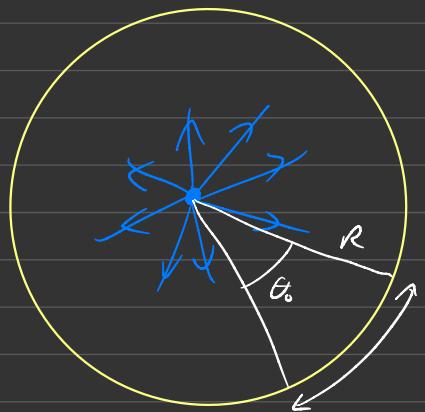
$$\rho(r) = \rho_\infty - \frac{\sigma_0 a^2}{2r^2}$$

$$\rho(r) w = \rho_\infty w + \frac{\sigma_0 a^2}{2r^2}$$





$$\vec{F} = \oint_C (\rho_w) \hat{n} ds$$



$$F = \int_0^{\theta_0} \rho_w d\theta$$

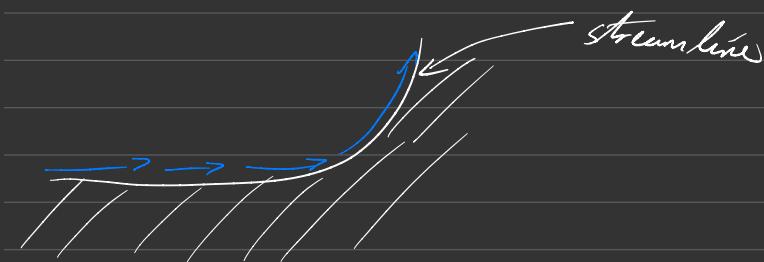
$$= \int_0^{\theta_0} \left( \rho_{\infty} w - \frac{\sigma_0 a^2}{2R^2} \right) R d\theta$$

$$= \rho_{\infty} w R \theta_0 - \frac{\sigma_0 a^2 \theta_0}{2R}$$

$$Q_c = 2\pi a$$

$$F = \text{const} - \frac{\sigma_0 C^2 \theta_0}{8\pi^2 R}$$

## Flow on Boundaries



Given a boundary  $C$ , the curve  $w(z)$  that describes the flow is one whose stream function is constant on  $C$  and  $\nabla^2 \psi = 0$

Recall

$$\vec{\nabla} \cdot \vec{u} = 0$$

$$\vec{\nabla} \times \vec{u} = 0 \Rightarrow \vec{u} = \vec{\nabla} \phi$$

$$\Rightarrow \nabla^2 \phi = 0$$

CR

$$\frac{\partial \phi}{\partial x} = \frac{\partial \psi}{\partial y} \quad \frac{\partial^2 \phi}{\partial x^2} = \frac{\partial}{\partial x} \left( \frac{\partial \psi}{\partial y} \right)$$

$$\frac{\partial \phi}{\partial y} = -\frac{\partial \psi}{\partial x} \quad \frac{\partial^2 \phi}{\partial y^2} = -\frac{\partial}{\partial y} \left( \frac{\partial \psi}{\partial x} \right)$$

$$\Rightarrow \frac{\partial^2 \mathcal{Q}}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$$

$$= \nabla^2 \mathcal{Q}$$

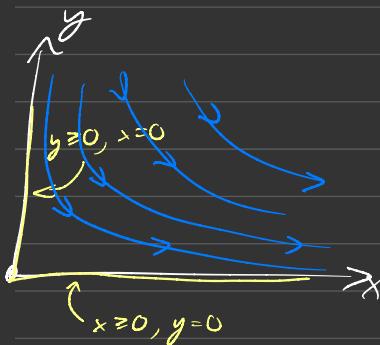
$$\frac{\partial^2 \mathcal{Q}}{\partial x \partial y} = \frac{\partial^2 \psi}{\partial y^2}$$

$$\frac{\partial^2 \mathcal{Q}}{\partial x \partial y} = -\frac{\partial^2 \psi}{\partial x^2}$$

$$\Rightarrow 0 = \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2}$$

$$= \nabla^2 \psi$$

Example



$$\psi(x, y) = Ax y$$

$$\mathcal{Q}(x, y) = \frac{1}{2} A(x^2 y^2) + B$$

$$\left. \begin{aligned} \frac{\partial \mathcal{Q}}{\partial x} &= \frac{\partial \psi}{\partial y} = Ay \\ \frac{\partial \mathcal{Q}}{\partial y} &= -\frac{\partial \psi}{\partial x} = -Ax \end{aligned} \right.$$

$$\mathcal{Q}(x, y) = \int A x dx = \frac{1}{2} A x^2 + f(y)$$

$$\frac{\partial \mathcal{Q}}{\partial y} = f'(y) = -Ay$$

$$\Rightarrow f(y) = -\frac{A}{2} y^2 + B$$

$$W(z) = \frac{1}{2}(x^2 - y^2) + B + iAxy$$

$$= \frac{A}{2}(x^2 - y^2 + 2ixy) + B$$

$$= \frac{A}{2}z^2 + B$$

$$\vec{w} = \vec{\nabla} \varphi = Ax\hat{e}_x - Ay\hat{e}_y$$

$$= |W'(z)| = Az$$

$$= ux - iy$$

$$\Rightarrow ux = Ax, uy = -Ay$$

$$Axy = C$$

$$xy = \frac{C}{A}, A > 0$$

$$\frac{1}{2}| \vec{\nabla} \varphi |^2 + \frac{\rho}{\rho_0} = \varepsilon$$

$$\frac{1}{2}A(x^2 + y^2) + \frac{\rho}{\rho_0} = \varepsilon$$

$$\Rightarrow \rho(x, y)$$

## C. Viscous Fluids

$$\frac{\partial \vec{F}}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$\rho \frac{\partial \vec{u}}{\partial t} = \rho \vec{f} + \vec{\nabla} \cdot \sigma$$

$$(\vec{\nabla} \cdot \sigma)_i = \sum_j \frac{\partial \sigma_{ij}}{\partial x_j}$$

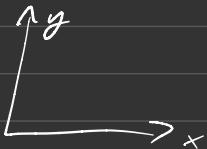
$$\sigma_{ij} = \sigma_{ji}$$

$$\text{Inviscid} \quad \sigma_{ij} = -\rho S_{ij}$$

$$\vec{\nabla} \cdot \sigma = -\vec{\nabla} \rho$$

$$\text{Viscous} \quad \sigma_{ij} = -\rho S_{ij} + \tau_{ij}$$

↑  
"deviatoric stress tensor"



$$F_r \propto \frac{\partial u_x}{\partial y} \quad \text{Newtonian Fluids}$$

$$\frac{\partial u_i}{\partial x_j} = \partial_j u_i$$

$$\tau_{ij} = \eta \left( \partial_i u_j + \partial_j u_i - \frac{2}{3} \delta_{ij} (\vec{\nabla} \cdot \vec{u}) \right) + \zeta (\delta_{ij} \vec{\nabla} \cdot \vec{u})$$

Dynamic Viscosity      Dynamic Stress  
 Bulk Stress  
 Bulk Viscosity

2 types of stresses

- Dynamic / shear

change shape but not volume

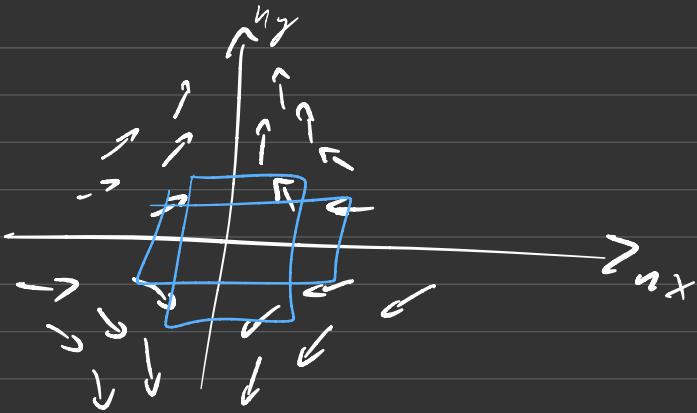
- Bulk / Tensile

Volume but not shape

$$d\vec{F} = \begin{pmatrix} \vec{\nabla} \cdot \vec{w} & 0 \\ 0 & \vec{\nabla} \cdot \vec{w} \end{pmatrix} \cdot \hat{n} dS$$

$$= (\vec{\nabla} \cdot \vec{w})$$

$$\sum_j \left\{ \partial_i u_j + \partial_j u_i - \frac{2}{3} \delta_{ij} \vec{\nabla} \cdot \vec{u} \right\} n_j dS$$



$$\sigma_{ij} = -\rho \delta_{ij} + \gamma \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \delta_{ij} (\vec{\nabla} \cdot \vec{u}) \right) + \zeta \delta_{ij} \vec{\nabla} \cdot \vec{u}$$

$$\frac{d\vec{u}}{dt} = \rho \vec{f} + \vec{\nabla} \cdot \sigma$$

$$(\vec{\nabla} \cdot \sigma)_i = \sum_j \frac{\partial \sigma_{ij}}{\partial x_j}$$

$$= \sum_j \left\{ -\delta_{ij} \frac{\partial \rho}{\partial x_j} + \gamma \frac{\partial^2 u_i}{\partial x_j^2} + \gamma \frac{\partial^2 u_j}{\partial x_j \partial x_i} \right.$$

$$\left. - \frac{2}{3} \delta_{ij} \gamma \frac{\partial}{\partial x_j} (\vec{\nabla} \cdot \vec{u}) + \zeta \delta_{ij} \frac{\partial}{\partial x_j} (\vec{\nabla} \cdot \vec{u}) \right\}$$

$$= -\frac{\partial P}{\partial x_i} + \gamma \nabla^2 \vec{u}_i + \gamma \frac{\partial}{\partial x_i} (\vec{\nabla} \cdot \vec{u})$$

$$- \frac{2}{3} \eta \frac{\partial}{\partial x_i} (\vec{\nabla} \cdot \vec{u}) + 5 \frac{\partial}{\partial x_i} (\vec{\nabla} \cdot \vec{u})$$

$$(\nabla \cdot \sigma)_i = \left[ \vec{\nabla} P + \gamma \nabla^2 \vec{u} + \left( 5 + \frac{4}{3} \right) \vec{\nabla} (\vec{\nabla} \cdot \vec{u}) \right]_i$$

$$\Rightarrow \rho \frac{\partial \vec{u}}{\partial t} = \rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right]$$

$$= \rho \vec{f} - \vec{\nabla} P + \gamma \nabla^2 \vec{u} + \left( 5 + \frac{4}{3} \right) \vec{\nabla} (\vec{\nabla} \cdot \vec{u})$$

Navier Stokes equations

B.C.  
Boundary  
Equations

along with the continuity equation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u})$$

and some equation of state

Incompressible:  $\rho \approx \rho_0 \Rightarrow \vec{\nabla} \cdot \vec{u} = 0$

$$\Rightarrow \rho \frac{\partial \vec{u}}{\partial t} = \rho_0 \vec{f} - \vec{\nabla} p + \eta \nabla^2 \vec{u}$$

Vorticity:  $\vec{\omega} = \vec{\nabla} \times \vec{u}$

$$\frac{\partial \vec{u}}{\partial t} = \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u}$$

$$= \frac{\partial \vec{u}}{\partial t} + \vec{\nabla} \left( \frac{1}{2} |\vec{u}|^2 \right) + \vec{\omega} \times \vec{u}$$

$$\vec{\nabla} \times \left( \frac{\partial \vec{u}}{\partial t} + \vec{\nabla} \left( \frac{1}{2} |\vec{u}|^2 \right) + \vec{\omega} \times \vec{u} \right) \quad f = -\vec{\nabla} \frac{\omega}{4}$$

$$= \vec{\nabla} \times \left( \vec{f} - \frac{1}{\rho_0} \vec{\nabla} p + \frac{\eta}{\rho_0} \nabla^2 \vec{u} \right)$$

$$= \frac{\partial \vec{u}}{\partial t} + \vec{\nabla} \times (\vec{\omega} \times \vec{u}) = \frac{\eta}{\rho_0} \nabla^2 \vec{u}$$

$$= (\vec{u} \cdot \vec{\nabla}) \vec{\omega} + (\vec{\nabla} \cdot \vec{u}) \vec{\omega} - (\vec{\nabla} \cdot \vec{\omega}) \vec{u} - (\vec{\omega} \cdot \vec{\nabla}) \vec{u}$$

$$\boxed{\frac{\partial \vec{u}}{\partial t} = (\vec{u} \cdot \vec{\nabla}) \vec{\omega} + \frac{\eta}{\rho_0} \nabla^2 \vec{u}}$$

2D Fluid  $\vec{w} = w(t, x, y) \hat{e}_z$

$$\frac{\partial w}{\partial t} = -\frac{\eta}{\rho_0} \nabla^2 w$$

Heat equation

$\Rightarrow$  Dissipation, the vorticity tends to equalize



## Special Solutions to the NS Equation

Consider incompressible and unidirectional flow

$$\text{so } V = V_x \mathbf{i} \quad \text{where } V_x(x, y, z, t)$$

continuity equation says

$$\nabla \cdot V = \frac{\partial V_x}{\partial x} = 0$$

$$\Rightarrow V_x = V_x(y, z, t)$$

NS for incompressible flow

$$\rho \frac{\partial V}{\partial t} = \rho F_b - \nabla P + \eta \nabla^2 V$$

The  $y$  and  $z$  components of this equations are

$$\left. \begin{aligned} \frac{\partial P}{\partial y} &= \rho F_{by} \\ \text{and } \frac{\partial P}{\partial z} &= \rho F_{bz} \end{aligned} \right\} \quad (8)$$

The  $x$  component of the same equation  
 $\rightarrow$

$$\rho \frac{\partial V_x}{\partial t} = \rho \left( \frac{\partial V_x}{\partial t} + V_x \frac{\partial V_x}{\partial x} + \cancel{V_y \frac{\partial V_x}{\partial y}}^0 + \cancel{V_z \frac{\partial V_x}{\partial z}}^0 \right)$$

$\uparrow$  continuity

$$= \rho F_{bx} - \frac{\partial P}{\partial x} + \gamma \nabla^2 V_x$$

$$\Rightarrow \rho \frac{\partial V_x}{\partial t} = \rho F_{bx} - \frac{\partial P}{\partial x} + \gamma \left( \frac{\partial^2 V_x}{\partial x^2} + \frac{\partial^2 V_x}{\partial y^2} + \frac{\partial^2 V_x}{\partial z^2} \right)$$

$\uparrow$  continuity

This simplifies further if we assume  
 steady flow we get

$$\gamma \left( \frac{\partial^2 V_x}{\partial y^2} + \frac{\partial^2 V_x}{\partial z^2} \right) = \frac{\partial P}{\partial x} - \rho F_{bx} \quad \left( \text{since } \frac{\partial V_x}{\partial t} = 0 \right)$$

We can find an expression for  $P$  by  
 differentiating wrt  $x$  and assume  $F_b$   
 is conservative

$$\gamma \frac{\partial}{\partial x} \left( \frac{\partial^2 V_x}{\partial y^2} + \frac{\partial^2 V_x}{\partial z^2} \right) = \frac{\partial^2 P}{\partial x^2} + \rho \frac{\partial^2 \psi}{\partial x^2} \quad (\text{so})$$

$\uparrow$  by continuity

Also (\*) became

$$\frac{\partial \rho}{\partial y} = -\rho \frac{\partial \psi}{\partial y} \Rightarrow \rho = -\rho \psi + C_2(x, z)$$

$$\frac{\partial \rho}{\partial z} = -\rho \frac{\partial \psi}{\partial z} \Rightarrow \rho = -\rho \psi + C_2(x, y)$$

So  $\rho = -\rho \psi + f(x)$  for some  $f(x)$ .

Plugging this into (\*\*) gives

$$\frac{\partial^2}{\partial x^2} \left( -\rho \psi + f(x) \right) + \rho \frac{\partial^2 \psi}{\partial x^2} = 0$$

$$\Rightarrow \frac{\partial^2 f}{\partial x^2} = 0$$

$$\Rightarrow f(x) = C_x + D$$

$$\therefore \rho = -\rho \psi + C_x + D$$

If we plug this into  $x$ -component of NS we get

$$2 \left( \frac{\partial^2 V_x}{\partial y^2} + \frac{\partial^2 V_x}{\partial z^2} \right) = \frac{\partial}{\partial x} \left( -\rho \psi + C_x + D \right) + \rho \frac{\partial \psi}{\partial x}$$

$$= -\rho \frac{\partial \phi}{\partial x} + C + \rho \frac{\partial \phi}{\partial x}$$

$$\text{So } \left( \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) V_x = \frac{C}{\eta} \quad (\ast \ast \ast)$$

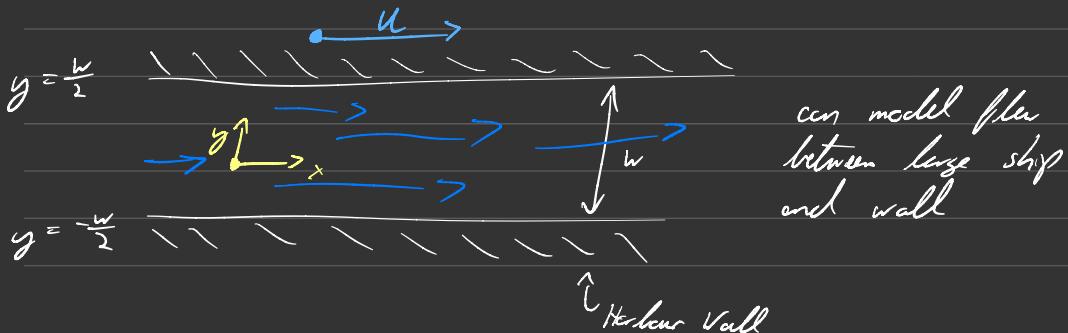
To go further need more information about the fluid eg boundary conditions.

### Non-Slip Boundary Conditions

The velocity of the fluid at an interface with a solid is the same as the velocity of the solid (the fluid sticks to the boundary and moves with it).

### Example

Steady undirectional viscous flow is an infinitely deep straight channel



We'll assume the flow is independent of  $z$ , ( $\omega_z = 0$ ) then becomes

$$\left( \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) V_x = \boxed{\frac{\partial^2 V_x}{\partial y^2} = \frac{C}{\gamma}}$$

Integrating this twice yields

$$V_x = \frac{cy^2}{2y} + \underbrace{\omega_1 y + \omega_2}_{\text{const}}$$

No slip B.C's

$$\Rightarrow V_x = 0 \text{ when } y = -\frac{w}{2}$$

$$\text{and } V_x = u, \text{ when } y = \frac{w}{2}$$

so when  $y = -\frac{w}{2}$  we have

$$\frac{C}{2y} \left( \frac{w}{2} \right)^2 - \omega_1 \frac{w}{2} + \omega_2 = 0 \quad (1)$$

$$\text{and when } y = \frac{w}{2}$$

$$\frac{C}{2y} \left( \frac{w}{2} \right)^2 + \omega_1 \frac{w}{2} + \omega_2 = u \quad (2)$$

Subtracting (1) from (2) gives

$$\omega_1 - \frac{w}{2} + \omega_2 - \frac{w}{2} = u \Rightarrow \omega_1 - \omega_2 = \frac{u}{w}$$

Subbing into (1) gives

$$\frac{C}{2y} \frac{w^2}{4} - \frac{u}{2} + \omega_2 = 0$$

$$\Rightarrow \omega_2 = \frac{u}{2} - \frac{C}{2} \frac{w^2}{8}$$

Thus  $V_x = \frac{C}{2y} \left( y^2 - \frac{w^2}{4} \right) + \frac{u}{w} \left( y + \frac{w}{2} \right)$

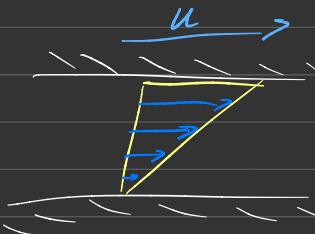
Special Cases

(1)  $C = 0, u \neq 0, \psi = 0$

Recall  $\rho = -\psi + C_x + \rho$

so  $\rho = \text{const}$

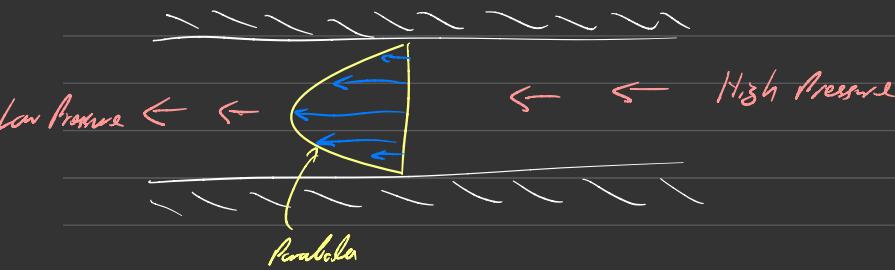
Also  $V_x = \frac{u}{w} \left( y + \frac{w}{2} \right)$



(2) If  $C \neq 0$  and  $U = 0$

then  $V_x = \frac{C}{2y} \left( y^2 - \frac{U^2}{4} \right)$   $\begin{cases} V_x = 0 \text{ when } \\ y = \pm \frac{U}{2} \end{cases}$

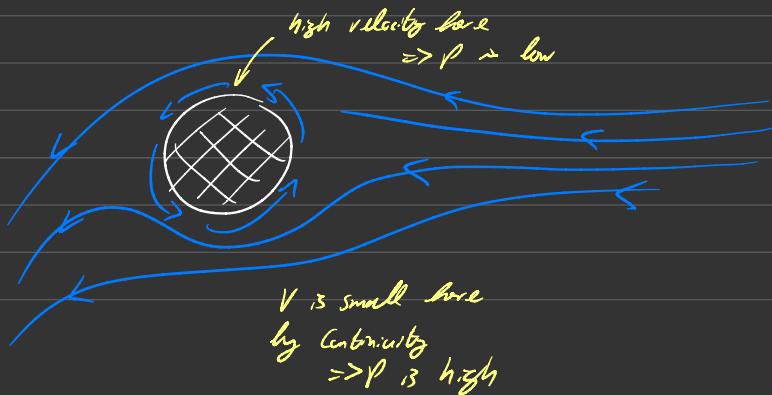
If  $C > 0$ , this looks like



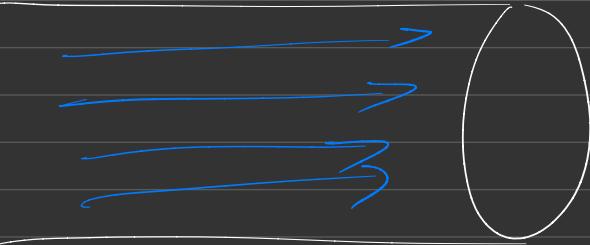
### Remark 4

The non-slip BC and Bernoulli's Principle produces the magnus effect

A spinning object moving through a fluid feels a force perpendicular to the velocity and axis of rotation



# Rosenthal Flows



- viscous (Newtonian)
- incompressible (liquid)
- steady (no time-dep.)
- ignoring body forces

$$\frac{\partial \vec{p}}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$\rho_0 \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right] = -\vec{\nabla} p + \eta \vec{\nabla}^2 \vec{u} + \left( f + \frac{\eta}{3} \right) \vec{\nabla} (\vec{u} \cdot \vec{u})$$

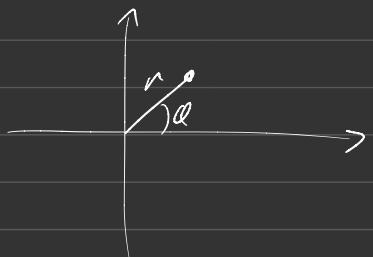
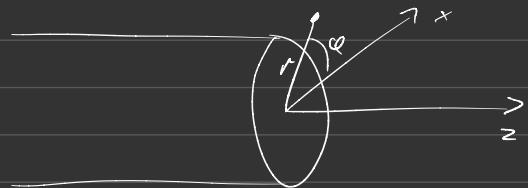
$$\rho = \rho_0, \quad \vec{\nabla} \cdot \vec{u} = 0$$

$$\vec{u}(r, \theta, z) = u(r, \theta, z) \hat{e}_z$$

$$\vec{\nabla} \cdot \vec{u} = \frac{1}{r} \frac{\partial}{\partial r} (r u_r) + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z}$$

$$\frac{\partial u}{\partial z} = 0$$

$$(u \cdot \vec{\nabla}) \vec{u} = u \frac{\partial}{\partial z} (u \hat{e}_z) = \vec{0}$$



$$-\vec{\nabla} p + \gamma \vec{\nabla}^2 \vec{u} = \vec{0}$$

$$r : -\frac{\partial p}{\partial r} = 0$$

$$\theta : -\frac{1}{r} \frac{\partial p}{\partial \theta} = 0$$

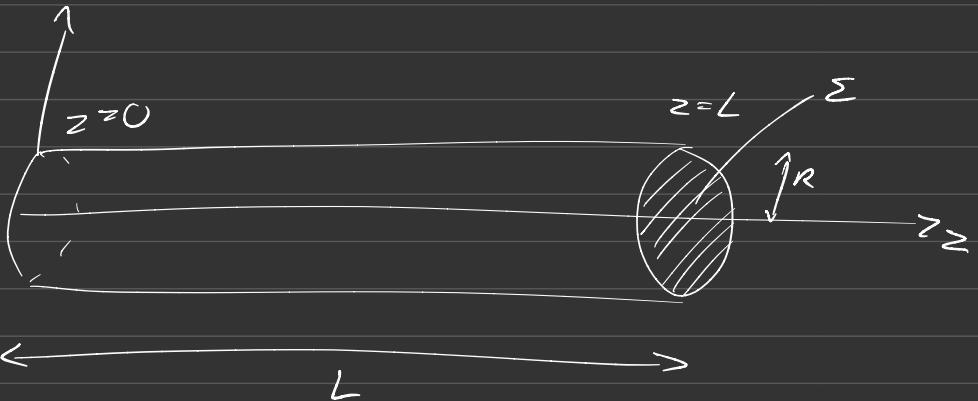
$$z : -\frac{\partial p}{\partial z} + \gamma \vec{\nabla}^2 \vec{u} = 0$$

$$\nabla^2 u = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{\partial^2 u}{\partial z^2}$$

$$\frac{dp}{dz} = 2 \left\{ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} \right\}$$

$z$  alone

$$\frac{d^2 p}{dz^2} = 0 \Rightarrow p(z) = A z + B$$



$$P_0 = P(0) \\ = B$$

$$P(L) = P_0 + \Delta P \\ = AL + B$$

$$\beta = P_0 \quad A = \frac{\Delta P}{L}$$

$$P(z) = \frac{\Delta P}{L} z + P_0$$

$$\frac{dP}{dz} = \frac{\Delta P}{L}$$

$$2 \left\{ \frac{1}{r} \frac{d}{dr} \left( r \frac{du}{dr} \right) + \frac{1}{r^2} \frac{d^2 u}{dr^2} \right\} = \frac{\Delta P}{L}$$

• Cylindrical symmetry



$$2 \frac{1}{r} \frac{d}{dr} \left( r \frac{du}{dr} \right) = \frac{\Delta P}{L}$$

$$\frac{d}{dr} \left( r \frac{du}{dr} \right) = \frac{\Delta P}{2L} r$$

$$\frac{r du}{dr} = \frac{\Delta P}{2\gamma L} r^2 + C$$

$$\frac{du}{dr} = \frac{\Delta P}{2\gamma L} r^2 + \frac{C}{r}$$

$$u = \frac{\Delta P}{4\gamma L} r^2 + C \ln r + E$$

•  $u$  finite in  $r=0$   $C=0$

$$u = \frac{\Delta P}{4\eta L} r^2 + E$$

- no slip:  $\vec{u}$  at rigid boundaries must be the same as the boundary itself

$$\vec{u}|_{r=R} = \vec{0}$$

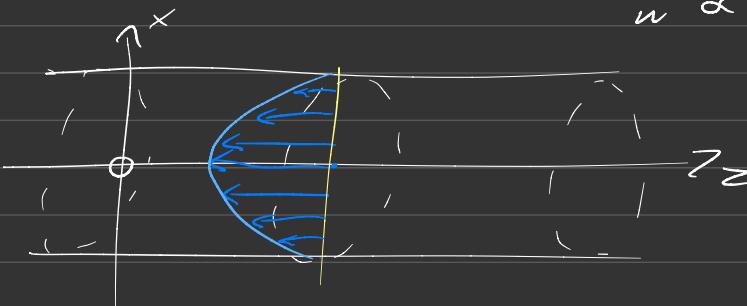
$$u(R) = 0 = \frac{\Delta P}{4\eta L} R^2 + E$$

$$\Rightarrow E = -\frac{\Delta P}{4\eta L} R^2$$

$$\boxed{\vec{u} = \frac{\Delta P}{4\eta L} (r^2 - R^2) \hat{e}_z}$$

$$\Delta P > 0$$

$$\vec{u} \propto -\hat{e}_z$$



$\Rightarrow$  Fluid flow from high  $P$  to low  $P$

$$\Delta P < 0 \Rightarrow \vec{u} = \frac{|\Delta P|}{4 \rho L} (R^2 - r^2) \hat{e}_r$$

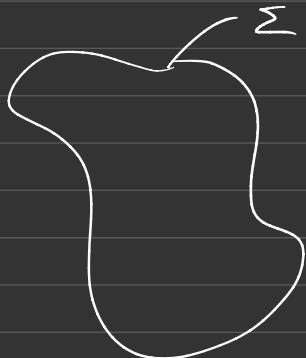
$\rho \vec{u}$  = "mass current density"

(eg  $\vec{j}$  "electro current density")



$$dI = \rho \vec{u} \cdot d\vec{S}$$

$$(dI = \vec{j} \cdot d\vec{S})$$



$$I_\Sigma = \int_{\Sigma} \rho \vec{u} \cdot d\vec{S}$$



$$\dot{m}_{\text{rate}} = \int_{Q=0}^{\Omega=2\pi} \int_{r=0}^{r=R} \frac{\Delta P_{\text{bar}}}{4\gamma L} (r^2 - R^2) \hat{e}_z \cdot r dr d\theta \hat{e}_z$$

$$= \frac{\Delta P_{\text{bar}} (2\pi)}{4\gamma L} \int_0^R (r^3 - r R^2) dr$$

$$= \frac{\pi \Delta P_{\text{bar}}}{2\pi L} \left( \frac{1}{4} r^4 - \frac{1}{2} R r^2 \right) \Big|_0^R$$

$$\dot{m} = - \frac{\pi \Delta P R^4}{8\gamma L}$$

$$Q = \frac{\dot{m}}{\rho_0} = - \frac{\pi \Delta P R^4}{8\gamma L}$$

- inversely proportional to  $L$
- inversely proportional to  $\eta$
- proportional to  $| \Delta P |$
- proportional to  $r^4$

Putting in some numbers

$$L = 1 \text{ m}$$

$$R = 2 \text{ cm} = 0.02 \text{ m}$$

$$\eta = 10^{-3} \text{ Pa}\cdot\text{s}$$

$$| \Delta P | = 0.01 \text{ atm} = 10^3 \text{ Pa}$$

$$= \overrightarrow{D}P + \downarrow D^2 \vec{u}$$

$$\frac{\text{pressure}}{\text{length}} = [z] \frac{\frac{\text{length}}{\text{line}}}{\frac{\text{length}}{\text{length around}}}$$

$$[z] = \text{pressure} \cdot \text{radius}$$

$$Q = \frac{\pi (10^3 \text{ Pa}) (0.02 \text{ m})^4}{8 (10^{-3} \text{ Pa}\cdot\text{s}) (1 \text{ m})}$$

$$= 636 \cdot 10^{-2} \text{ m}^2 \cdot \text{s}^{-1}$$

$$= 63.6 \text{ l.s}^{-1} \quad \text{that's a lot of fluid you clayum}$$

$$Q = \frac{1 \text{ l}}{30 \text{ s}} = 3.33 \times 10^{-5} \text{ m}^2 \cdot \text{s}^{-1}$$

$$| \Delta P | = \frac{8 \eta L Q}{\pi R^4} = 0.53 \text{ Pa}$$

$$|\Delta P| = P_A = 1.03 \times 10^5 \text{ Pa} \quad \text{realistic for man's pressure}$$

$$L = 50 \text{ km} = 5 \times 10^4 \text{ m}$$

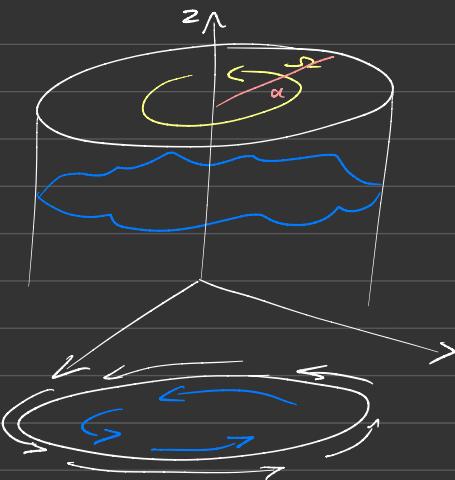
$$Q = 1000 \text{ l s}^{-1} = 1 \text{ m}^3 \cdot \text{s}^{-1}$$

$$R = \left( \frac{8g L \alpha}{\pi |\Delta P|} \right)^{\frac{1}{4}} \approx 0.19 \text{ m} = 19 \text{ cm}$$

## (b) Systems "Unidirectional" in Cylindrical coordinates

Example

cylindrical vat  
of fluid  $\rightarrow$



- steady flow (no time dependence)
- incompressible ( $\rho_0$ )
- gravitational force ( $\vec{f} = -g\hat{e}_z$ )
- vat spins with constant angular velocity  $\omega$

$$\rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right] = \rho \vec{f} - \vec{\nabla} p + \rho \vec{\nabla}^2 \vec{u} + (\frac{2}{3} \rho \omega^2) \vec{\nabla} (\vec{\nabla} \cdot \vec{u})$$

$$\frac{\partial \vec{u}}{\partial t} = \vec{0}, \quad \rho = \rho_0, \quad \vec{\nabla} \cdot \vec{u} = 0$$

$$\vec{f} = -g\hat{e}_z$$

$$\rho_0 (\vec{u} \cdot \vec{\nabla}) \vec{u} = \rho_0 g \hat{e}_z - \vec{\nabla} P + \gamma \vec{\nabla}^2 \vec{u}$$

$$\vec{u} = u(r, \theta, z) \hat{e}_z = u(r, z) \hat{e}_z$$

$$\left\{ \begin{array}{l} \vec{\nabla} \cdot \vec{u} = \frac{1}{r} \frac{\partial}{\partial r} (r u_r) + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z} = \frac{1}{r} \frac{\partial u}{\partial \theta} = 0 \\ (\vec{u} \cdot \vec{\nabla}) \vec{u} = \frac{u}{r} \frac{\partial}{\partial \theta} (u \hat{e}_\theta) = \frac{u^2}{r} \frac{\partial \hat{e}_\theta}{\partial \theta} \quad \hat{e}_\theta = \sin \theta \hat{e}_x + \cos \theta \hat{e}_y \\ \qquad \qquad \qquad \frac{\partial \hat{e}_\theta}{\partial \theta} = -\sin \theta \hat{e}_x - \cos \theta \hat{e}_y \\ \qquad \qquad \qquad \frac{\partial \hat{e}_\theta}{\partial \theta} = \hat{e}_r \\ \qquad \qquad \qquad \hat{e}_\theta = -\hat{e}_\theta \\ = -\frac{u^2}{r} \hat{e}_r \end{array} \right.$$

$$\left\{ \begin{array}{l} \vec{\nabla}^2 \vec{u} = \frac{1}{r} \frac{\partial}{\partial r} \left[ r \frac{\partial}{\partial r} (u \hat{e}_z) \right] + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} (u \hat{e}_\theta) + \frac{\partial^2}{\partial z^2} (u \hat{e}_\theta) \\ = \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) + \frac{\partial^2 u}{\partial z^2} \right] \hat{e}_\theta + \frac{u}{r^2} \frac{\partial^2 \hat{e}_\theta}{\partial \theta^2} \\ = \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) + \frac{u}{r^2} + \frac{\partial^2 u}{\partial z^2} \right] \hat{e}_\theta \end{array} \right.$$

✓

$$= -\frac{\rho_0 \vec{u}}{r} \hat{e}_r$$

$$(\vec{u} \cdot \vec{\nabla}) \vec{u} = \frac{1}{2} \vec{\nabla} / |\vec{u}|^2 + (\vec{\nabla} \times \vec{u}) \times \vec{u}$$

$$\nabla^2 \vec{u} = \vec{\nabla} (\vec{\nabla} \cdot \vec{u}) - \vec{\nabla} \times (\vec{\nabla} \times \vec{u})$$

$$-\frac{\rho_0 u^2}{r} \hat{e}_r = -\rho_0 g \hat{e}_z$$

$$-\frac{\partial P}{\partial r} \hat{e}_r - \frac{1}{r} \frac{\partial P}{\partial r} \hat{e}_\theta$$

$$-\frac{\partial P}{\partial z} \hat{e}_z$$

$$r : \rho \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) - \frac{u}{r^2} + \frac{\partial^2 u}{\partial z^2} \right] \hat{e}_\theta$$

$$r : -\frac{\rho_0 u^2}{r} = -\frac{\partial P}{\partial r}$$

$$\theta : 0 = \frac{1}{r} \frac{\partial P}{\partial \theta} + 2 \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) - \frac{u}{r^2} + \frac{\partial^2 u}{\partial z^2} \right]$$

$$z : 0 = \rho_0 g - \frac{\partial P}{\partial z}$$

$$\frac{\partial}{\partial \theta} \left( \frac{1}{r} \frac{\partial P}{\partial \theta} \right) = \frac{\partial}{\partial \theta} \left( 2 \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) - \frac{u}{r^2} + \frac{\partial^2 u}{\partial z^2} \right] \right)$$

$$\Rightarrow \frac{1}{r} \frac{\partial^2 P}{\partial \theta^2} = 0$$

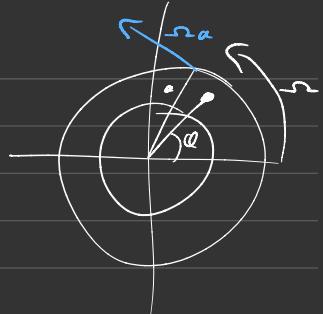
$$\Rightarrow \frac{\partial^2 P}{\partial \varphi^2} = 0$$

$$\Rightarrow P = A(r, z)\varphi + B(r, z)$$

$$P(r, \varphi, z) = P(r, \varphi + 2\pi, z)$$

$$\Rightarrow A = 0$$

$$\Rightarrow P = P(r, z)$$



$$\frac{\partial P}{\partial z} = -\rho_0 g \Rightarrow P(r, z) = -\rho_0 g z + f(r)$$

$$\frac{\partial P}{\partial r} = \frac{\rho_0 u^2}{\rho} \Rightarrow f'(r) = \frac{\rho_0 u^2}{r} \Rightarrow u(r)$$

$$\frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) - \frac{u}{r^2} \frac{\partial^2 u}{\partial z^2} = 0$$

$$\Rightarrow \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) - \frac{u}{r^2} = 0$$

$$\Rightarrow \frac{d^2 u}{dr^2} + \frac{1}{r} \frac{du}{dr} - \frac{u}{r^2} = 0$$

$$r^2 \frac{du}{dr^2} + r du - u = 0$$

$$r^{\alpha}$$

$$\alpha(\alpha-1)r^{\alpha} + \alpha r^{\alpha} - r^{\alpha} = (\alpha^2 - 1)r^{\alpha} = 0$$

$$\Rightarrow \alpha = \pm 1$$

$$u(r) = c_1 r + \frac{c_2}{r}$$

$c_2 = 0$  if  $u(0)$  no defined

$$\vec{u} = c_1 r \hat{e}_\theta$$

$$\left. \vec{u} \right|_{\text{wall}} = \vec{u} \Big|_{r=a} = c_1 a \hat{e}_\theta = \sigma_0 a \hat{e}_\theta$$

$$\Rightarrow c_1 = \sigma_0$$

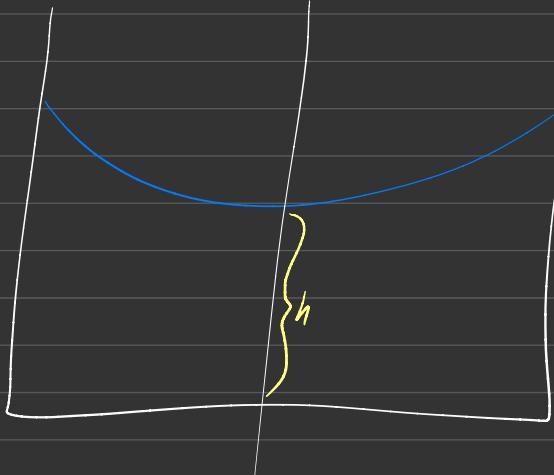
$$\boxed{\vec{u}(r, \theta, z) = \sigma_0 r \hat{e}_\theta}$$

$$f(r) = \cancel{\sigma_0} \frac{\sigma_0 r^2}{r}$$

$$= \rho_0 \sigma_0^2 r^2$$

$$f(r) = \frac{1}{2} \rho_0 \sigma_0^2 r^2 + C$$

$$\rho(r, z) = \frac{1}{2} \rho_0 r^2 n^2 - \rho_0 g z + C$$



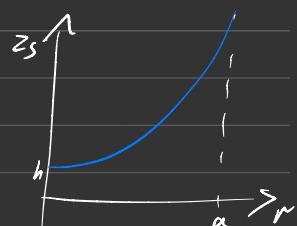
$$\rho(0, h) = \rho_A \Rightarrow C = \rho_0 gh + \rho_A$$

$\boxed{\rho(r, z) = \frac{1}{2} \rho_0 r^2 n^2 + \rho_0 g(h-z) + \rho_A}$

Let's assume that  $\rho = \rho_A$  everywhere on the surface of the fluid

$$\rho_A = \frac{1}{2} \rho_0 r^2 n^2 + \rho_0 g(h - z_s) + \rho_A$$

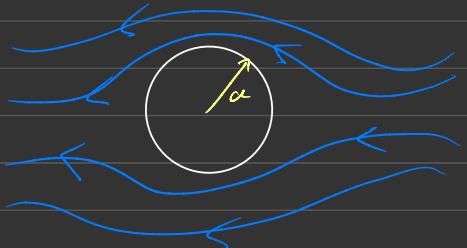
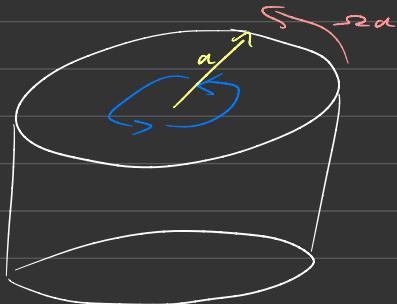
$$z_s(r) = \frac{r^2 n^2}{2g} + h$$



## (c) Reynolds Number

Incompressible, no body force

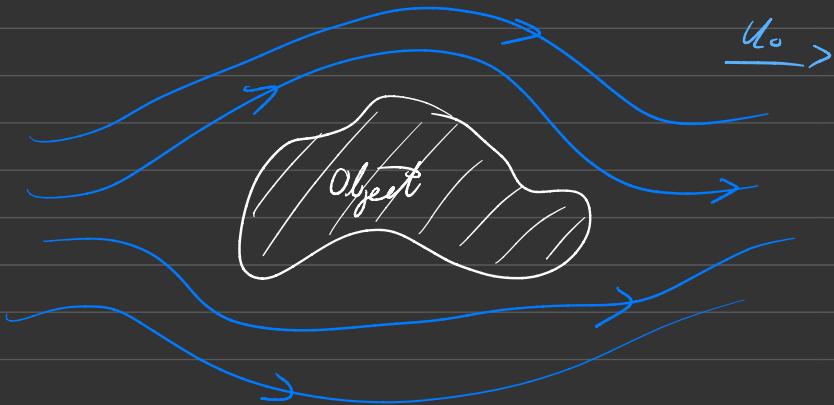
$$\rho_0 \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right] = -\vec{\nabla} p + \eta \nabla^2 \vec{u}$$



$$\vec{r}, L \Rightarrow \vec{s} = \frac{\vec{r}}{L}$$

### (c) Reynolds Number

Many realistic fluid problems have characteristic scales, e.g. lengths, speeds, densities etc.



We can use these to our advantage

Incompressible, no body force

$$\rho_0 \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right] = -\vec{\nabla} P + \gamma \vec{D}^2 \vec{u}$$

$$[\vec{u}] = \frac{\text{length}}{\text{time}} \Rightarrow \vec{u} = U_0 \vec{u}'$$

$$[\vec{r}] = \text{length} \quad \vec{r} = L_0 \vec{r}'$$

$$[t] = \text{time} \quad t = \frac{L_0}{U_0} t'$$

$$[\rho] = \frac{\text{force}}{\text{length}^2} = \frac{\frac{\text{mass length}}{\text{time}^2}}{\text{length}^2}$$

$$= \frac{\text{mass}}{\text{time}^2 \cdot \text{length}}$$

$$= \frac{\text{mass}}{\text{length}^3} \left( \frac{\text{length}}{\text{time}} \right)^2$$

$$\rho = \rho_0 U_0^2 \rho'$$

$$\rho_0 \frac{U_0^2}{L_0} \frac{\partial \vec{u}'}{\partial t'} + \rho_0 \frac{U_0^2}{L_0} (\vec{u}' \cdot \vec{\nabla}') \vec{u}'$$

$$= \frac{\rho_0 U_0}{L_0} \vec{\nabla}' \rho' + \frac{\rho_0}{L_0^2} U_0^2 \nabla'^2 \vec{u}'$$

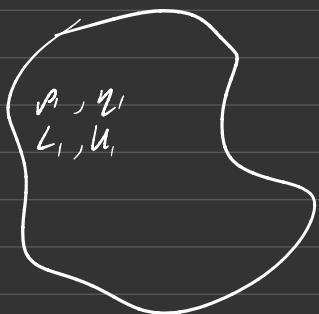
$$\frac{\partial \vec{u}'}{\partial t'} + (\vec{u}' \cdot \vec{\nabla}') \vec{u}' = -\vec{\nabla}' \rho' + \frac{\rho}{\rho_0 U_0 L_0} \nabla'^2 \vec{u}'$$

$$= -\vec{\nabla}' \rho' + \frac{1}{Re} \nabla'^2 \vec{u}'$$

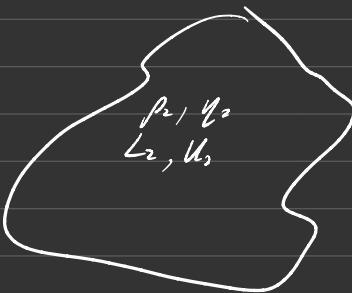
$$\left[ \frac{\rho_0 U_0 L_0}{\gamma} \right] = \frac{\text{mass}}{\text{length}^3} \frac{\text{length}}{\text{time}} \frac{\text{length}}{\frac{\text{mass}}{\text{time} \cdot \text{length}}}$$

$$\frac{\rho_0 U_0 L_0}{\gamma} = \text{Reynolds number} = Re$$

Systems 1



Systems 2



$$\frac{\partial \vec{w}'}{\partial t} + (\vec{w}' \cdot \vec{\nabla}') \vec{w}' = -\vec{\nabla}' P + \frac{1}{Re_1} \vec{\nabla}^2 w'^2$$

$$\frac{\partial \vec{w}'}{\partial t} + (\vec{w}' \cdot \vec{\nabla}') \vec{w}' = -\vec{\nabla}' P + \frac{1}{Re_2} \vec{\nabla}^2 w'^2$$

$$Re_1 = Re_2$$

$$\vec{w}', P'$$

$$\vec{w}_1 = U_1 \vec{w}', \quad P_1 = \rho_1 U_1^3 P'$$

$$\vec{w}_2 = U_2 \vec{w}', \quad P_2 = \rho_2 U_2^3 P'$$

## Example

$\rho_1, \eta_1$

38



$$Re_1 = Re_2$$

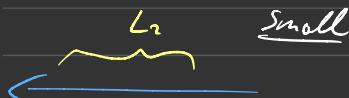
$$L_1 = 10\text{ m long}$$

$$U_1 = 360 \text{ km h}^{-1} = 100 \text{ m s}^{-1}$$

$$\rho_1 = 1.2 \text{ kg m}^{-3}$$

$$\eta_1 = 10^{-5} \text{ Pa s}$$

$$\frac{\rho_1 U_1 L_1}{\eta_1} = 1.2 \times 10^8 = Re$$



$$\frac{\rho_2 U_2 L_2}{\eta_2} = 1.2 \times 10^8$$
$$= 100 \text{ m}^2 \cdot \text{s}^{-1} \frac{\rho_2}{\eta_2}$$

$$\rho_2, \eta_2$$

$$L_2 = 2\text{ m}$$

$$U_2 = 50 \text{ m s}^{-1}$$

$$\Rightarrow \frac{\rho_2}{\eta_2} = 1.2 \times 10^6 \text{ s} \cdot \text{m}^{-2}$$

Incompressible vorticity equation

$$\frac{\partial \vec{w}}{\partial t} = \frac{\partial \vec{w}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{w} = (\vec{w} \cdot \vec{\nabla}) \vec{w} + \frac{\gamma}{\rho_0} \vec{\nabla}^2 \vec{w}$$

$$\vec{w} = \vec{\nabla} \times \vec{u}$$

$$\vec{w} = \frac{U_0}{L_0} \vec{w}'$$

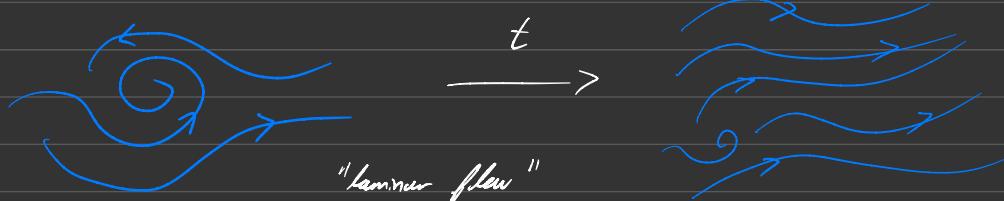
$$\left[ \frac{U_0}{L_0} \left( \frac{\partial \vec{w}'}{\partial t'} + (\vec{u}' \cdot \vec{\nabla}') \vec{w}' \right) \right] = \frac{U_0}{L_0} (\vec{w}' \cdot \vec{\nabla}') \vec{u}'$$

$$+ \frac{\gamma U_0}{\rho_0 L_0^3} \vec{\nabla}'^2 \vec{w}'$$

$$\frac{\partial \vec{w}'}{\partial t'} = (\vec{w}' \cdot \vec{\nabla}') \vec{u}' + \frac{1}{Re} \vec{\nabla}'^2 \vec{w}'$$

$$Re \ll 1 \quad (\gamma \gg \rho_0 U_0 L_0)$$

$$\frac{\partial \vec{w}'}{\partial t'} \approx \frac{1}{Re} \vec{\nabla}'^2 \vec{w}'$$



$$\underline{Re \gg L} \quad (\rho_0 U_0 L_0 \gg \gamma)$$

$$\frac{\partial \vec{w}'}{\partial t'} \times (\vec{w}' \cdot \vec{\nabla}') \vec{u}'$$

$$\frac{\partial w'_i}{\partial t'} \approx \sum_j w'_j \frac{\partial}{\partial x'_j} u'_i$$

$$M'_{ij} = \frac{\partial u'_i}{\partial x'_j}$$

$$= \sum_j \left( \frac{\partial u'_i}{\partial x'_j} \right) w'_j$$

$$= (M \cdot \vec{w}'),_i$$



$$\underline{Re \approx 20}$$

$\leftarrow$   $\rightarrow$   
 laminar                  turbulent flow

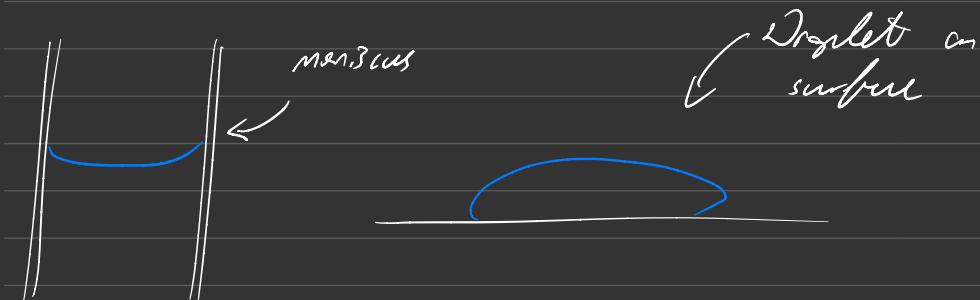
inviscid

viscous

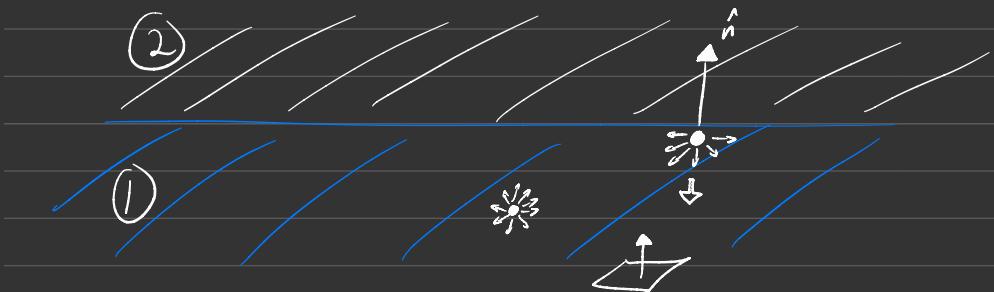


solid boundaries

(d) Free Surface, fluid-fluid boundaries

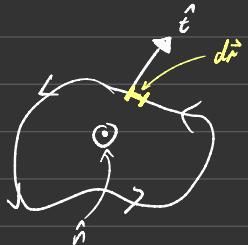


stationary fluid



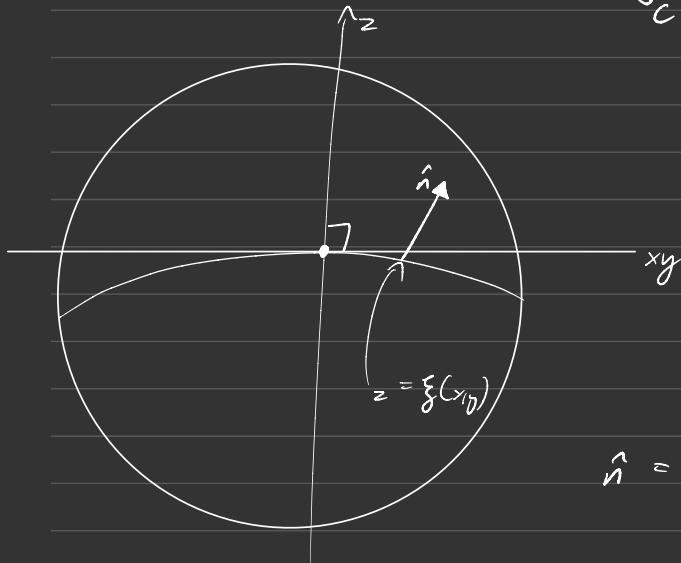


$$-\rho d\vec{S}$$



$$\begin{aligned} d\vec{F} &= -\gamma |d\vec{r}| \hat{t} = -\gamma \hat{n} \times d\vec{r} \\ &\quad \text{surfaces} \\ &= \gamma d\vec{r} \times \hat{n} \end{aligned}$$

$$\vec{F} = \oint_C \gamma d\vec{r} \times \hat{n}$$



$$\hat{n} = \frac{\vec{\nabla} f}{|\vec{\nabla} f|}$$

$$f(x_0, y_0) = \xi(x_0, y_0) - z$$

$$\vec{\nabla} f = \frac{\partial \xi}{\partial x} \hat{e}_x + \frac{\partial \xi}{\partial y} \hat{e}_y - \hat{e}_z$$

$\vec{\nabla} f \perp \text{surface}$

$$|\vec{\nabla} f| = \sqrt{\left(\frac{\partial \xi}{\partial x}\right)^2 + \left(\frac{\partial \xi}{\partial y}\right)^2 + 1}$$

$$\hat{n} = \frac{\frac{\partial \xi}{\partial x} \hat{e}_x + \frac{\partial \xi}{\partial y} \hat{e}_y - \hat{e}_z}{\sqrt{\left(\frac{\partial \xi}{\partial x}\right)^2 + \left(\frac{\partial \xi}{\partial y}\right)^2 + 1}}$$

$$\hat{x} \frac{\partial \xi}{\partial x} \hat{e}_x + \frac{\partial \xi}{\partial y} \hat{e}_y - \hat{e}_z$$

$$d\vec{r} = dx \hat{e}_x + dy \hat{e}_y + dz \hat{e}_z$$

$$= dx \hat{e}_x + dy \hat{e}_y + \left( \frac{\partial \xi}{\partial x} dx + \frac{\partial \xi}{\partial y} dy \right) \hat{e}_z$$

$$d\vec{r} \times \hat{n} \approx \begin{vmatrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ dx & dy & \frac{\partial \xi}{\partial x} dx + \frac{\partial \xi}{\partial y} dy \\ \frac{\partial \xi}{\partial x} & \frac{\partial \xi}{\partial y} & -1 \end{vmatrix}$$

$$\approx -dy \hat{e}_x + dx \hat{e}_y + \left( \frac{\partial \xi}{\partial y} dx - \frac{\partial \xi}{\partial x} dy \right) \hat{e}_z$$

$$\vec{F} \approx \hat{e}_x \oint_c (-\gamma dy) = (-\gamma \hat{e}_y d\vec{r})$$

$$+ \hat{e}_y \oint_c (\gamma dx) = (\gamma \hat{e}_x \cdot d\vec{r})$$

$$\oint_c \vec{A} \cdot d\vec{r} = \int_S (\vec{V} \times \vec{A}) dS$$

$$+ \hat{e}_z \underbrace{\oint_c \gamma \left( \frac{\partial \xi}{\partial y} dx - \frac{\partial \xi}{\partial x} dy \right)}_{\gamma \left( \frac{\partial \xi}{\partial y} \hat{e}_x - \frac{\partial \xi}{\partial x} \hat{e}_y \right)} \cdot d\vec{r}$$

$$\gamma \left( \frac{\partial \xi}{\partial y} \hat{e}_x - \frac{\partial \xi}{\partial x} \hat{e}_y \right) \cdot d\vec{r}$$

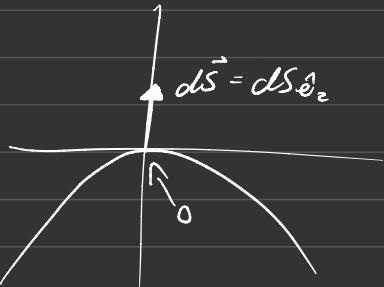
$$\vec{F} \approx \hat{e}_z \gamma \int_{\Sigma} \vec{\nabla} \times \left( \frac{\partial \xi}{\partial y} \hat{e}_x - \frac{\partial \xi}{\partial x} \hat{e}_y \right) \cdot d\vec{s}$$



$$\vec{\nabla} \times (\ ) = \hat{e}_z \left( -\frac{\partial^2 \xi}{\partial x^2} - \frac{\partial^2 \xi}{\partial y^2} \right) = -\hat{e}_z \nabla^2 \xi$$

$$\vec{F} \approx -\hat{e}_z \gamma \int \nabla^2 \xi \hat{e}_z \cdot d\vec{s}$$

$$= \gamma \nabla^2 \xi |_0 dS$$



$$d\vec{F} = -(\nabla^2 \xi) d\vec{s}$$

$$d\vec{F}_2 = -P_2 d\vec{s}$$

2



$$d\vec{F}_1 = -P_1 d\vec{s}$$

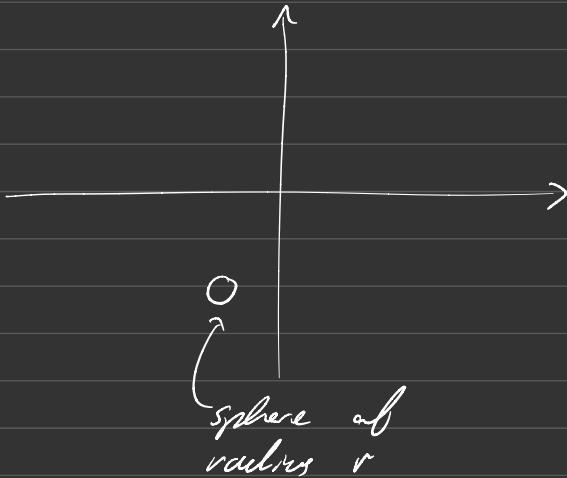
$$-\rho_1 d\vec{S} + \rho_2 d\vec{S} - (\gamma \nabla^2 \xi) d\vec{S} = 0$$

$$\boxed{\rho_2 - \rho_1 = \gamma \nabla^2 \xi}$$

Young - Laplace Equations

Example

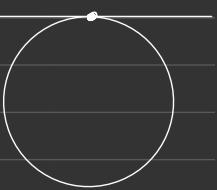
Bubble rising in liquid



$$P_{\text{water}} = P_A - \rho g z$$

$$\rho_{\text{bubble}} V_{\text{bubble}} = N k_B T \Rightarrow \rho_{\text{bubble}} = \frac{3 N k_B T}{4 \pi r^3}$$

$$\xi(x, y) = \sqrt{R^2 - x^2 - y^2} - R$$



$$\frac{\partial \xi}{\partial x} = \frac{-x}{\sqrt{R^2 - x^2 - y^2}}$$

$$\frac{\partial^2 \xi}{\partial x^2} = \frac{-1}{\sqrt{R^2 - x^2 - y^2}} - \frac{x^2}{(R^2 - x^2 - y^2)^{\frac{3}{2}}}$$

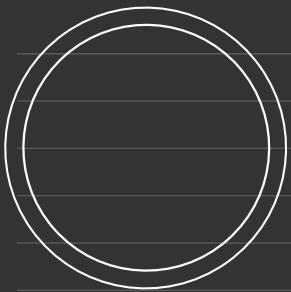
$$\nabla^2 \xi = \frac{-2}{\sqrt{R^2 - x^2 - y^2}} - \frac{x^2 + y^2}{(R^2 - x^2 - y^2)^{\frac{3}{2}}} \Big|_{x=y=0}$$

$$= -\frac{2}{R}$$

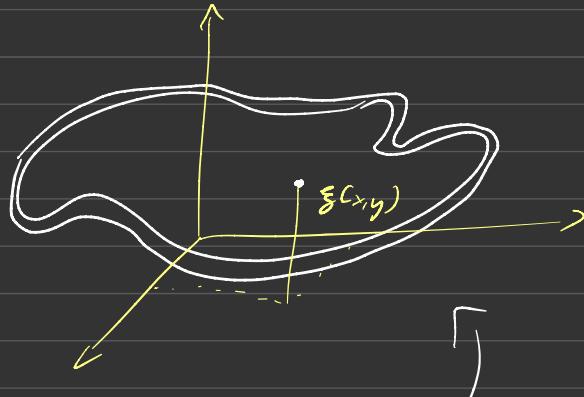
$$\rho_A - \rho_0 g^2 = -\frac{3Nk_B T}{4\pi R^3} = -\frac{2}{R}$$

$$(\rho_A - \rho_0 g^2) R^3 - 2gR^2 - \frac{3Nk_B T}{4\pi} = 0$$

$$\Rightarrow R(z)$$



$$\rho_1 = \rho_2 \Rightarrow \nabla^2 \xi = 0$$



"Minimal Surface"

$$-\rho_i d\vec{s} \rightarrow \sigma_i \cdot d\vec{s}$$

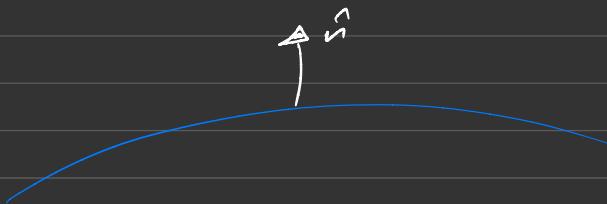


$$-\rho_i d\vec{s} \rightarrow \sigma_i \cdot d\vec{s}$$

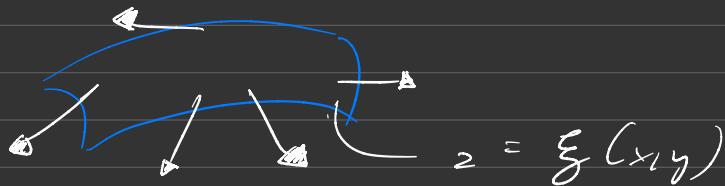
$$-\sigma_i \cdot d\vec{s} + \sigma_i \cdot d\vec{s} = \cancel{\int \nabla^i \xi d\vec{s}}$$

$$d\vec{s} = \hat{n} ds$$

$$-\sigma_i \cdot \hat{n} + \sigma_i \cdot \hat{n} = \cancel{\int \nabla^i \xi \hat{n}}$$

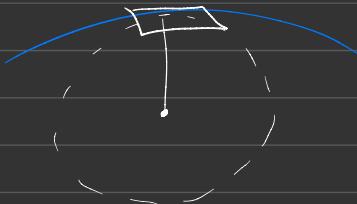


## Surface Tension

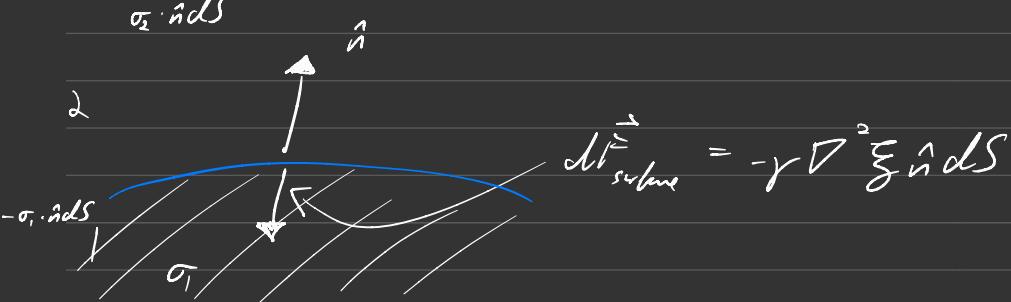


Net force :  $d\vec{F}_{\text{surface}} \approx -\gamma \nabla^2 \xi d\vec{S}$

Interpretation :  $\nabla^2 \xi \approx \frac{1}{\text{radius of curvature}} = \frac{1}{R}$



$$\sigma_i \cdot \hat{n} dS$$

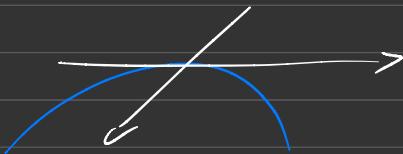


$$\nabla \cdot \sigma$$

$$\sigma_2 \cdot \hat{n} dS - \sigma_1 \cdot \hat{n} dS - \gamma \nabla^2 \xi \cdot \hat{n} dS = 0$$

$\perp$

$(\sigma_2 - \sigma_1) \cdot \hat{n}$ : parallel component is continuous



$(\sigma_2 - \sigma_1) \cdot \hat{n}$ : perpendicular component changes by  $\gamma \nabla^2 \xi$

$\gamma : H_2O - air \text{ at } 25^\circ C$

$$\approx 7.2 \cdot 10^{-2} \text{ N.m}^{-2}$$

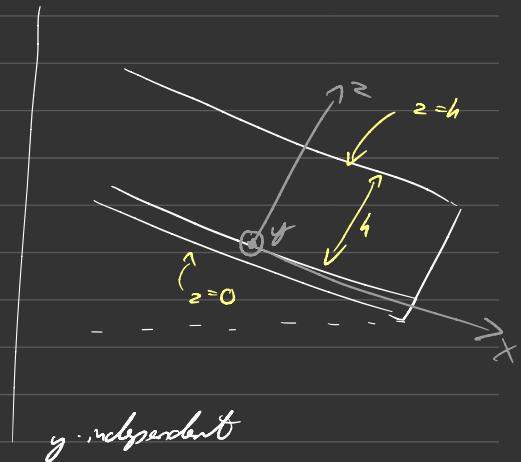
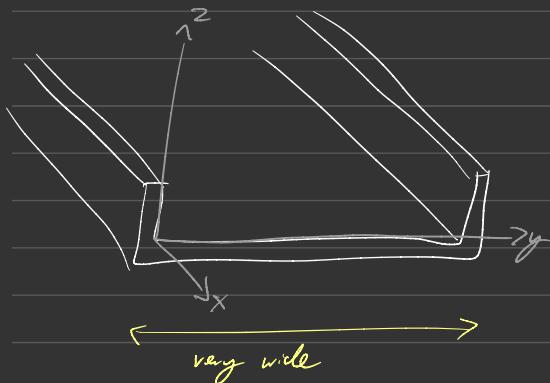
$$\gamma \nabla^2 \xi \approx 10^5 \text{ Pa}$$

$$\Rightarrow \nabla^2 \xi \approx 10^6 \text{ m}^{-1}$$

Practically speaking

$$\sigma_1 \cdot \hat{n} \approx \sigma_2 \cdot \hat{n}$$

## Aqueduct



$g$  independent

$$\vec{u} = u \hat{e}_x$$

$$\nabla \cdot \vec{u} = 0 = \frac{\partial u}{\partial x}$$

$$\vec{f} = g \sin \alpha \hat{e}_x - g \cos \alpha \hat{e}_y$$



Steady flow

$$\vec{u} = u(z) \hat{e}_x$$

$$\frac{D\vec{u}}{Dt} = (\vec{u} \cdot \vec{\nabla}) \vec{u} = \frac{\partial}{\partial x} (u \hat{e}_x) = \vec{0}$$

$$\vec{O} = \rho_0 \vec{f} - \vec{\nabla} P + g \vec{\nabla}^2 \vec{u}$$

$$\Rightarrow \vec{O} = \rho g \sin \alpha \hat{e}_x - \rho g \cos \alpha \hat{e}_y - \frac{\partial P}{\partial x} \hat{e}_x - \frac{\partial P}{\partial z} \hat{e}_z$$

$$+ g \frac{\partial^2 u}{\partial z^2} \hat{e}_x$$

$$x: \rho g \sin \alpha - \frac{\partial P}{\partial x} + g \frac{\partial^2 u}{\partial z^2} = 0$$

$$z: -\rho g \cos \alpha - \frac{\partial P}{\partial z} = 0$$

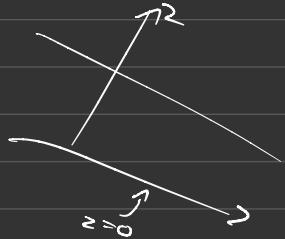
$$P(x, z) = f(x) - \rho g z \cos \alpha$$

$$\frac{\partial P}{\partial x} = 0 \Rightarrow f(x) = P_0$$

$$\Rightarrow P(z) = P_0 - \rho g z \cos \alpha$$

$$\frac{d^2 u}{dz^2} = -\frac{\rho_0 g \sin \alpha}{2} z$$

$$u(z) = -\frac{\rho_0 g z^2 \sin \alpha}{2} + Az + B$$



$$u(0) = 0 \quad \text{no slip}$$

$$\Rightarrow B = 0$$

$$\text{Atmosphere: } (\sigma_{\text{air}})_{ij} = -P_A S_{ij}$$

$$\sigma_{\text{air}} = \begin{pmatrix} -P_A & 0 & 0 \\ 0 & -P_A & 0 \\ 0 & 0 & -P_A \end{pmatrix} = -\left(P_A - \rho_0 g \sin \alpha \mathbf{I}\right)$$

$$\text{H}_2\text{O: } \sigma_{\text{H}_2\text{O}} = -\rho \delta_{ij} + \gamma \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

$u$ : only an  $x$  component, only  $z$  dependence

$$\frac{\partial u_x}{\partial x} = \frac{\partial u_x}{\partial y} = 0 \quad , \quad \frac{\partial u_y}{\partial x_i} = 0 \quad , \quad \frac{\partial u_z}{\partial x_i} = 0$$

$$\sigma_{H_0} = \begin{pmatrix} -P & 0 & -\rho g z \sin \alpha + y A \\ 0 & -P & 0 \\ -\rho g z \sin \alpha + y A & 0 & -P \end{pmatrix}$$

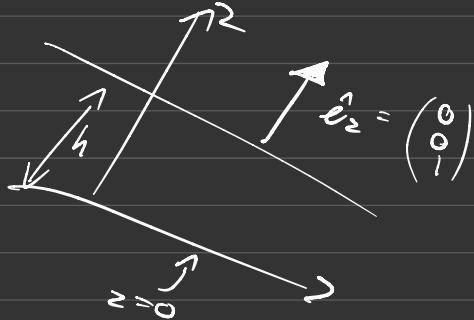
$$\sigma_{xy} = \gamma \left( \frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \right)$$

$$= 0$$

$$\sigma_{xz} = \gamma \left( \frac{\partial u_x}{\partial z} + \frac{\partial u_z}{\partial x} \right)$$

$$= \gamma \left( -\rho g z \sin \alpha + A \right)$$

$$\sigma_{yz} = 0$$



$$\sigma_{an} \cdot \hat{n} = \begin{bmatrix} 0 \\ 0 \\ -P_A \end{bmatrix}$$

$$\vec{v}_{no} \cdot \hat{n} = \begin{bmatrix} -\rho g z \sin \alpha + \gamma A \\ 0 \\ -\rho \end{bmatrix}$$

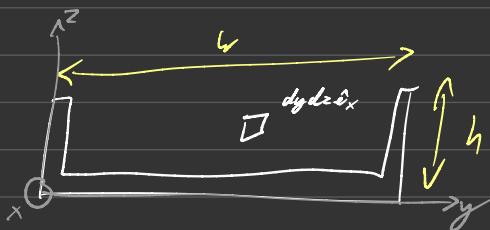
$$\Rightarrow -\rho g h \sin \alpha + \gamma A = 0$$

$$-\rho_A = -\rho_0$$

$$A = \frac{\rho g h \sin \alpha}{\gamma}$$

$$\vec{u} = \frac{\rho g \sin \alpha}{2\gamma} (2hz - z^2) \hat{e}_x$$

$$|\vec{u}|_{surface} = \frac{\rho g h^2}{2\gamma} \sin \alpha$$



$$Q = \int_{cross\ section} \vec{u} \cdot d\vec{S} = \int \frac{\rho g \sin \alpha}{2\gamma} (2hz - z^2) dy dz$$

$$= \frac{\rho g v s n \alpha}{2g} \left( \frac{2h^3}{3} \right)$$

$$= \frac{\rho g v h^3}{3g} \sin \alpha$$

$$= \frac{2}{3} |\vec{u}|_{\text{surface}} h w$$

$$\begin{aligned} \rho_0 &= 1000 \text{ kg} \cdot \text{m}^{-3} & h &= 0.5 \text{ m} \\ g &= 10^{-3} \text{ Pa} \cdot \text{s} & w &= 2 \text{ m} \\ g &= 9.81 \text{ m} \cdot \text{s}^{-2} \end{aligned}$$

a drop of 1 m for every Kilometer



$$\tan \alpha \approx \frac{1}{1000} = \alpha$$

$$|\vec{u}| = 1.22 \cdot 10^6 \text{ m} \cdot \text{s}^{-1}$$

$$Q = 8.2 \cdot 10^5 \text{ m}^3 \text{s}^{-1}$$

## Relativistic fluids

NR (non relativistic):  $|\vec{u}| \ll c$

Ideal fluid: described fully by its density, pressure and velocity

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$\rho \frac{\partial \vec{u}}{\partial t} + \rho (\vec{u} \cdot \vec{\nabla}) \vec{u} = - \vec{\nabla} p$$

$$\frac{\partial}{\partial t} (\rho \vec{u}) - \frac{\partial \rho}{\partial t} \vec{u} + \rho (\vec{u} \cdot \vec{\nabla}) \vec{u}$$

$$= \frac{\partial}{\partial t} (\rho \vec{u}) + (\vec{\nabla} \cdot \rho \vec{u}) \vec{u} + (\rho \vec{u} \cdot \vec{\nabla}) \vec{u}$$

$i^{th}$  component

$$\frac{\partial}{\partial t} (\rho u_i) + \vec{\nabla} \cdot (\rho \vec{u} u_i)$$

$$\Rightarrow \frac{\partial}{\partial t} (\rho u_i) + \vec{\nabla} \cdot (\rho \vec{u} u_i) + (\vec{\nabla} p)_i = 0$$

4-vector  $\mathcal{U}^\mu$

$$\mathcal{U}^0 = \gamma(\vec{u}) c ,$$

$$\mathcal{U}^1 = \gamma(\vec{u}) u_x , \quad \mathcal{U}^2 = \gamma(\vec{u}) u_y , \quad \mathcal{U}^3 = \gamma(\vec{u}) u_z$$

$$\gamma(\vec{u}) = \frac{1}{\sqrt{1 - \frac{|\vec{u}|^2}{c^2}}}$$

$$\gamma(\vec{u}) = 1 + \frac{|\vec{u}|^2}{2c^2} + \mathcal{O}\left(\frac{|u|^4}{c^4}\right) \approx 1$$

$$\mathcal{U}^0 \approx c , \quad \mathcal{U}^{1,2,3} \approx u_{x,y,z}$$

$$P \longrightarrow \sqrt{c^2} \Rightarrow \frac{\partial}{\partial t} (\sqrt{c^2})$$

$$X^\mu : x^0 = ct , \quad x^1 = x , \quad x^2 = y , \quad x^3 = z$$

$$\frac{\partial}{\partial x^\mu} = \partial_\mu : \quad \partial_0 = \frac{1}{c} \frac{\partial}{\partial t} , \quad \partial_{1,2,3} = \frac{\partial}{\partial (x,y,z)}$$

$$\frac{\partial}{\partial t} (\rho c^2) + \vec{\nabla} \cdot (\rho c^2 \vec{u}) = 0$$

$$\frac{\partial}{\partial t} (\rho \vec{u}_i) + \vec{\nabla} \cdot (\rho \vec{u} \vec{u}_i) + (\vec{\nabla} \rho)_i = 0$$

$x$ -component :  $\partial_0(\rho U') + \partial_1(\rho U' U') + \partial_2(\rho U^2 U') + \partial_3(\rho U^3 U') + \partial_1 \rho = 0$

$$\Rightarrow \partial_0(\rho U' U^0) + \partial_1(\rho U' U') + \partial_2(\rho U^2 U') + \partial_3(\rho U^3 U') + \partial_1 \rho = 0$$

$$\Rightarrow \partial_\mu(\rho U^\mu) + \partial_1 \rho = 0$$

$$ds^2 = -c^2 dt^2 + dx^2 + dy^2 + dz^2$$

$$\partial_m(\rho U^m) + \partial' \rho = 0$$

$$\partial_m(\rho U^m U') + \partial' \rho = 0$$

$$\partial_m(\rho U^m U^2) + \partial' \rho = 0$$

$$\partial_m(\rho U^m U^3) + \partial' \rho = 0$$

$$\begin{aligned} & c \partial_0(\rho U^0 U^0) + \partial_1(\rho c U^0 U^1) + \partial_2(\rho c U^0 U^2) \\ & + \partial_3(\rho c U^0 U^3) = 0 \end{aligned}$$

$$\begin{aligned} & \partial_0(\rho U^0 U^0) + \partial_1(\rho U^0 U^1) + \partial_2(\rho U^0 U^2) \\ & + \partial_3(\rho U^0 U^3) = 0 \end{aligned}$$

$$\partial_m(\rho U^m U^0) = 0$$

$$\partial_m(\rho U^m U') + \partial' \rho = 0$$

$$\partial_m(\rho U^m U^2) + \partial' \rho = 0$$

$$\partial_m(\rho U^m U^3) + \partial' \rho = 0$$

$$\gamma_{\mu\nu} = \begin{bmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}_{\mu\nu} = \gamma^{\mu\nu}$$

$$\gamma^i_j = \gamma^{ij} = \delta_{ij}$$

$$\partial^\nu \rho = \partial_\mu \gamma^{\mu\nu} \rho$$

$$= \partial_0 (\cancel{\gamma^0 \rho}) + \partial_1 (\cancel{\gamma^1 \rho}) + \cancel{\partial_2 (\gamma^2 \rho)} + \cancel{\partial_3 (\gamma^3 \rho)}$$

$$= \partial_1 \rho$$

$$\partial_\mu (\rho V^\mu V^\circ) = 0$$

$$\partial_\mu (\rho V^\mu V^1) + \partial_\mu (\gamma^{\mu 1} \rho) = 0$$

$$\partial_\mu (\rho V^\mu V^2) + \partial_\mu (\gamma^{\mu 2} \rho) = 0$$

$$\partial_\mu (\rho V^\mu V^3) + \partial_\mu (\gamma^{\mu 3} \rho) = 0$$

$$T^{\mu\nu}, \quad \partial_\mu T^{\mu\nu} = 0$$

Candidates for  $T^{\mu\nu}$

$$U^\mu$$

$$\cancel{U^\mu}$$

$$\cancel{J^\mu}$$

$$U^\mu U^\nu \quad \gamma^{\mu\nu}$$

$$T^{\mu\nu} = A U^\mu U^\nu + B \gamma^{\mu\nu}$$

$$\partial_\mu T^{\mu\nu} = 0$$

$$\partial_\mu T^{\mu 0} = 0 = \partial_0 T^{00} + \partial_1 T^{10} + \partial_2 T^{20} + \partial_3 T^{30}$$

$$= \frac{1}{c} \frac{\partial}{\partial t} (T^{00}) + \vec{\nabla} \cdot (\quad)$$

$$\frac{\partial}{\partial t} (\rho c^2) + \dots$$

Propose  $T^{00} = \rho c^2$

$$\Rightarrow T^{\mu\nu} = A (U^\mu)^2 + B \gamma^{\mu\nu} \approx A c^2 + B$$

$$\Rightarrow A = \rho + \frac{\beta}{c^2}$$

$$\begin{aligned}
\partial_m T^{mu} &= \partial_0 (T^{0u}) + \partial_1 (T^{1u}) + \partial_2 (T^{2u}) + \partial_3 (T^{3u}) \\
&= \partial_0 (AV^0 V^1) + \partial_1 (AV^1 V^1 + B) \\
&\quad + \partial_2 (AV^2 V^1) + \partial_3 (AV^3 V^1) = 0 \\
&= \partial_0 (AV^0 V^1) + \partial_1 (AV^1 V^1) + \partial_2 (AV^2 V^1) \\
&\quad + \partial_3 (AV^3 V^1) + \partial_1 B = 0
\end{aligned}$$

$$\begin{aligned}
\Rightarrow \partial_0 (\rho V^0 V^1) + \partial_1 (\rho V^1 V^1) + \partial_2 (\rho V^2 V^1) \\
+ \partial_3 (\rho V^3 V^1) + \partial_1 B = 0
\end{aligned}$$

$$\beta = \rho$$

$$\begin{aligned}
T^{mu} &= (\rho + \frac{\rho}{c^2}) V^m V^u + \gamma^{mu} P \\
&= \text{energy momentum tensor for} \\
&\quad \text{an ideal fluid}
\end{aligned}$$

$$\partial_m T^{mu} = 0$$

$$\partial_u T^{uu} = 0$$

$$= \partial_0 \left[ (\rho + \frac{\rho}{c^2}) (V^o)^2 - P \right]$$

$$+ \partial_1 \left[ (\rho + \frac{\rho}{c^2}) V^o V^1 \right]$$

$$+ \partial_2 \left[ (\rho + \frac{\rho}{c^2}) V^o V^2 \right]$$

$$+ \partial_3 \left[ (\rho + \frac{\rho}{c^2}) V^o V^3 \right] = 0$$

$$\frac{1}{c} \frac{\partial}{\partial t} \left[ (\rho + \frac{\rho}{c^2}) c^2 j^2 - P \right]$$

$$+ \frac{\partial}{\partial x} \left[ (\rho + \frac{\rho}{c^2}) c u_x j^2 \right]$$

$$+ \frac{\partial}{\partial y} \left[ (\rho + \frac{\rho}{c^2}) c u_y j^2 \right]$$

$$+ \frac{\partial}{\partial z} \left[ (\rho + \frac{\rho}{c^2}) c u_z j^2 \right] = 0$$

$$\frac{1}{c^2} \frac{\partial}{\partial t} \left[ (\rho + \frac{\rho}{c^2}) \gamma^2 - \rho \right]$$

$$+ \frac{\partial}{\partial x} \left[ (\rho + \frac{\rho}{c^2}) u_x \gamma^2 \right]$$

$$+ \frac{\partial}{\partial y} \left[ (\rho + \frac{\rho}{c^2}) u_y \gamma^2 \right]$$

$$+ \frac{\partial}{\partial z} \left[ (\rho + \frac{\rho}{c^2}) u_z \gamma^2 \right] = 0$$

$$\frac{\partial}{\partial t} \left( \frac{\rho}{1 - \frac{u^2}{c^2}} \right) + \frac{1}{c^2} \frac{\partial}{\partial t} \left[ \left( \frac{1}{1 - \frac{u^2}{c^2}} - 1 \right) \rho \right]$$

$$+ \vec{\nabla} \cdot \left[ \left( \frac{\rho + \frac{\rho}{c^2}}{1 - \frac{u^2}{c^2}} \right) \vec{u} \right] = 0$$

$$\partial_{\mu} T^{\mu\nu} = \partial_0 T^{01} + \partial_1 T^{11} + \partial_2 T^{21} + \partial_3 T^{31}$$

$$= \frac{1}{c} \frac{\partial}{\partial t} \left[ (\rho + \frac{\rho}{c^2}) U^0 U^1 \right]$$

$$+ \frac{\partial}{\partial x} \left[ (\rho + \frac{\rho}{c^2}) (U^1)^2 + \rho \right]$$

$$+ \frac{\partial}{\partial y} \left[ (\rho + \frac{\rho}{c^2}) V^2 V' \right]$$

$$+ \frac{\partial}{\partial z} \left[ (\rho + \frac{\rho}{c^2}) V^3 V' \right] = 0$$

$$\frac{\partial}{\partial t} \left[ \left( \rho + \frac{\rho}{c^2} \right) u_x \right] + \vec{\nabla} \cdot \left[ \left( \rho + \frac{\rho}{c^2} \right) \vec{u} u_x \right] \\ = - \frac{\partial \rho}{\partial x}$$

$$T^{\mu\nu} = \left( \rho + \frac{\rho}{c^2} \right) V^\mu V^\nu + g^{\mu\nu} \rho$$

$\downarrow GR$  with curved space time

$$T^{\mu\nu} = \left( \rho + \frac{\rho}{c^2} \right) V^\mu V^\nu + g^{\mu\nu} \rho$$